

# Using Ambient Vibration Array Techniques for Site Characterisation

## Dispersion Curve Inversion

### Lecture

# Dispersion Curve Inversion

- What's an inverse problem?
- Inversion techniques
- Neighbourhood Algorithm (NA, Sambridge, 1999)
- Conditional parameter spaces
- Dispersion curve inversion examples

# SESARRAY PACKAGE



**figure**

*figures*

**gp tools**

*Dispersion curves  
Ellipticity curves  
Autocorr. Curves  
...*

**build\_array**

*Array response*

*Post-processing*

**max2curve**

**spac2disp**

**DINVER**

*inversion*

# 1. What's an inversion problem ?

## Parameters



$V_{p0}$   $V_{s0}$   $H_0$

$V_{p1}$   $V_{s1}$   $H_1$

$V_{p2}$   $V_{s2}$

Ground model

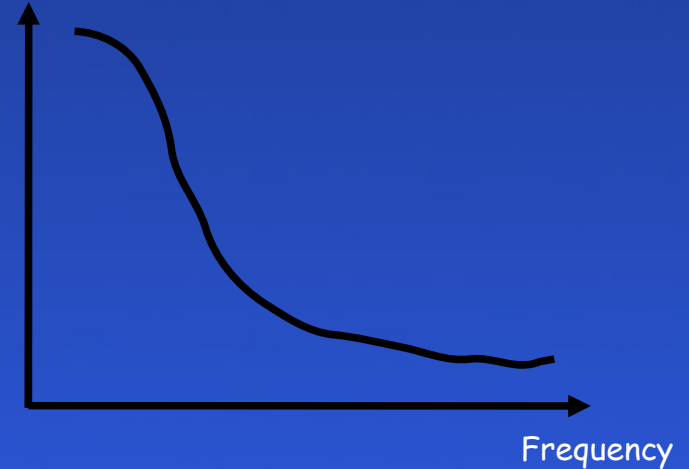
Unknowns

Forward  
problem



Inverse  
problem

Velocity

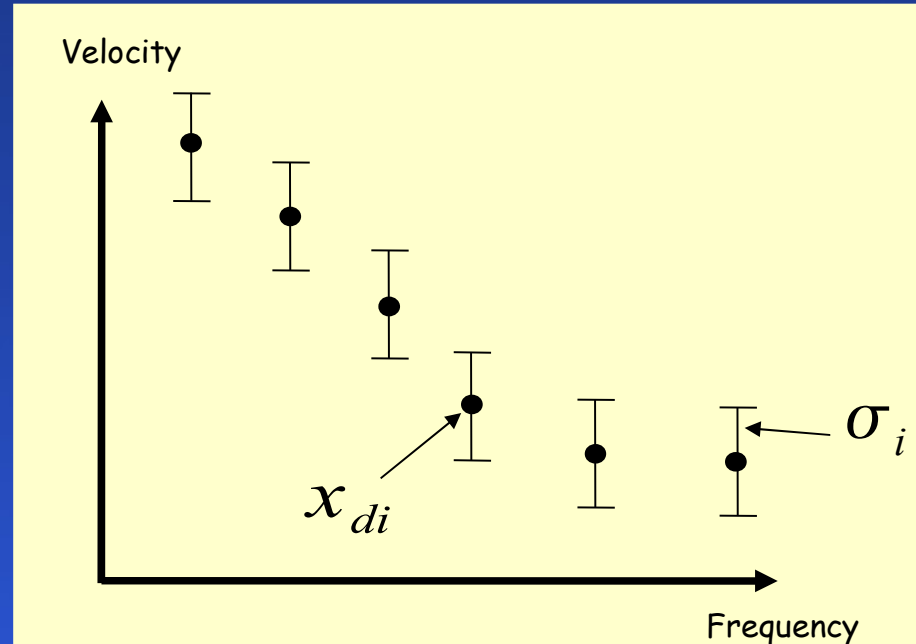


Dispersion curve  
or SPAC ratios

Data

# 2. Inversion Techniques

Ranking models  
 VS  
 Inversion target

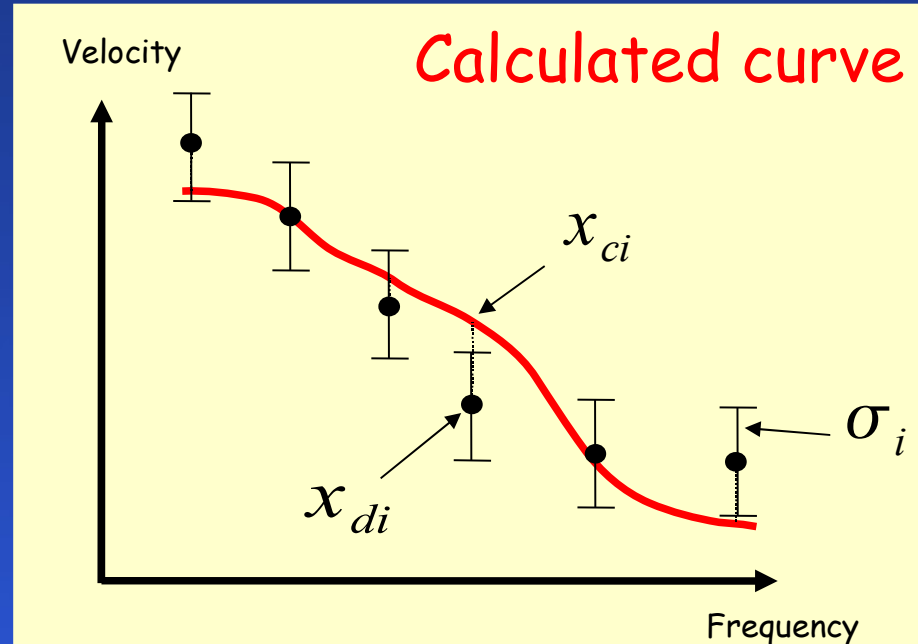


$$\text{Misfit} = \sqrt{\sum_{i=1}^{n_F} \frac{(x_{di} - x_{ci})^2}{\sigma_i^2 n_F}}$$

$n_F$  Number of frequency samples

# 2. Inversion Techniques

Ranking models  
 VS  
 Inversion target



$$\text{Misfit} = \sqrt{\sum_{i=1}^{n_F} \frac{(x_{di} - x_{ci})^2}{\sigma_i^2 n_F}}$$

$n_F$  Number of frequency samples

# A gentle 2D misfit function...



Imagine yourself without a map (nor a GPS) ...

December 6th-12st 2008, Thessaloniki, Greece

... at the same place on a stormy day.



Where is the exit ? (= minimum misfit)

December 6th-12st 2008, Thessaloniki, Greece



Where is the exit ?

Start from anywhere and go down?

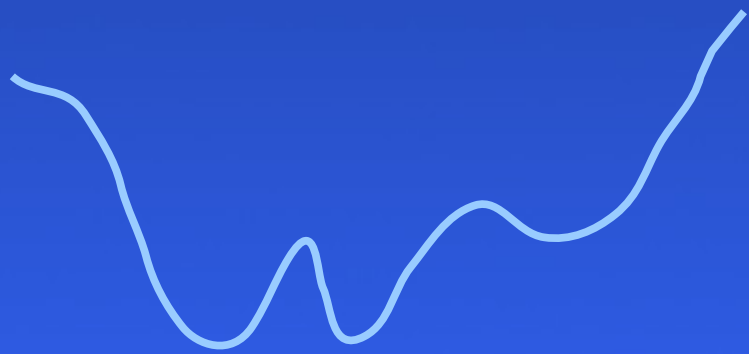
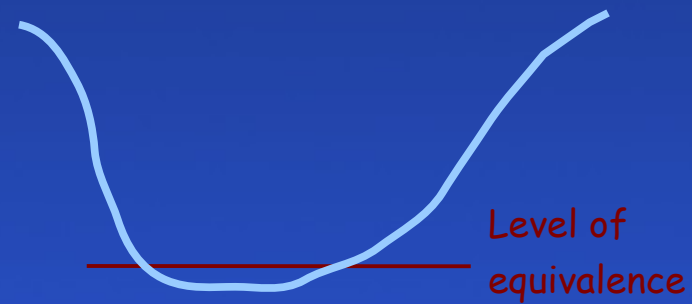


# Possible shapes for a misfit function

A single narrow valley



A larger valley



Local minima and  
equivalent minima



A truly flat valley

## 2. Inversion Techniques

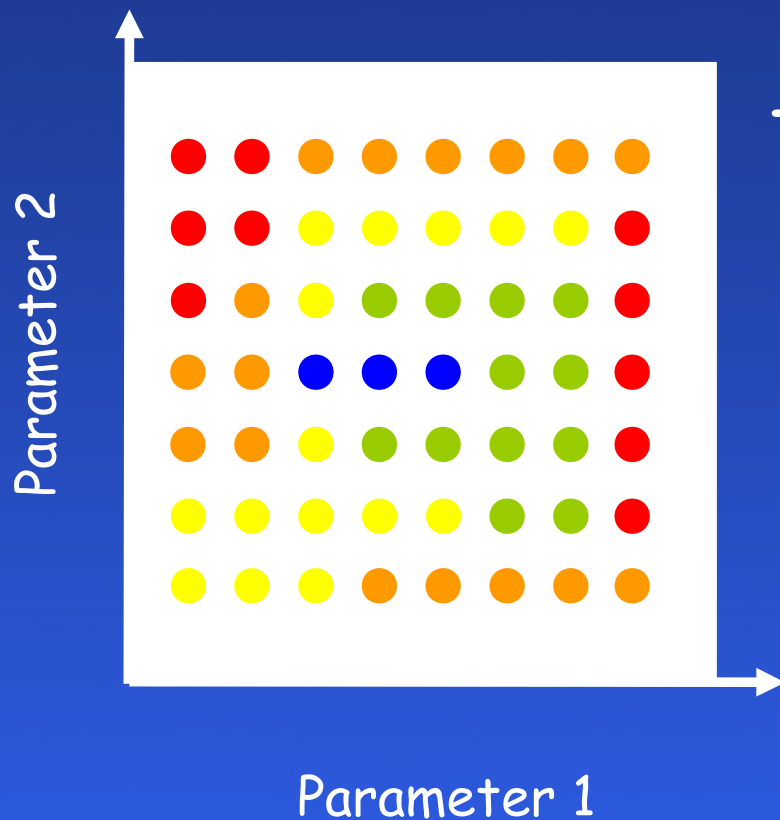
Forward problem:

- Analytic or numerical processing
- **Only one solution**

Inverse problem:

- Trial and error to adjust parameters of the model
- Simplex downhill method
- Brute force uniform search (gridding)
- Least square methods (based on derivatives)
- Brute force Monte Carlo sampling
- Simulated Annealing
- Genetic Algorithm
- Neighbourhood Algorithm
- **Generally not only one solution**

## A. Uniform search (gridding)



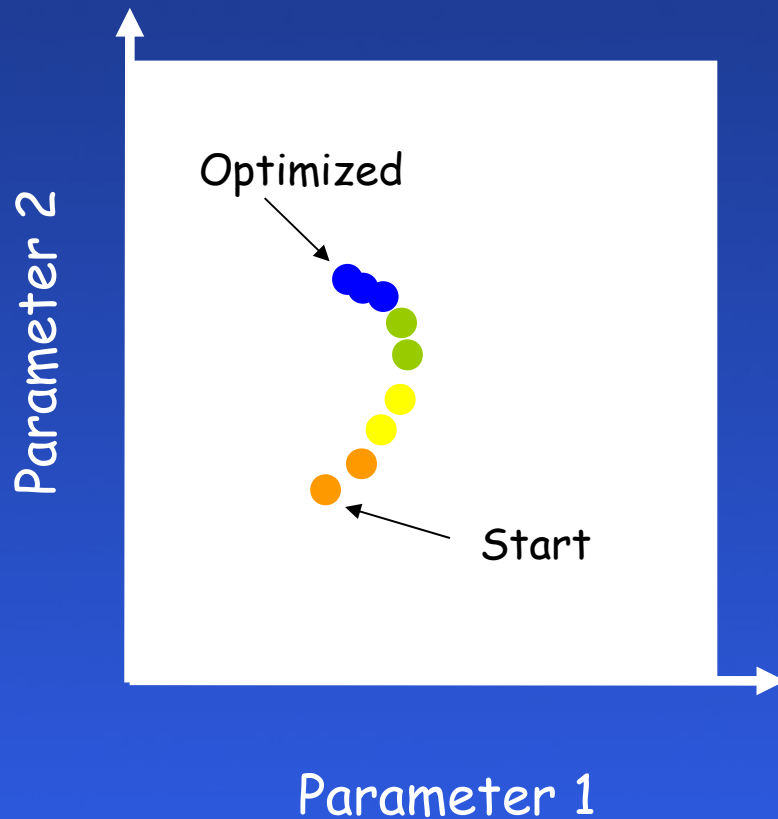
- If  $nd > 3$  : number of forward computations are prohibitive
- + Complete exploration of the parameter space
- + Optimum error estimates

Misfit



## B. Iterative methods (optimisation)

Least Square, Simplex, Gradient methods, ...

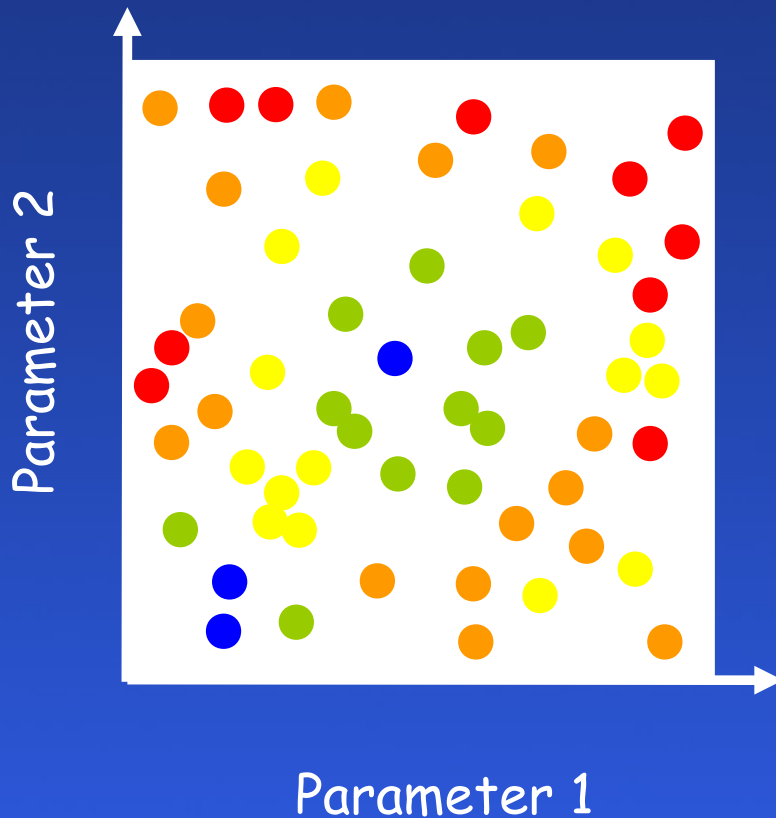


Misfit



- Easily trapped in local minima
- Non-uniqueness  $\Leftrightarrow$  choice of starting model
- Bad error estimates
- Cannot include prior information
- + High dimensionality
- + Few forward computations

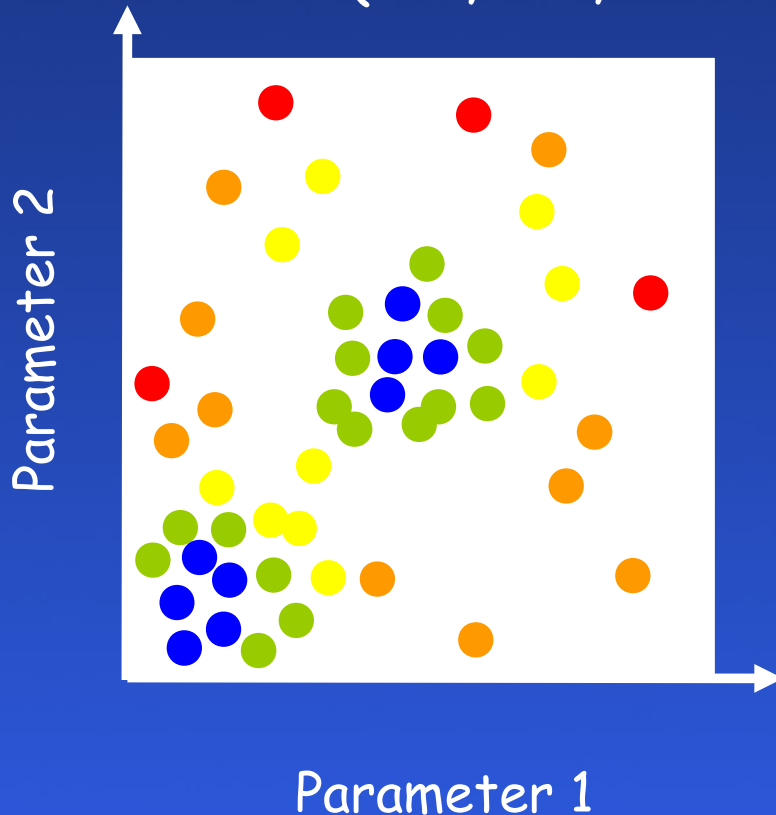
## C. Random search (Monte Carlo)



- Requires lot of forward computations
- + Not too bad exploration of the parameter space
- + Good error estimates

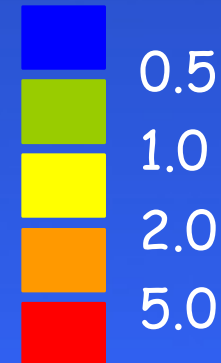


## D. Oriented random search (~ 1990) (SA, GA, and NA)



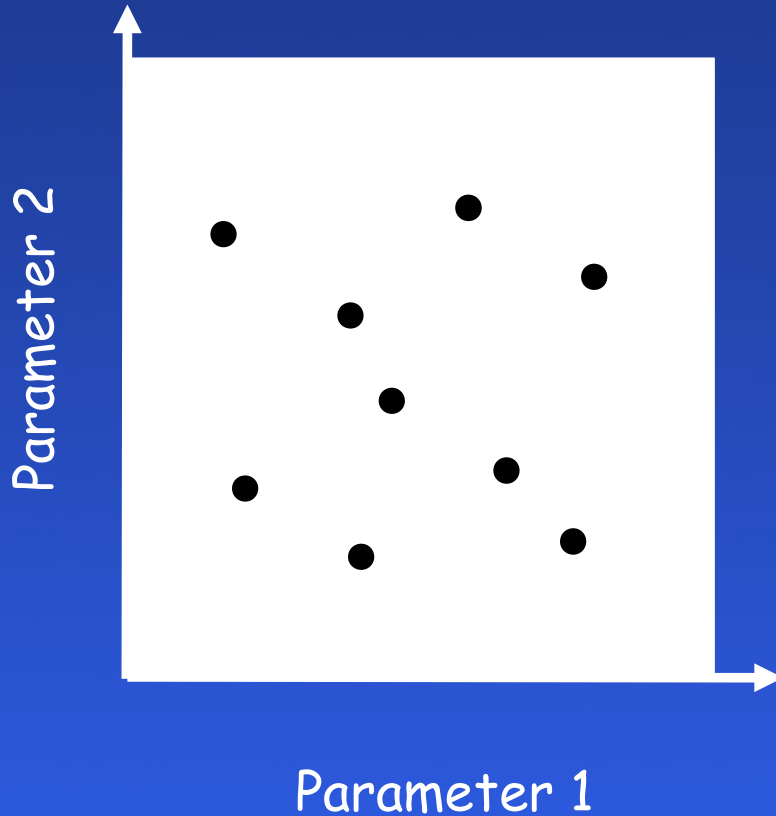
- + Requires less of forward computations than MC
- Max nd ~ 25-50
- + Not too bad exploration of the parameter space
- + Good error estimates

Misfit



# 3. Neighbourhood Algorithm

(Sambridge, 1999)



Few tuning parameters ( $N_s$ ,  $N_r$ )

Based on Voronoi division of the parameter space

~ SA and GA (better according to Sambridge)

Misfit

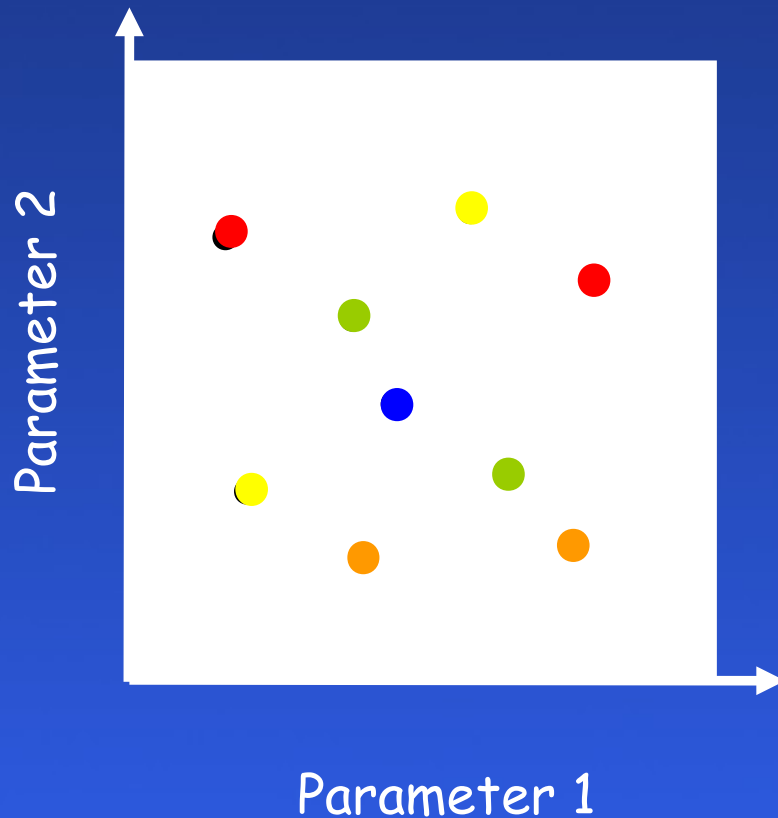


$N_s$  new samples generated into  
 $N_r$  selected cells



### 3. Neighbourhood Algorithm

(Sambridge, 1999)



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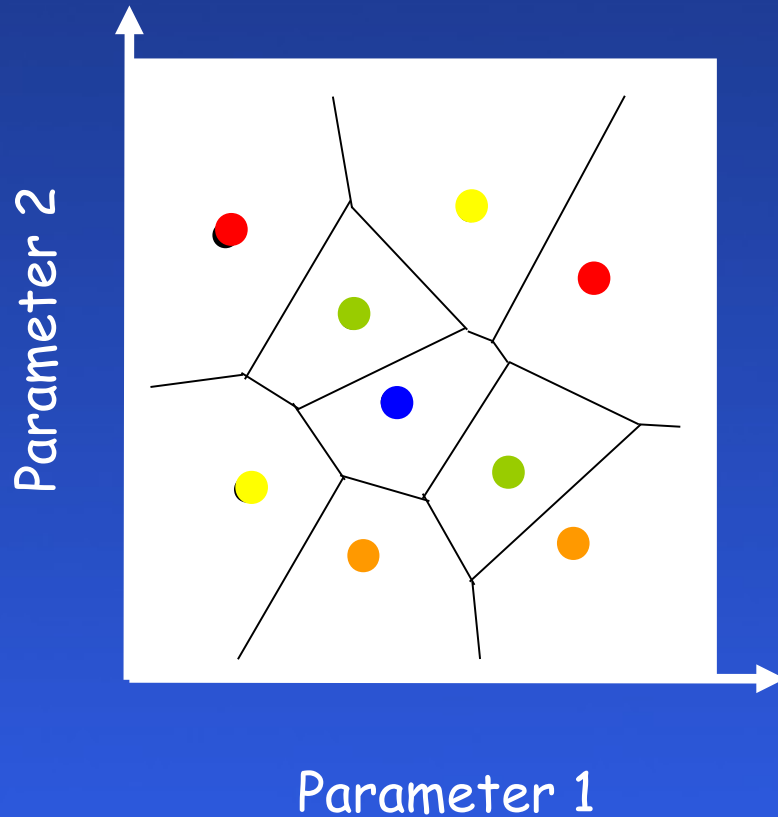
Misfit



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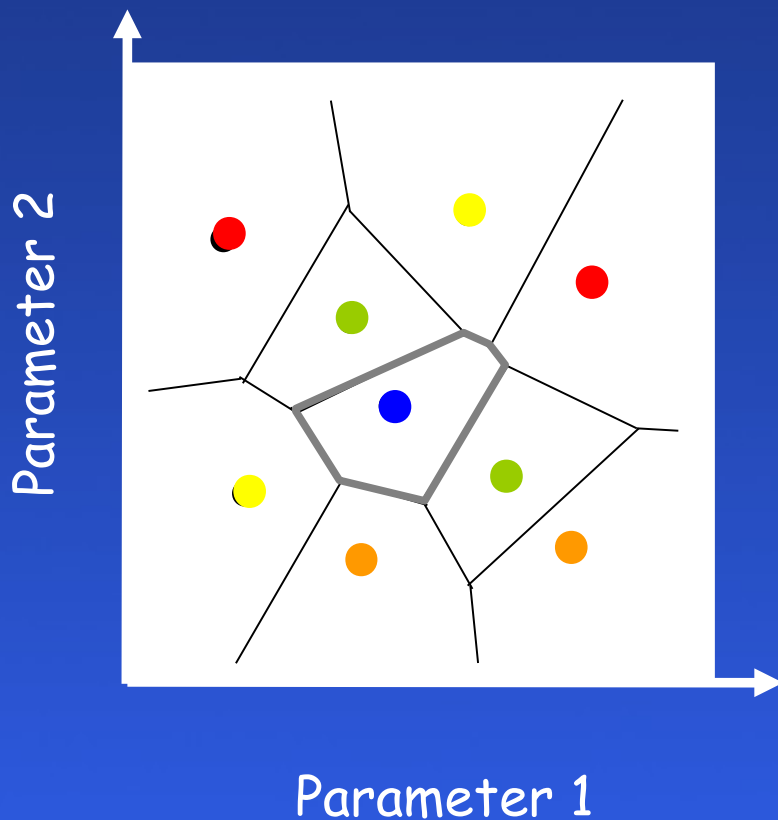
Misfit



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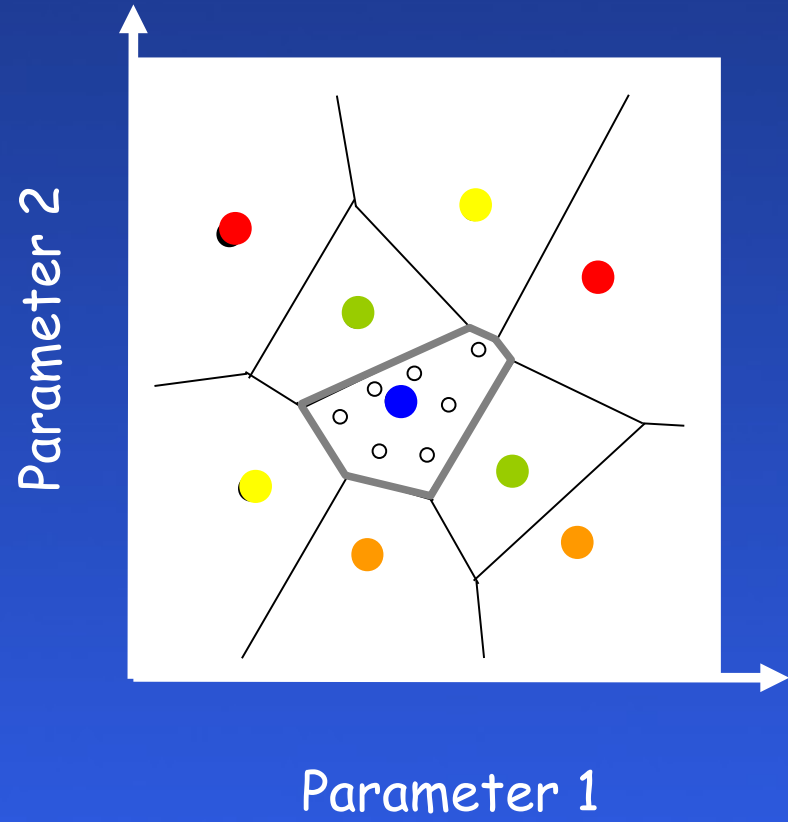
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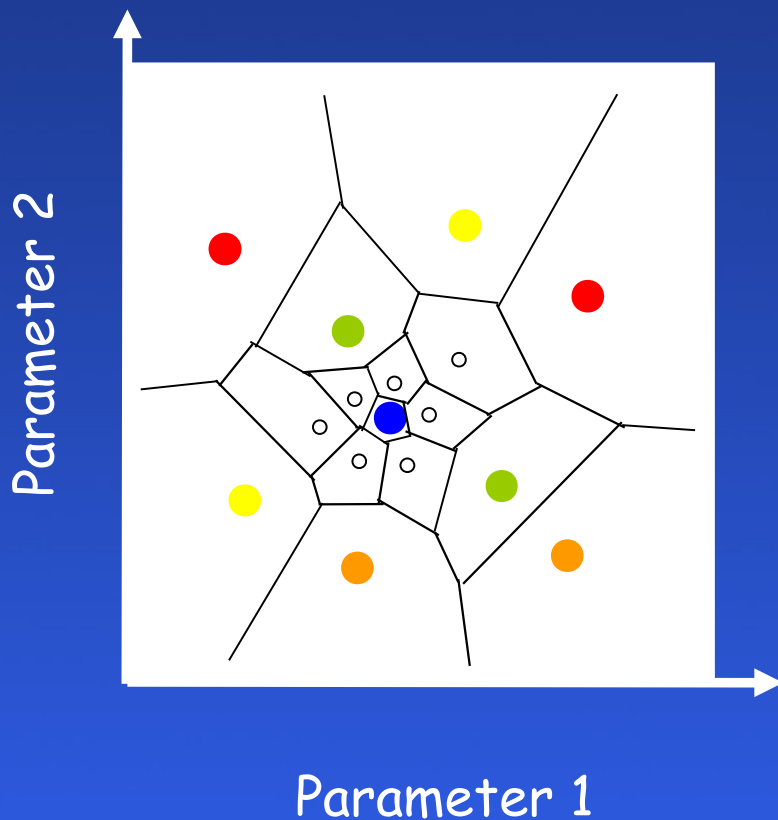
Misfit



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Misfit



$N_s$  new samples generated into  
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## NA for dispersion curves (DC) inversion

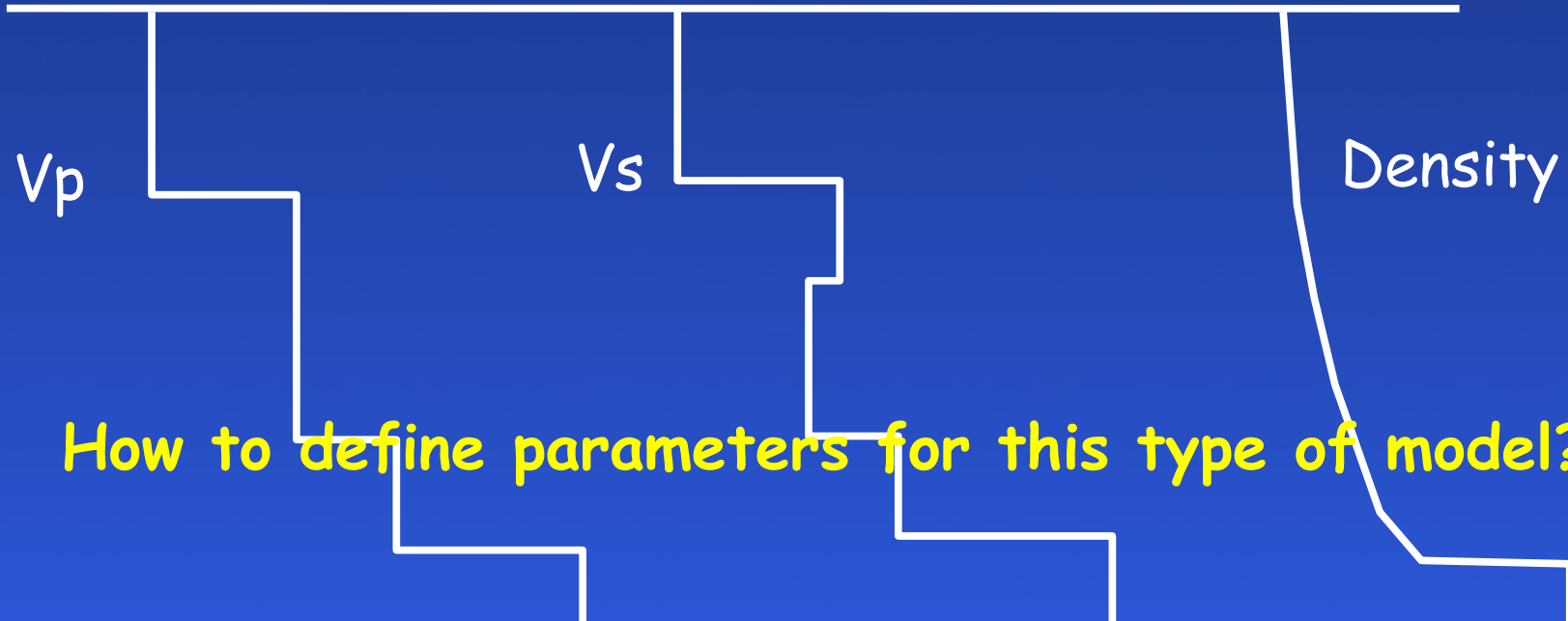
High number of forward computation required (~50,000)

Computation of DC for 1D elastic model =  
numerical process not always stable

(Wathelet, 2005)

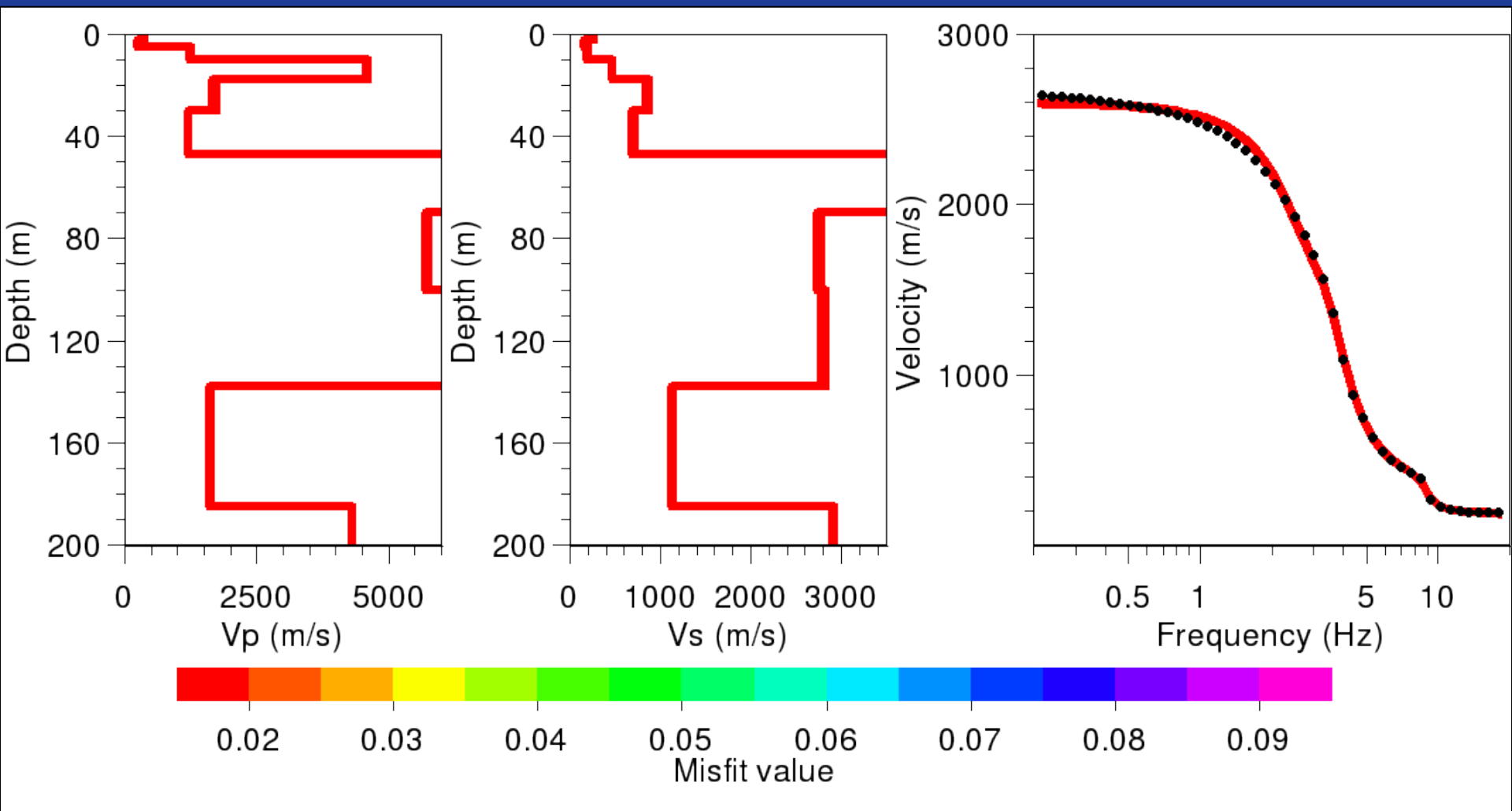
- ==> Battery of tests to automatically tune computation
- ==> Improvement of algorithm efficiency (~ ms/model)

# 4. Conditional parameter spaces



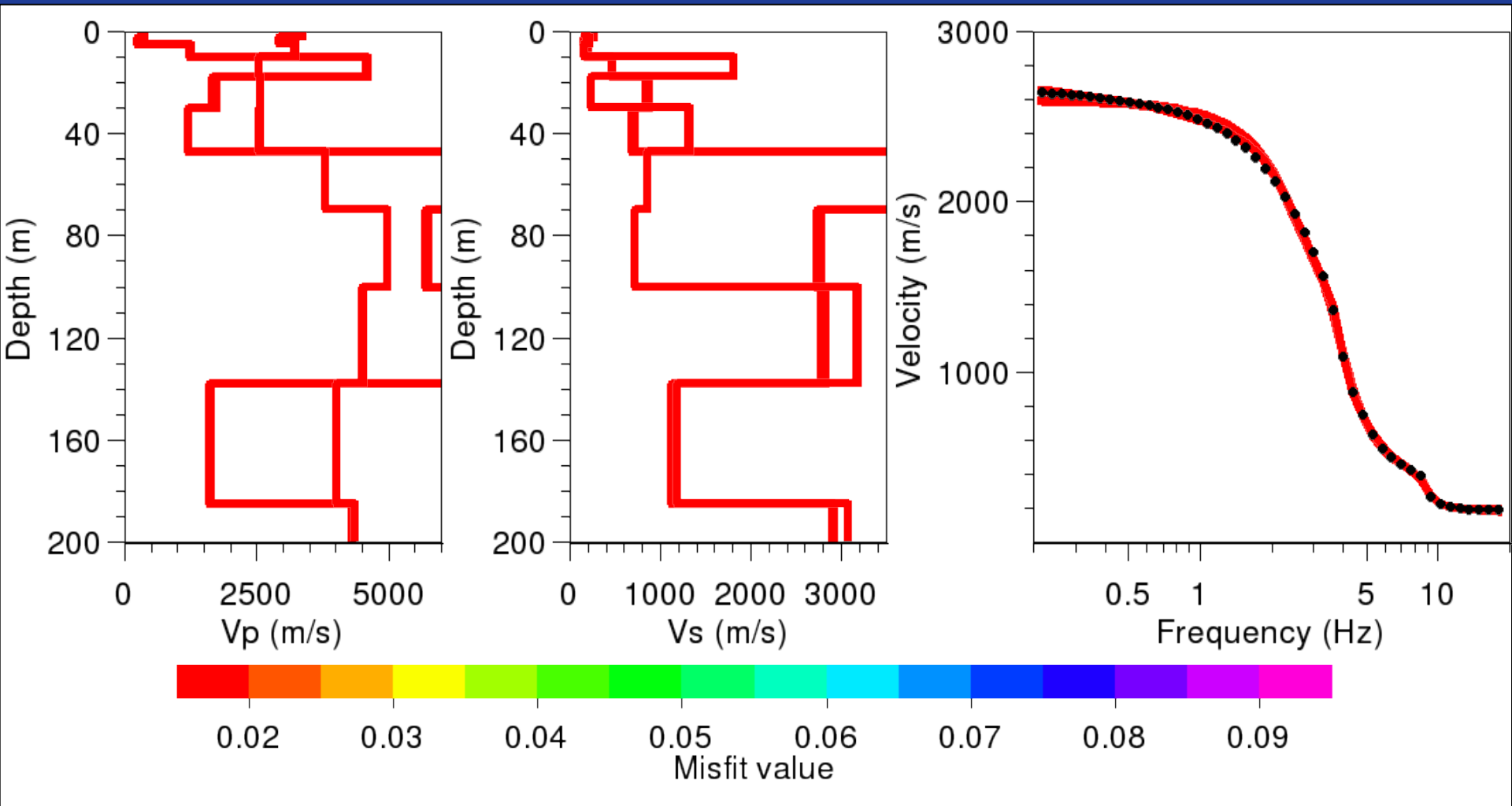
- fixed thicknesses, Poisson's ratios fixed, free  $V_s$  in each layer (classical approach in Herrmann's codes)
- free thicknesses, free  $V_s$ , free  $V_p$ , fixed density  
BUT physical limits: conditions between  $V_s$  and  $V_p$

# Dangers of classical least square approach surface wave inversion

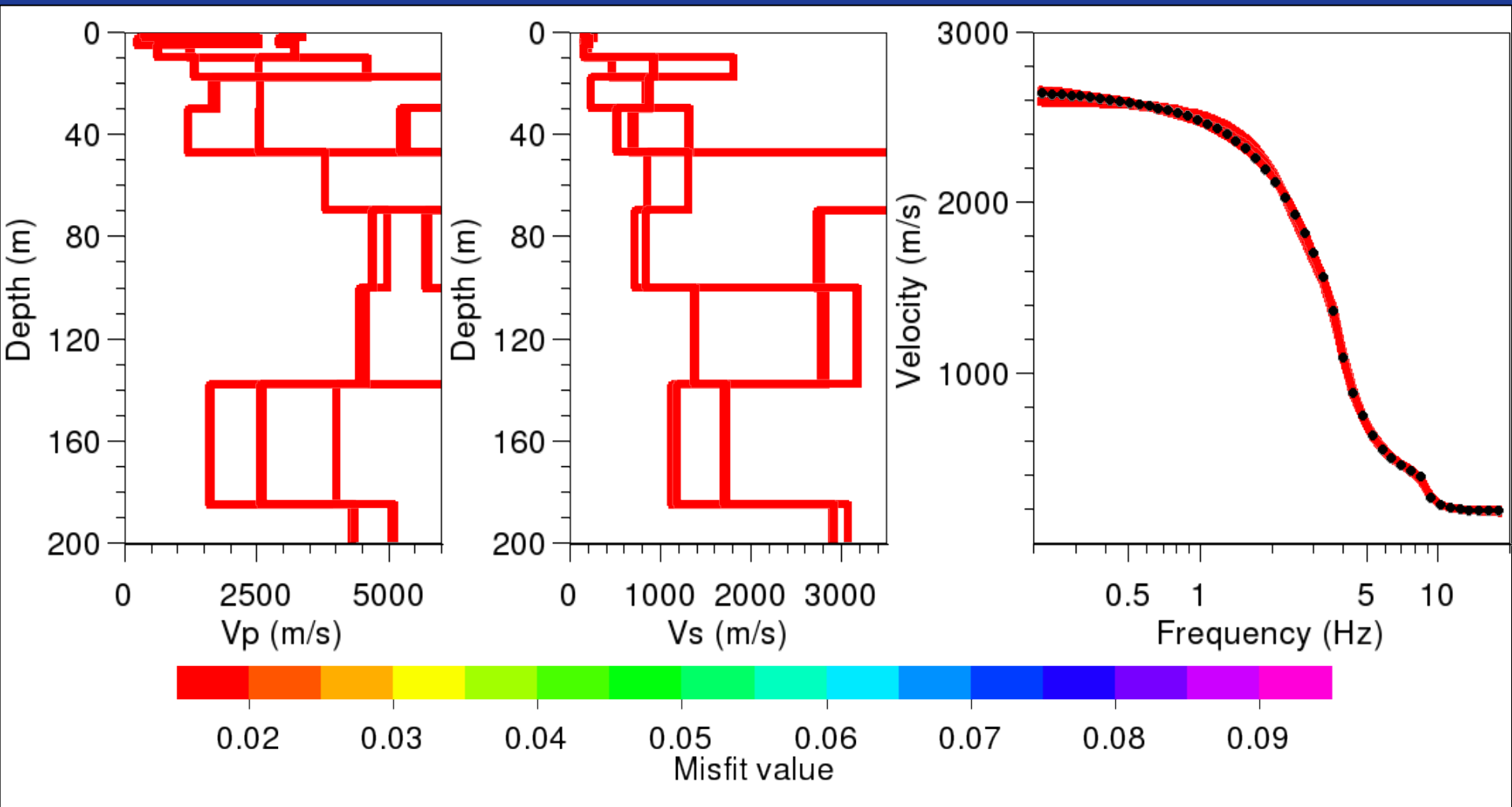




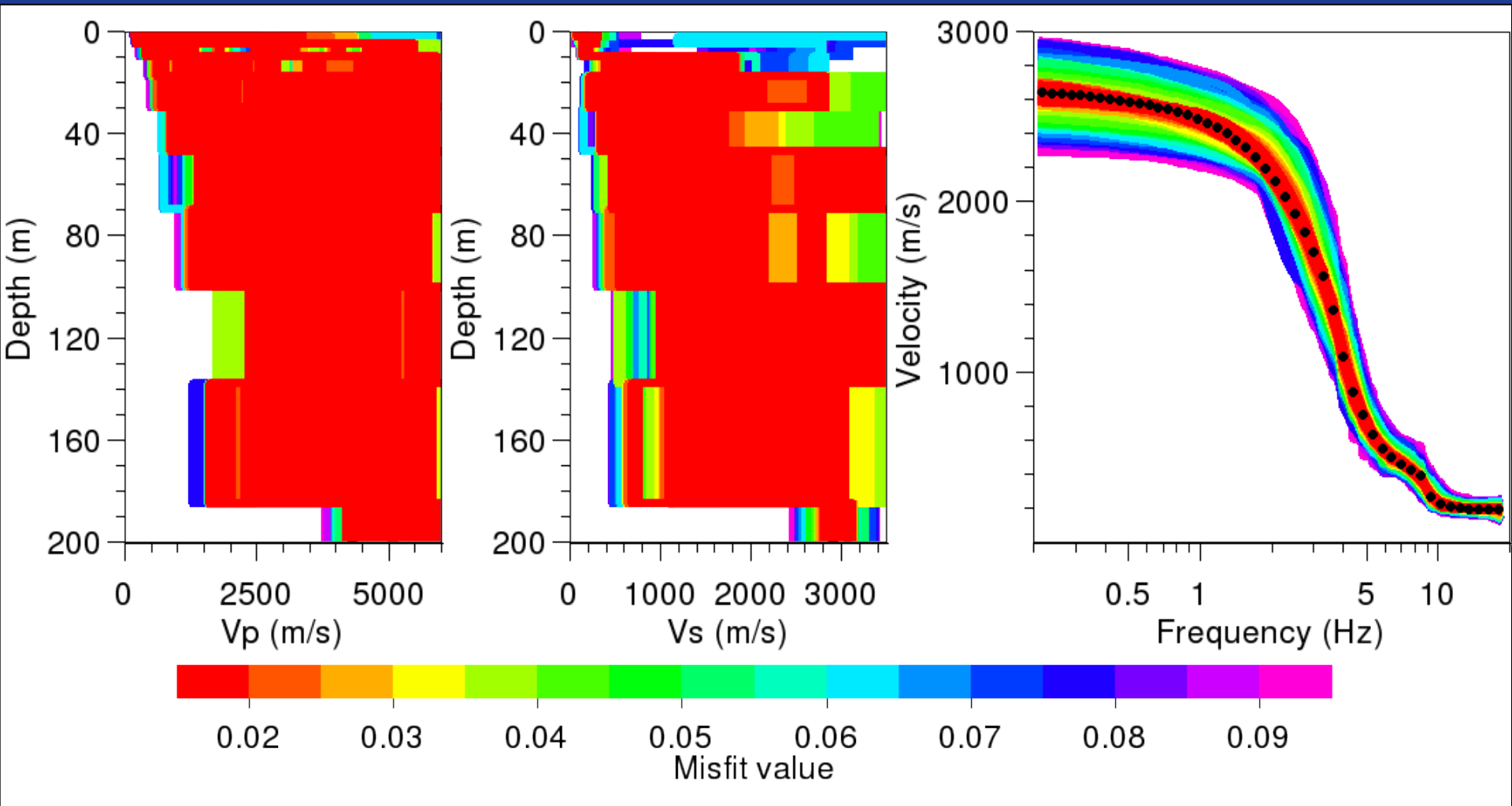
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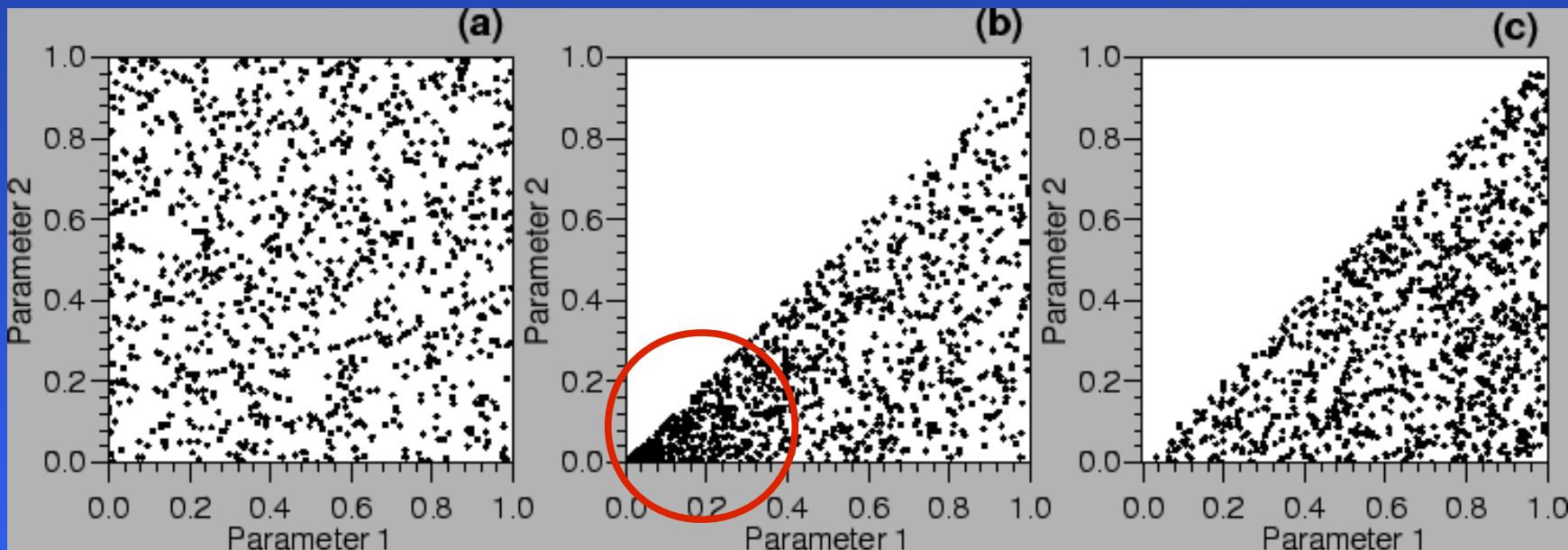


# Irregular parameter space boundaries

Wathelet, M. (2008). An improved neighborhood algorithm: parameter conditions and dynamic scaling. *Geophysical Research Letters*, 35, doi:10.1029/2008GL033256

Sambridge: box (fixed range for all parameters)

↳ Solution to introduce conditions: variable change



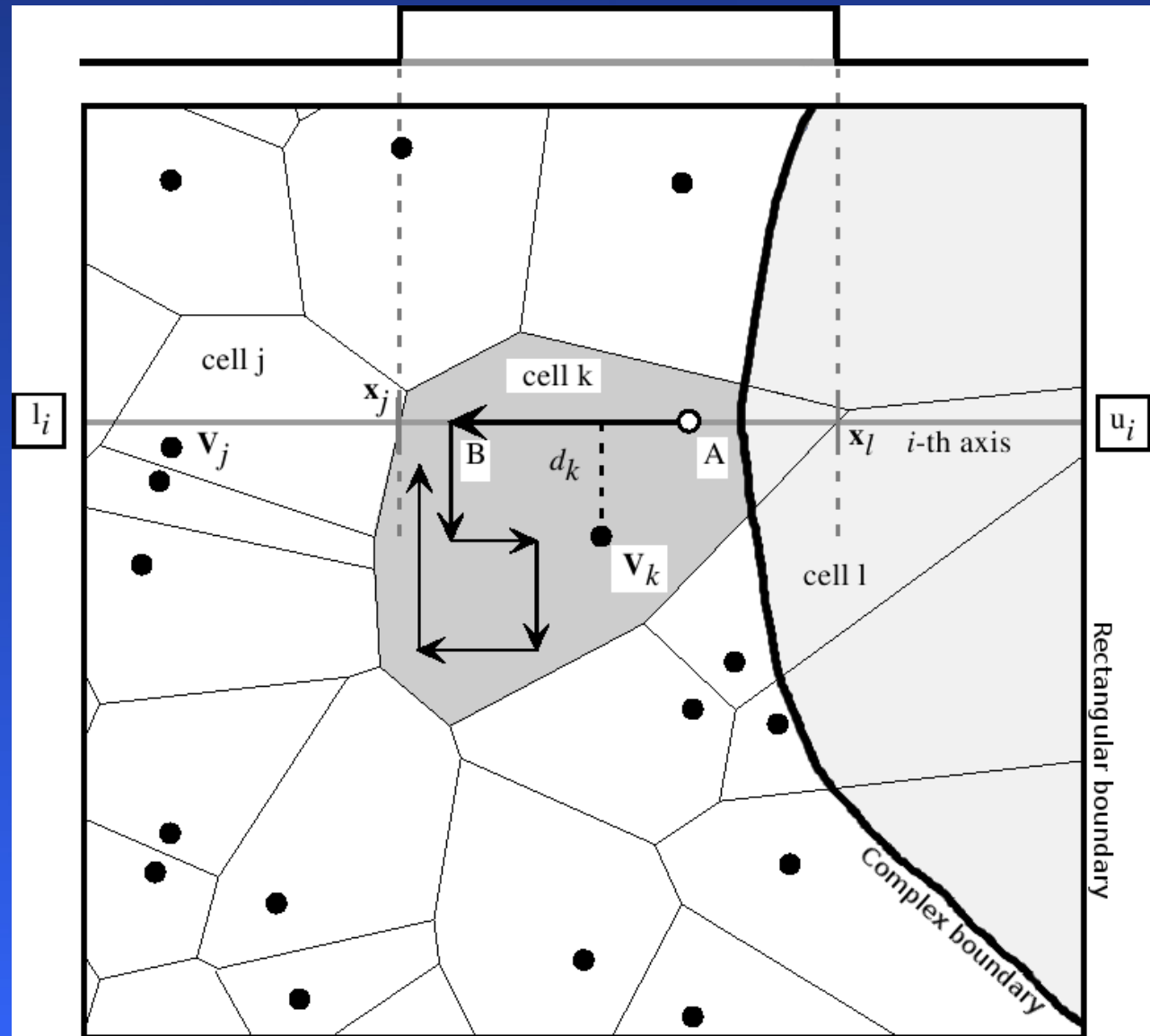
Uncontrolled Prior information

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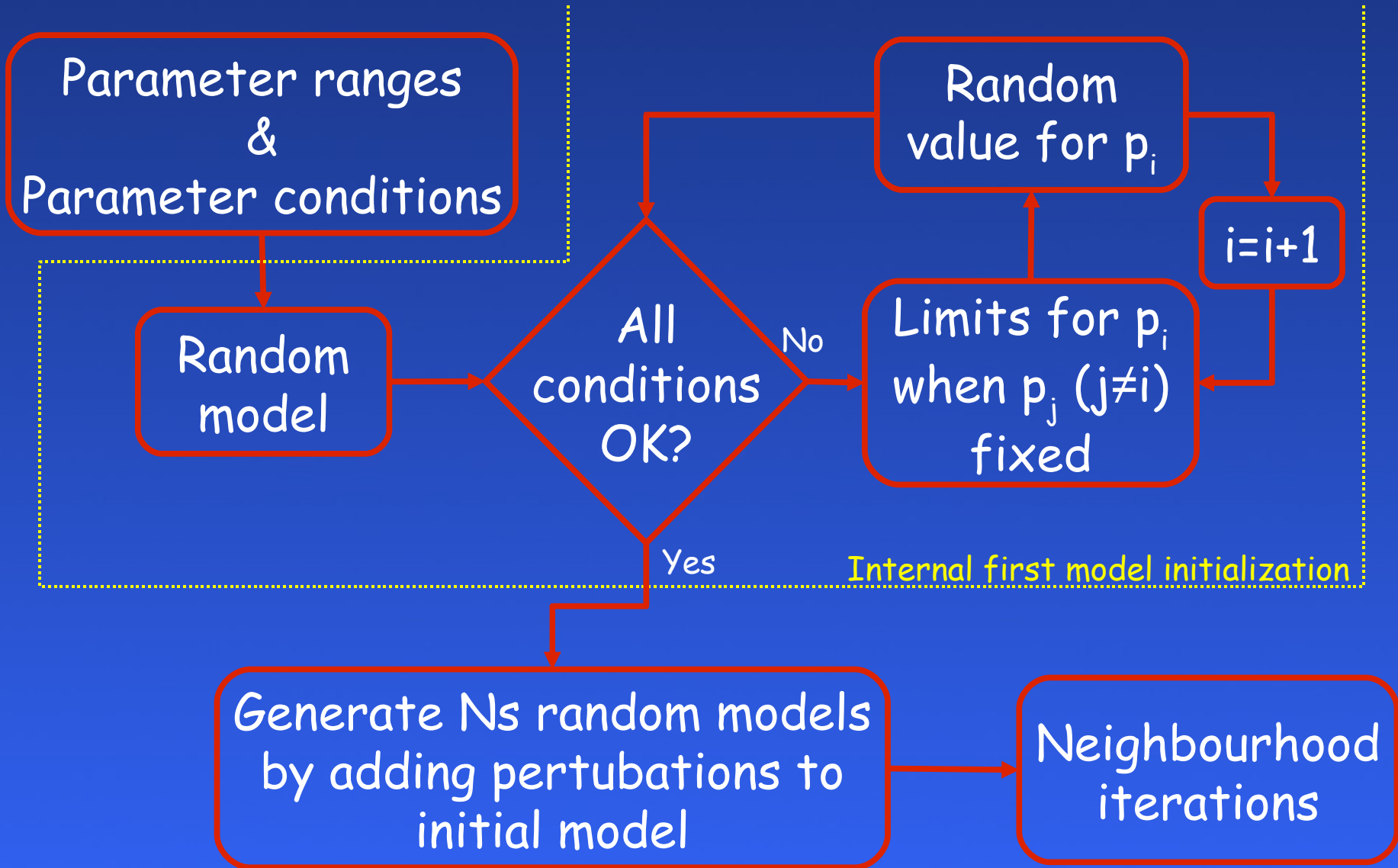
# A modified Neighborhood kernel: irregular parameter boundaries

From model A  
 add "valid" random  
 perturbations so  
 that model B stays  
 in cell k

Loop over all axes



# Conditions in a Neighbourhood Algorithm



# Parameterization of a ground structure

- $V_p$  and  $V_s$  as free parameters: Poisson's ratio limitations

Poisson's ratio =

$$\frac{V_s^2 - \frac{V_p^2}{2}}{V_s^2 - V_p^2}$$

Usual values for  
 soft soil & rocks  
 From 0.2 to 0.5

- Thickness versus depth parameters

$$depth[i] > depth[i-1]$$

- Avoid Low Velocity Zones

$$V[i] > V[i-1]$$

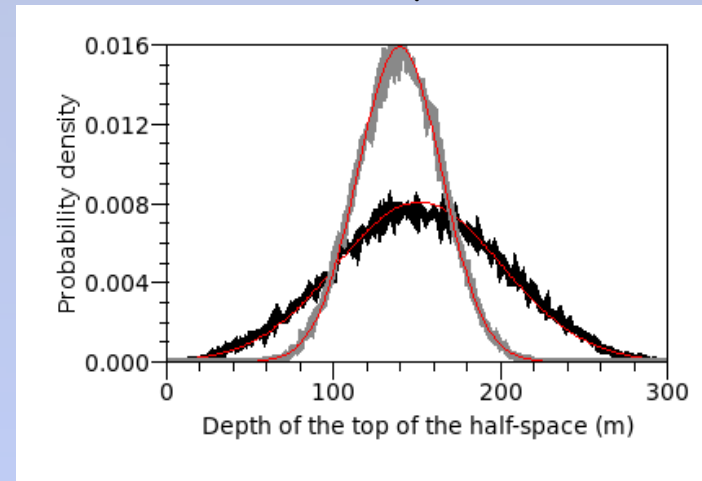
- Parameters for non-uniform layers (gradients)

$V_t$  = Velocity at top

$V_b$  = Velocity at bottom

Power law gradient:  $V_b > V_t$  &  $V_b < V_t + \delta$

Uncontrolled prior distribution  
due to a sum of parameters



# Conversion between Vs-Vp ground model and a conditional parameter space

<p>Add Del</p> <p><b>Compression-wave velocity (m/s)</b></p> <p>Uniform <input type="radio"/> <input type="checkbox"/> Fixed</p> <p>Linked to Vs0</p> <p>Vp0: 200 to 5000 m/s</p> <p>Uniform <input checked="" type="radio"/> <input type="checkbox"/> Fixed</p> <p><input checked="" type="checkbox"/> Vp0 &lt; Vp1</p> <p>Vp1: 200 to 5000 m/s</p>	<p>Add Del</p> <p><b>Poisson's Ratio</b></p> <p>Uniform <input type="radio"/> <input type="checkbox"/> Fixed</p> <p>Linked to Vs0</p> <p>Nu0: 0.45 to 0.5</p> <p>Uniform <input checked="" type="radio"/> <input type="checkbox"/> Fixed</p> <p><input checked="" type="checkbox"/> Nu0 &gt; Nu1</p> <p>Nu1: 0.2 to 0.4</p>	<p>Add Del</p> <p><b>Shear-wave velocity (m/s)</b></p> <p>Uniform <input type="radio"/> <input type="checkbox"/> Fixed</p> <p>Linked to Not linked</p> <p>Bottom depth</p> <p>Vs0: 150 to 3500 m/s</p> <p>DVs0: 1 to 100 m <input type="checkbox"/> Fixed</p> <p>Uniform <input checked="" type="radio"/> <input type="checkbox"/> Fixed</p> <p><input checked="" type="checkbox"/> Vs0 &lt; Vs1</p> <p>Vs1: 150 to 3500 m/s</p>	<p>Add Del</p> <p><b>Density (kg/m3)</b></p> <p>Uniform <input checked="" type="radio"/> <input type="checkbox"/> Fixed</p> <p>Rho0: 2000 kg/m3 <input checked="" type="checkbox"/> Fixed</p>
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## Rectangular limits

$200 < \text{TopVp0} < 5000 \text{ m/s}$

$200 < \text{TopVp1} < 5000 \text{ m/s}$

$150 < \text{TopVs0} < 3500 \text{ m/s}$

$1 < \text{DVs0} < 100 \text{ m}$

$150 < \text{TopVs1} < 3500 \text{ m/s}$

$\text{TopRho0} = 2000 \text{ kg/m}^3$

## Special limits

Poisson's ratio

$\text{TopVp1} > \text{TopVp0}$

$\text{TopVs1} > \text{TopVs0}$

5 parameters



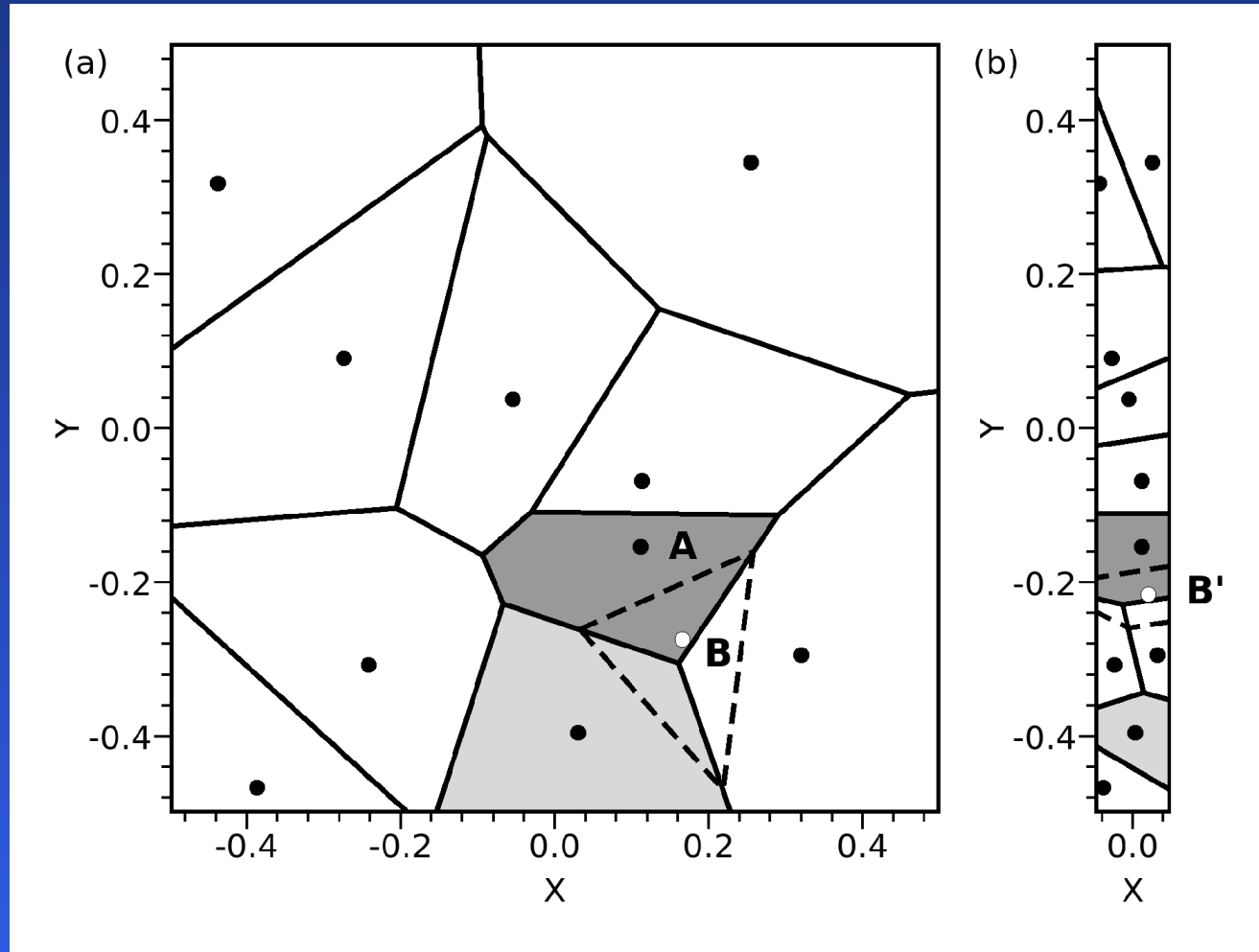
# Feature summary

- Uniform or gradient layers (power law or linear)
- Fixed parameter range for prior information
- Uncorrelated  $V_p$ ,  $V_s$  and density profiles
- Depth and/or thickness
- Full control over Low Velocity Zones
- Custom conditions (impedance contrast)
- Fine Poisson's ratio limits

# Dynamic parameter scaling

An interesting property of Voronoi cells:

Effect of axis scaling

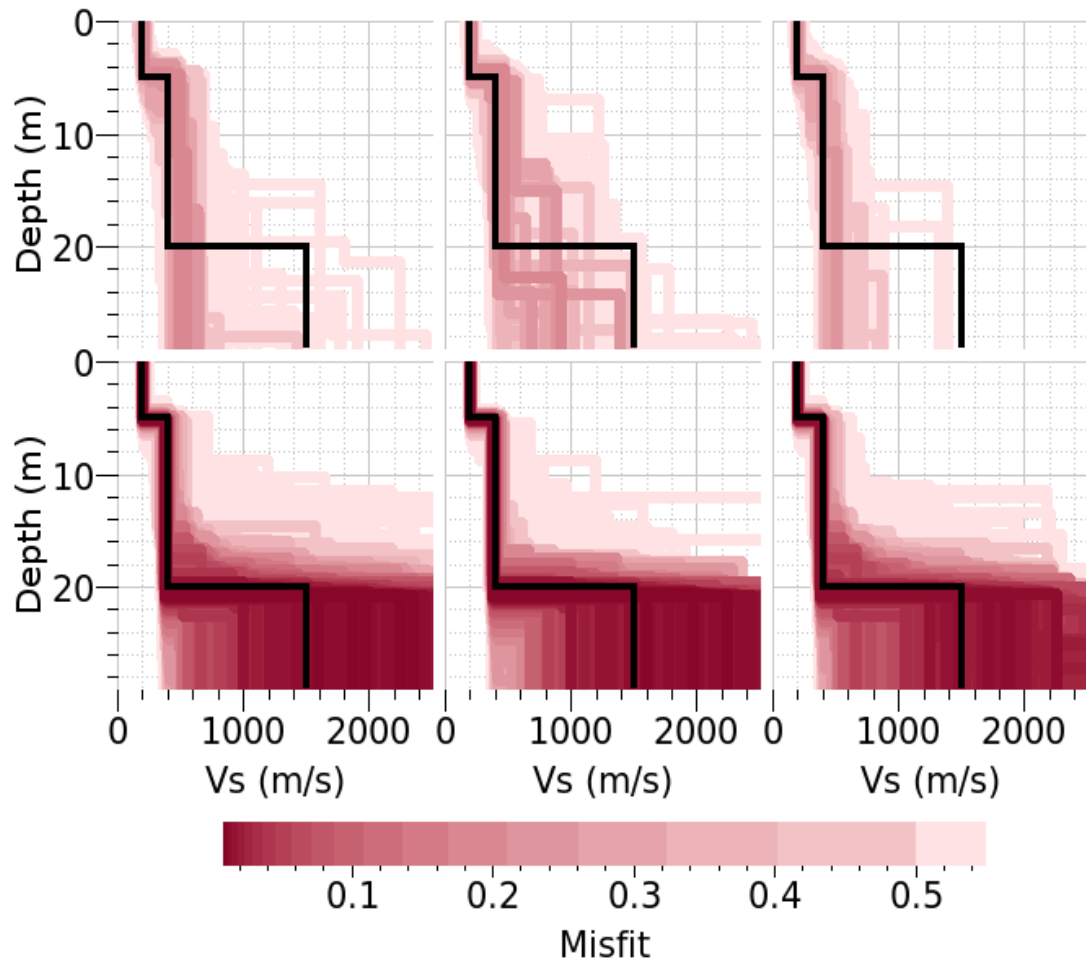


NA explores always best along the smallest axis range

# Boosting exploration capabilities

Static scaling

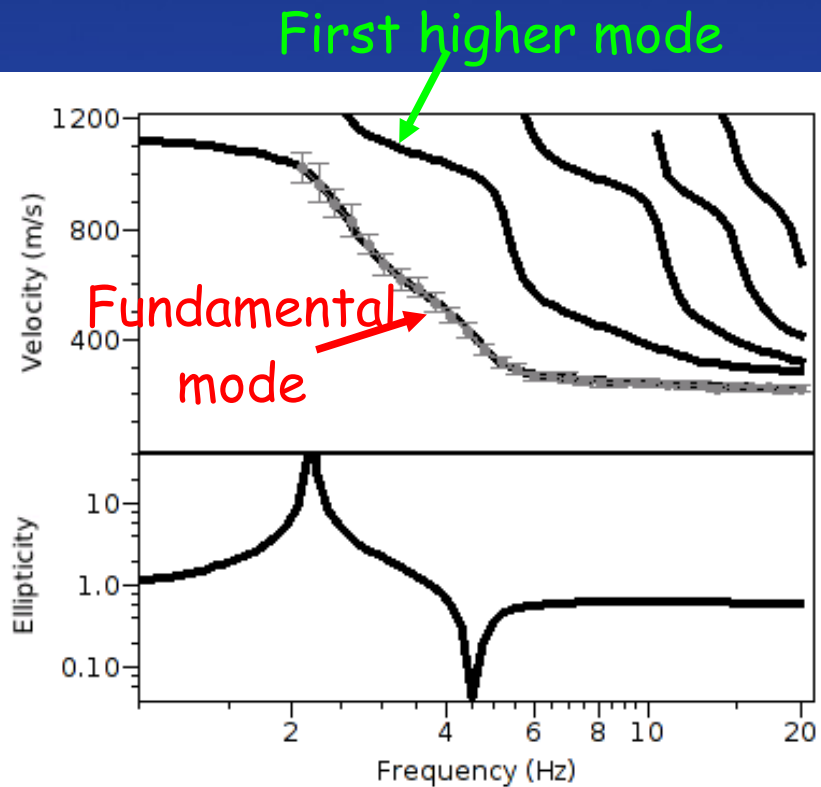
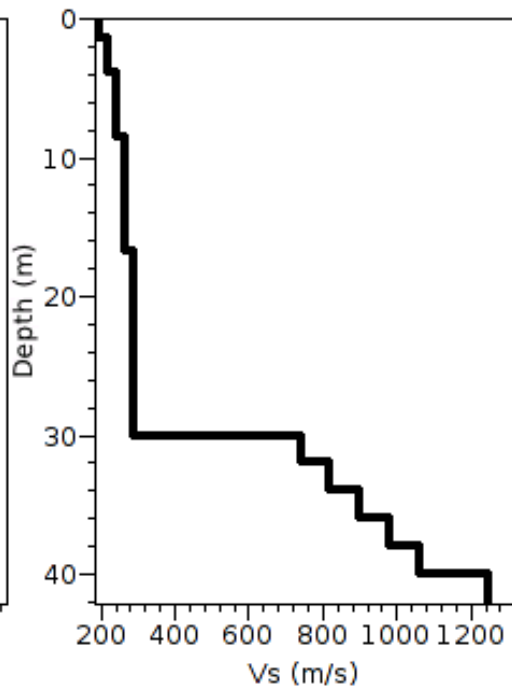
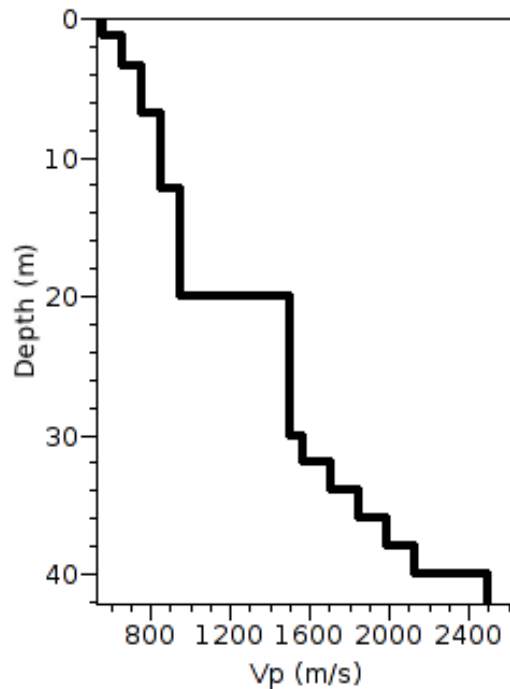
Dynamic scaling



Various random seeds: robustness

# 5. Dispersion curve inversion

Virtual test site: Vp and Vs structure



# Parameterization of a 2-layer model

Vp

Uniform Linked to Vs0  
 Vp0: 200 to 5000 m/s  Fixed Bottom depth

---

Uniform  Vp0 < Vp1  
 Vp1: 200 to 5000 m/s  Fixed

Vs

Power law Linked to Not linked  
 Number of sub-layers 5 Bottom depth  
 Top Vs0: 150 to 3500 m/s  Fixed  
 Bottom Vs0: 150 to 3500 m/s  Fixed  
 DVs0: 5 to 50 m  Fixed

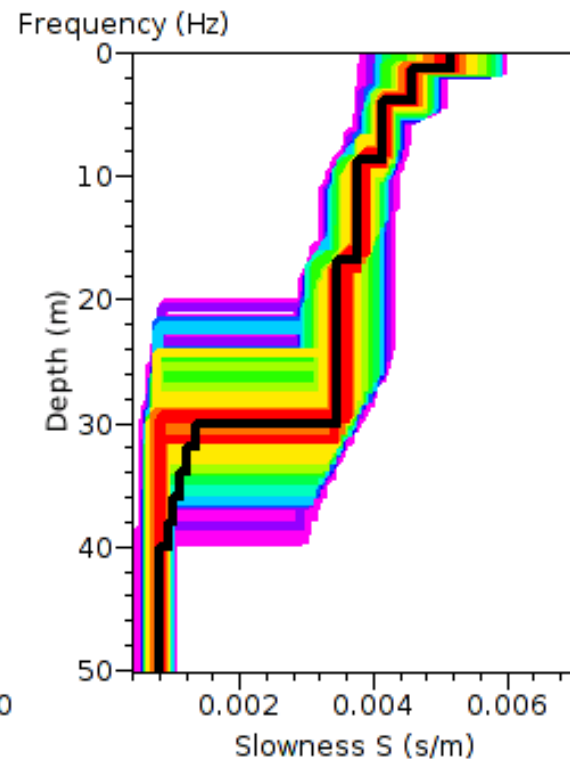
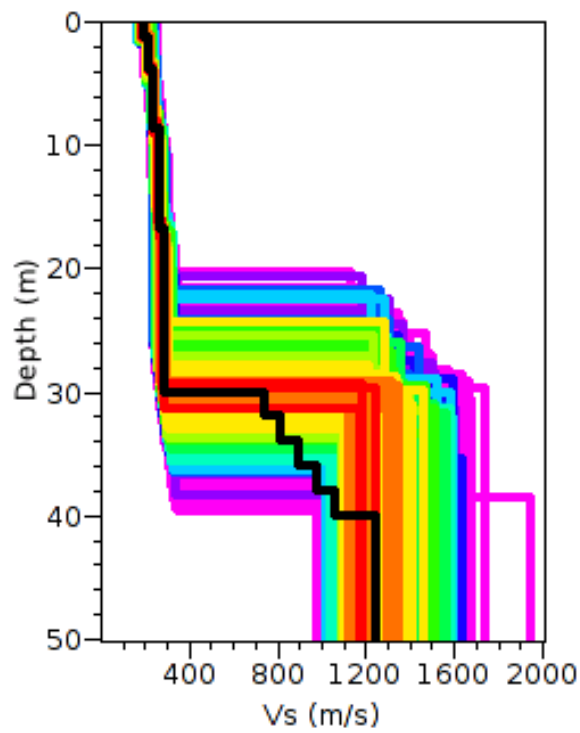
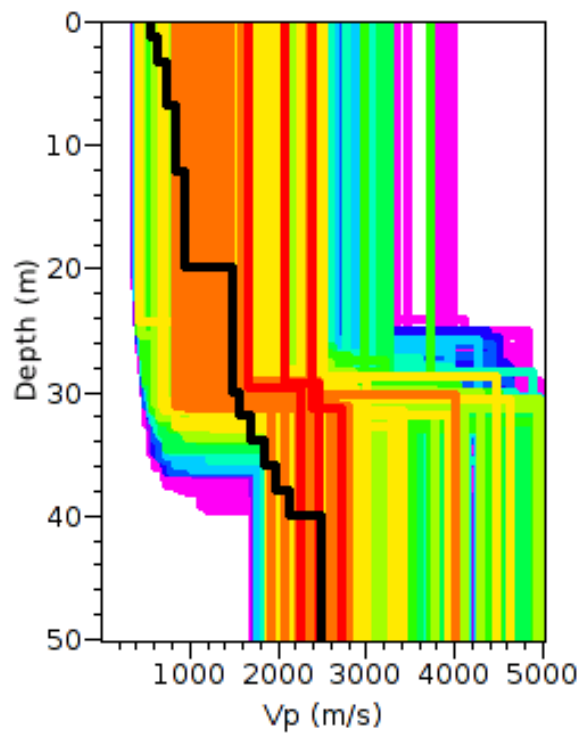
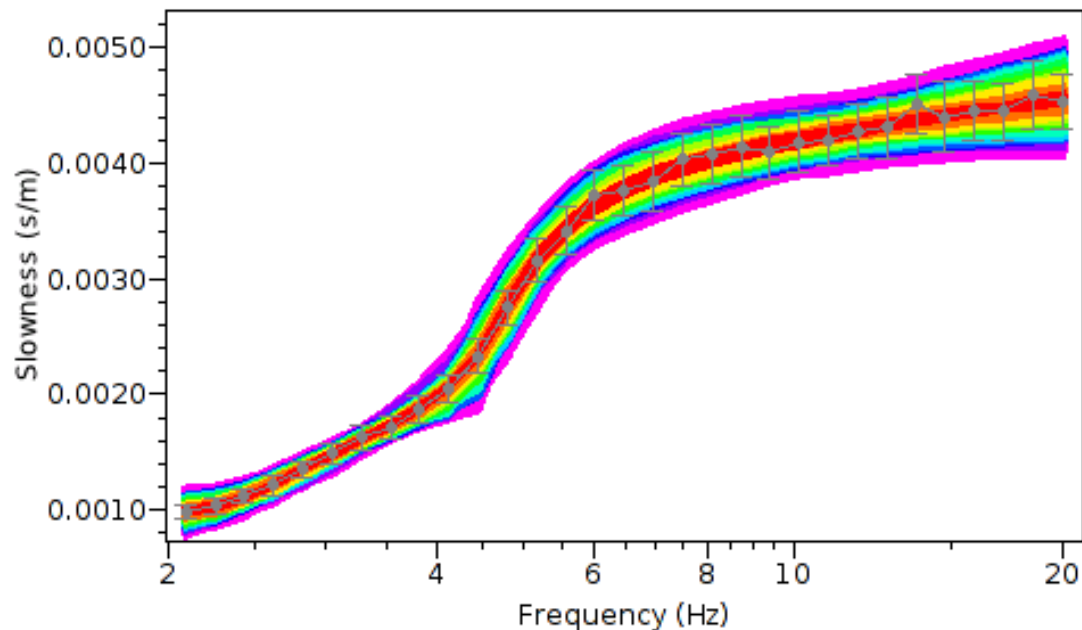
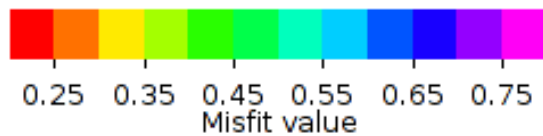
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Uniform  Vs0 < Vs1  
 Vs1: 150 to 3500 m/s  Fixed

Density

Uniform  
 Rho0: 2 t/m3  Fixed

# 2-layer model



# Parameterization of a 3-layer model

Vp

Uniform Linked to Vs1  
 Vp0: 200 to 5000 m/s  Fixed Bottom depth

---

Uniform  Vp0 < Vp1  
 Vp1: 200 to 5000 m/s  Fixed

Vs

Power law Linked to Not linked  
 Number of sub-layers 5 Bottom depth  
 Top Vs0: 150 to 3500 m/s  Fixed  
 Bottom Vs0: 150 to 3500 m/s  Fixed DV0: 5 to 50 m  Fixed

---

Power law  Vs0 < Vs1 Linked to Not linked  
 Number of sub-layers 5 Bottom depth  
 Top Vs1: 150 to 3500 m/s  Fixed  
 Bottom Vs1: 150 to 3500 m/s  Fixed DV1: 5 to 50 m  Fixed

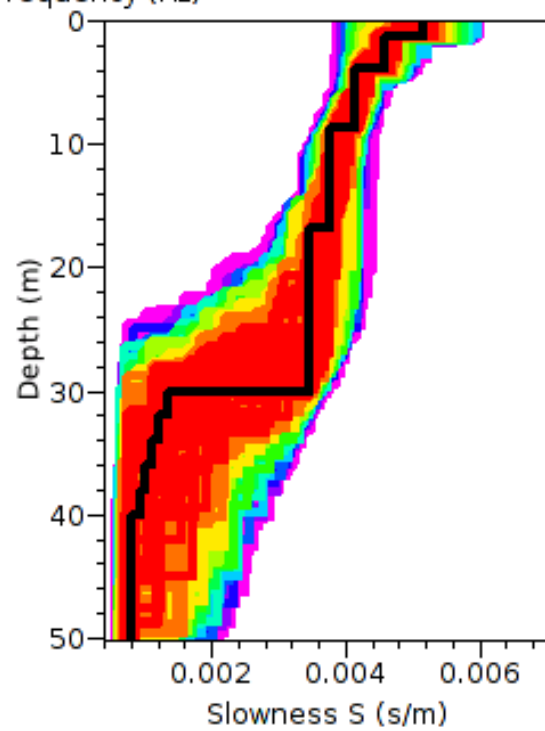
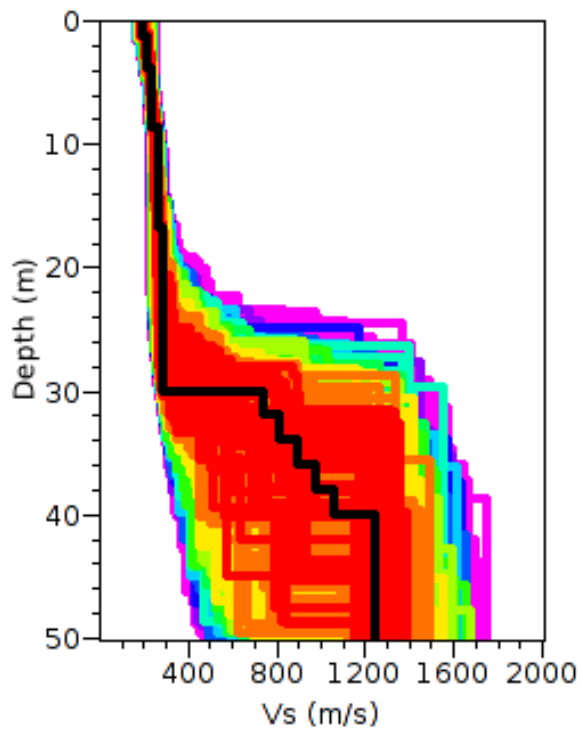
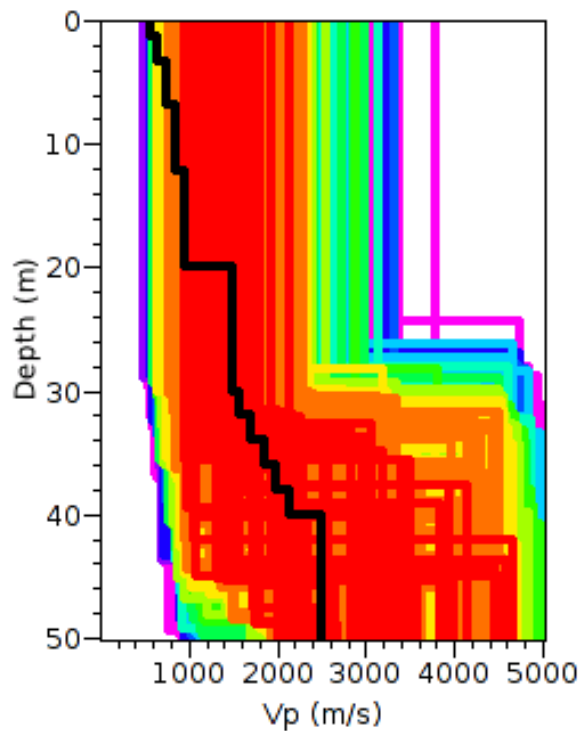
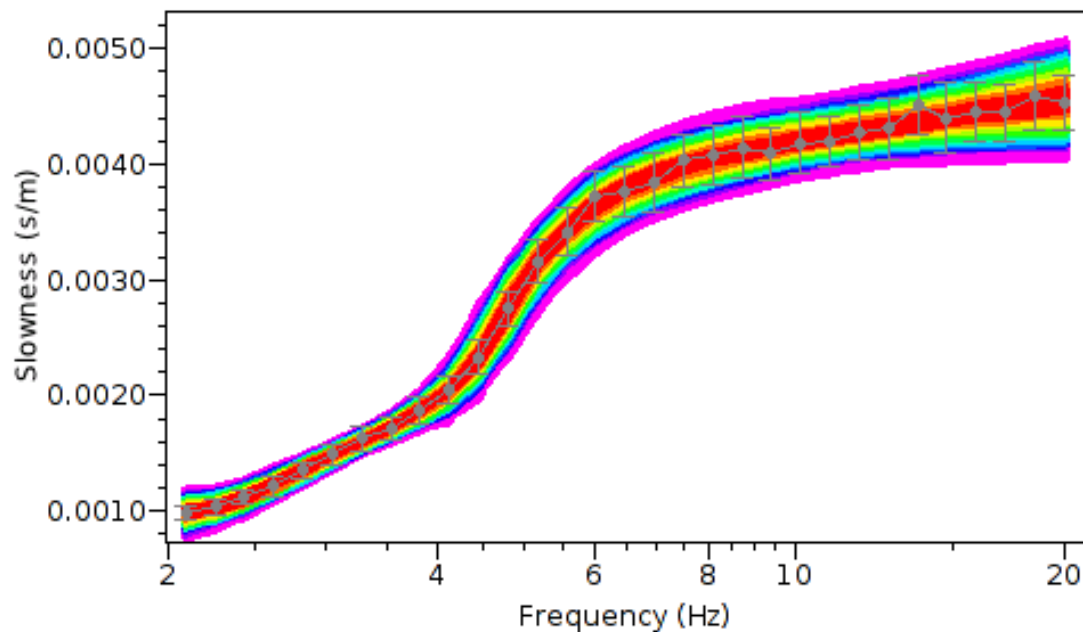
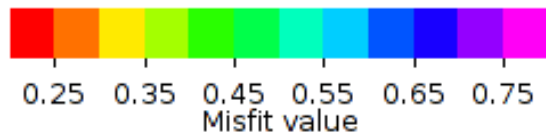
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Uniform  Vs1 < Vs2  
 Vs2: 150 to 3500 m/s  Fixed

Density

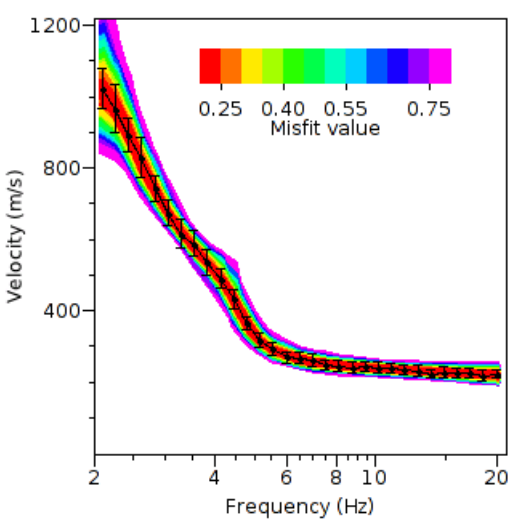
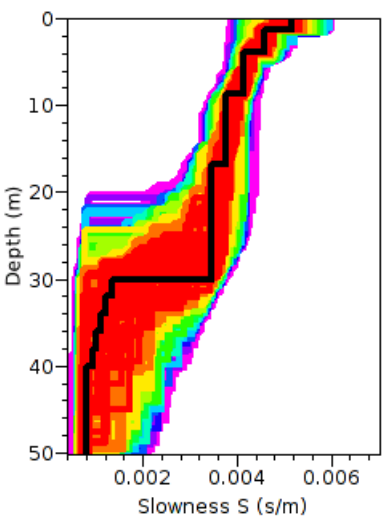
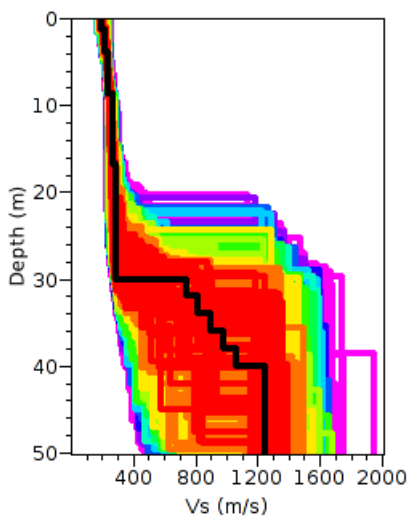
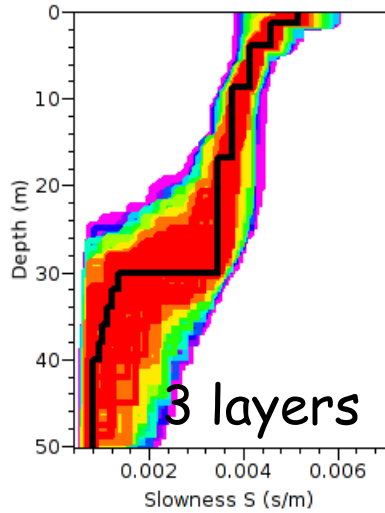
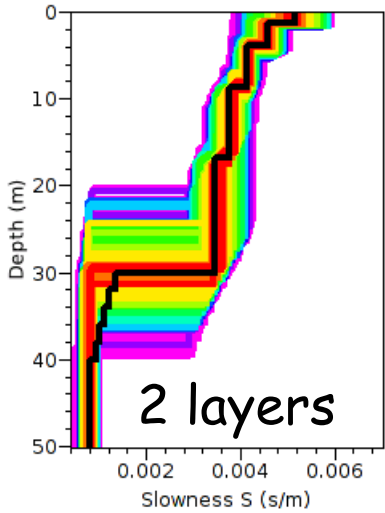
Uniform  
 Rho0: 2 t/m3  Fixed

# 3-layer model





# 2-layer models or 3-layer models What's the best solution?



We can merge  
all models

**ONLY**

if the misfit is  
computed in  
the same way

# Parameterization of a 15-layer model

=> Identical to the classical approach (Herrmann, linearization, gradient methods)

Vs

<input type="radio"/> Uniform	Linked to Not linked
Vs0: 150 to 3500 m/s <input type="checkbox"/> Fixed	Bottom depth DVs0: 2.5 m <input checked="" type="checkbox"/> Fixed
<input type="radio"/> Uniform <input type="checkbox"/> Vs0 < Vs1	Linked to Not linked
Vs1: 150 to 3500 m/s <input type="checkbox"/> Fixed	Bottom depth DVs1: 5 m <input checked="" type="checkbox"/> Fixed
<input type="radio"/> Uniform <input type="checkbox"/> Vs1 < Vs2	Linked to Not linked
Vs2: 150 to 3500 m/s <input type="checkbox"/> Fixed	Bottom depth DVs2: 7.5 m <input checked="" type="checkbox"/> Fixed

...

<input type="radio"/> Uniform <input type="checkbox"/> Vs12 < Vs13	Linked to Not linked
Vs13: 150 to 3500 m/s <input type="checkbox"/> Fixed	Bottom depth DVs13: 50 m <input checked="" type="checkbox"/> Fixed
<input checked="" type="radio"/> Uniform <input type="checkbox"/> Vs13 < Vs14	
Vs14: 150 to 3500 m/s <input type="checkbox"/> Fixed	

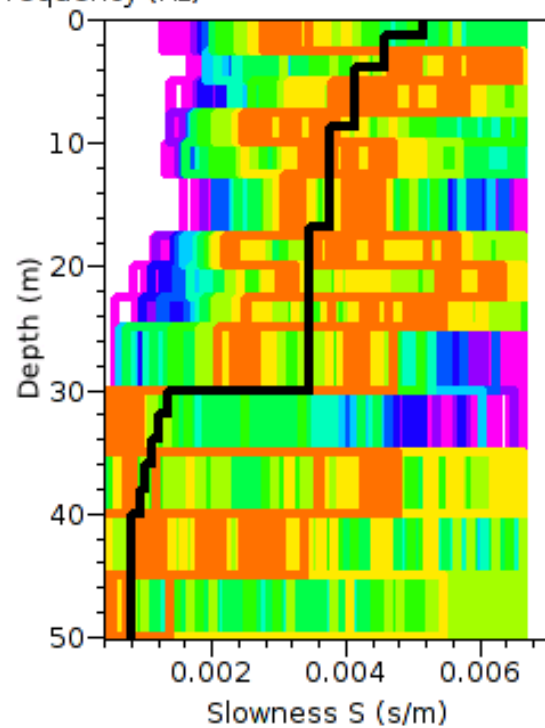
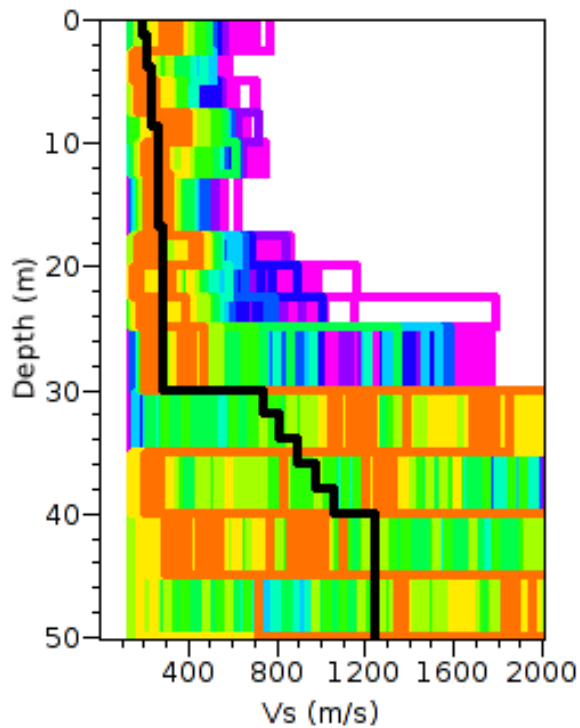
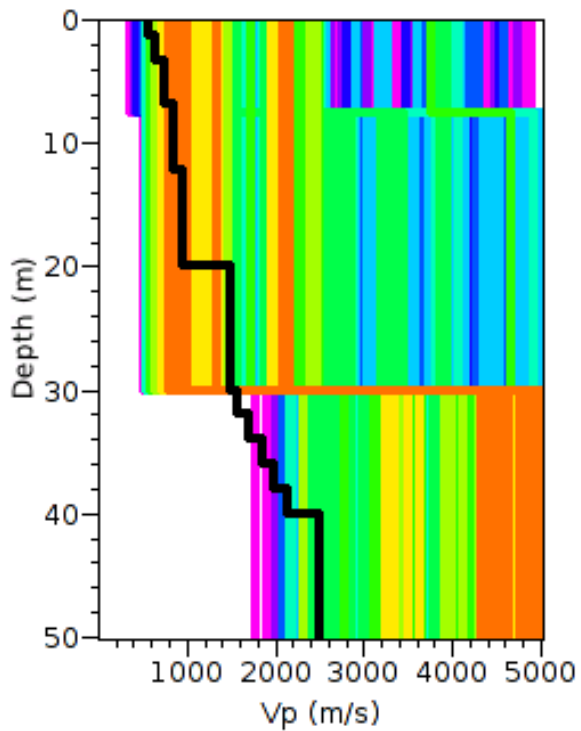
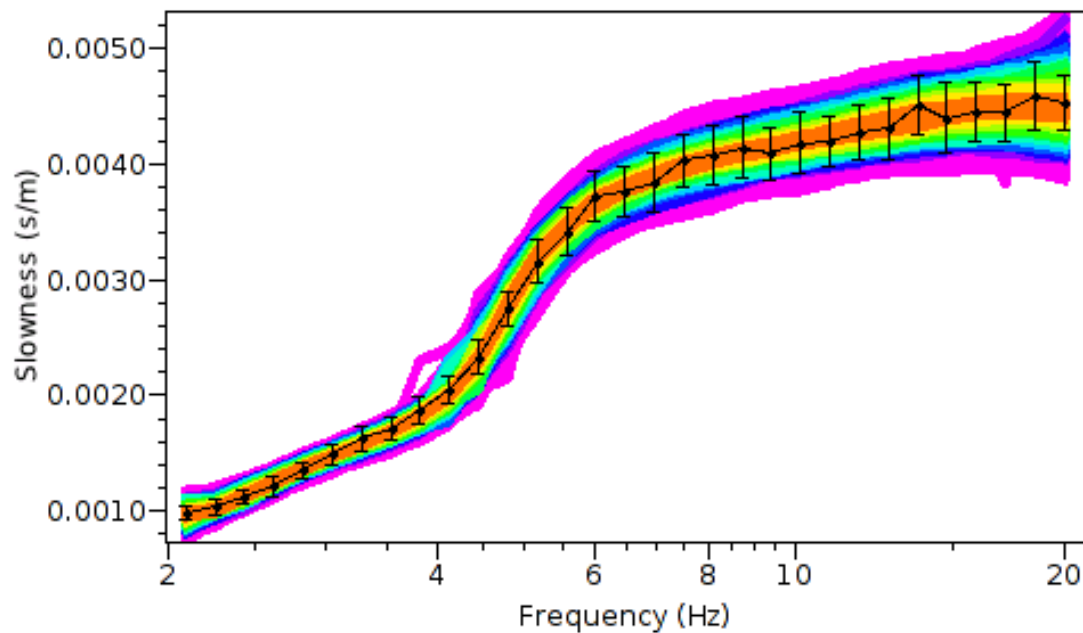
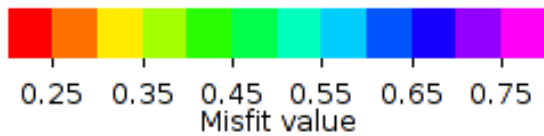
Vp

<input type="radio"/> Uniform	Linked to Vs9
Vp0: 200 to 5000 m/s <input type="checkbox"/> Fixed	Bottom depth
<input checked="" type="radio"/> Uniform <input checked="" type="checkbox"/> Vp0 < Vp1	
Vp1: 200 to 5000 m/s <input type="checkbox"/> Fixed	

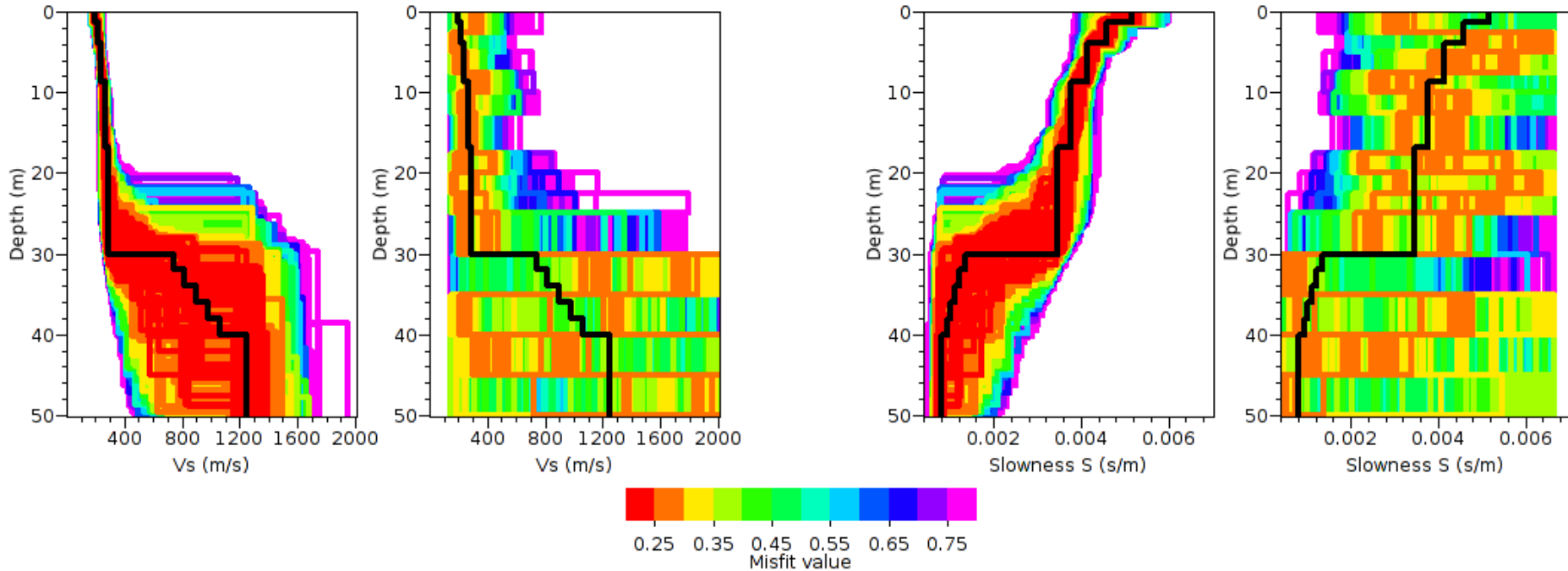
Density

<input checked="" type="radio"/> Uniform
Rho0: 2 t/m3 <input checked="" type="checkbox"/> Fixed

# 15-layer model



# Parameterization of a 15-layer model versus Limited number of layers (2-3)



Velocity

Slowness

# Parameterization of a 15-layer model

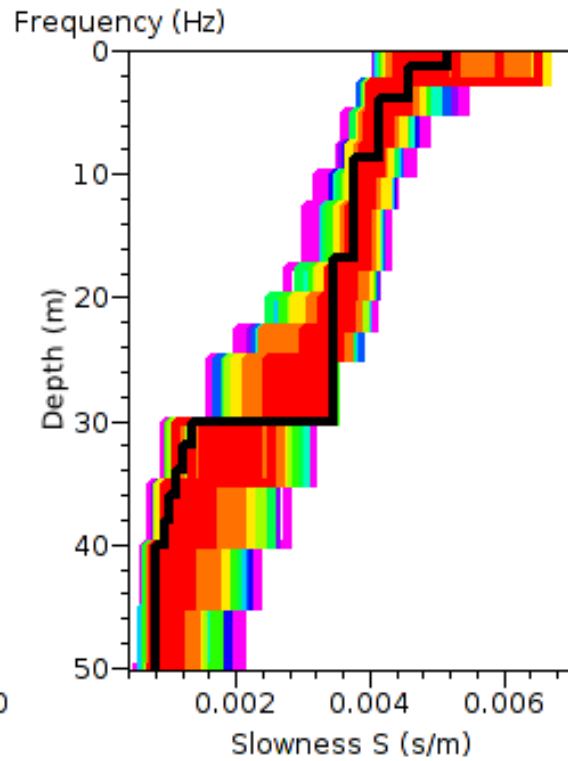
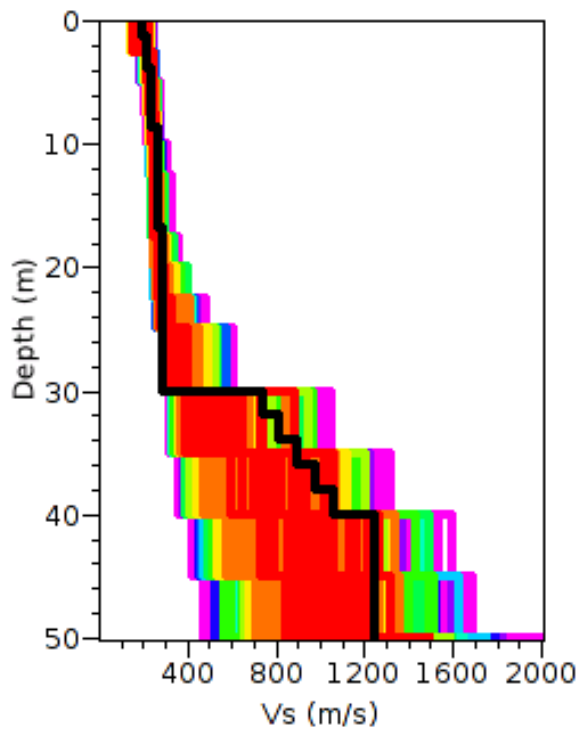
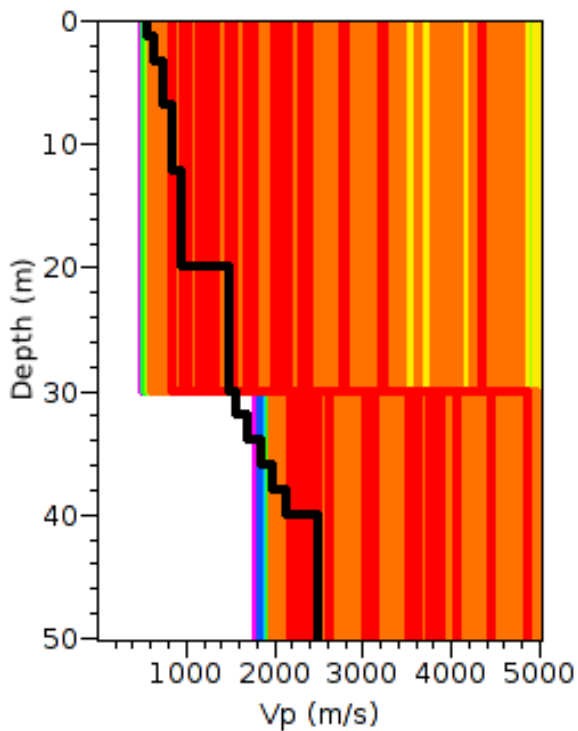
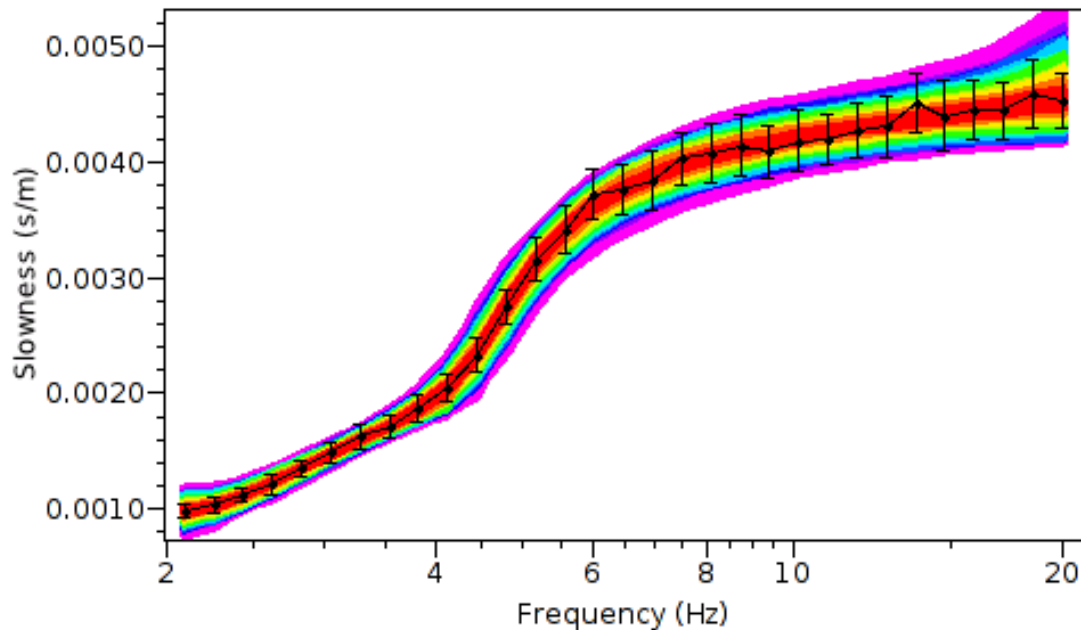
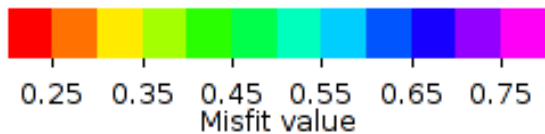
## Controlling the presence of low velocity zones

Vs

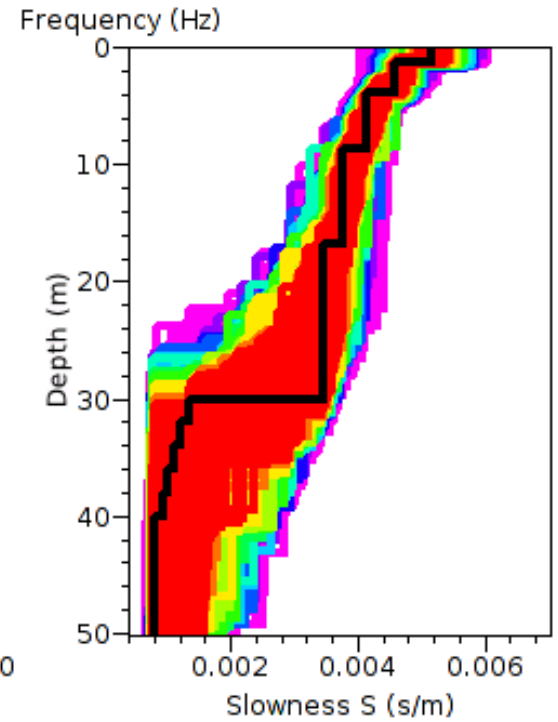
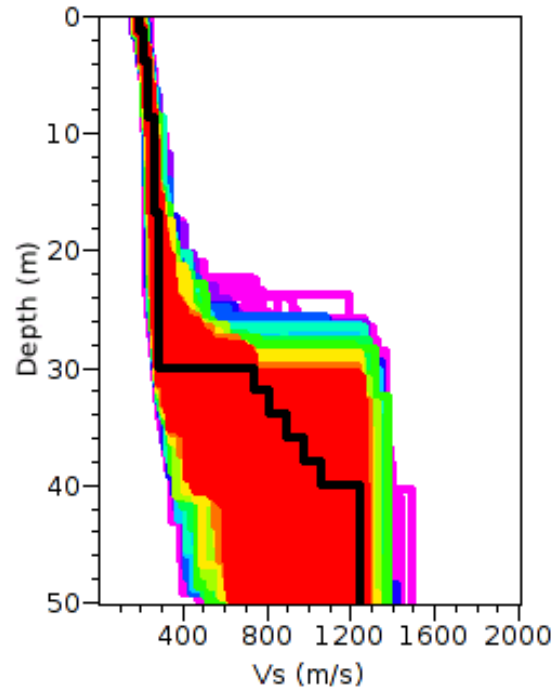
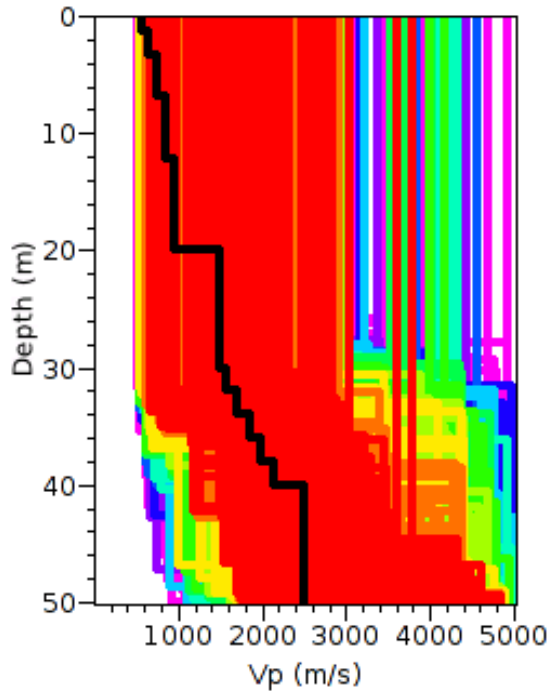
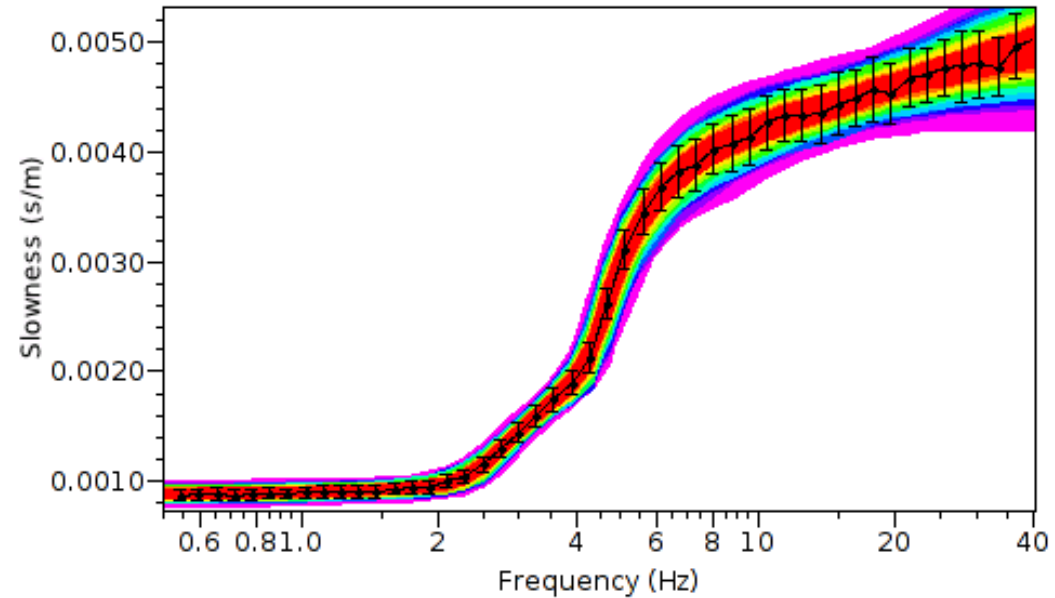
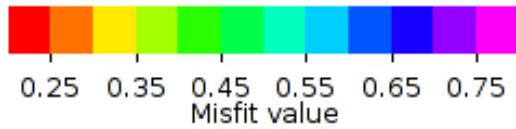
<input type="radio"/>	Uniform	Linked to	Not linked
Vs0: 150 to 3500 m/s		<input type="checkbox"/> Fixed	Bottom depth
DV0: 2.5 m		<input checked="" type="checkbox"/> Fixed	
<input type="radio"/>	Uniform	<input checked="" type="checkbox"/> Vs0 < Vs1	Linked to
Vs1: 150 to 3500 m/s		<input type="checkbox"/> Fixed	Not linked
DV1: 5 m		<input checked="" type="checkbox"/> Fixed	Bottom depth
<input type="radio"/>	Uniform	<input checked="" type="checkbox"/> Vs1 < Vs2	Linked to
Vs2: 150 to 3500 m/s		<input type="checkbox"/> Fixed	Not linked
DV2: 7.5 m		<input checked="" type="checkbox"/> Fixed	Bottom depth

<input type="radio"/>	Uniform	<input checked="" type="checkbox"/> Vs11 < Vs12	Linked to
Vs12: 150 to 3500 m/s		<input type="checkbox"/> Fixed	Not linked
DV12: 45 m		<input checked="" type="checkbox"/> Fixed	Bottom depth
<input type="radio"/>	Uniform	<input checked="" type="checkbox"/> Vs12 < Vs13	Linked to
Vs13: 150 to 3500 m/s		<input type="checkbox"/> Fixed	Not linked
DV13: 50 m		<input checked="" type="checkbox"/> Fixed	Bottom depth
<input checked="" type="radio"/>	Uniform	<input checked="" type="checkbox"/> Vs13 < Vs14	Linked to
Vs14: 150 to 3500 m/s		<input type="checkbox"/> Fixed	Not linked

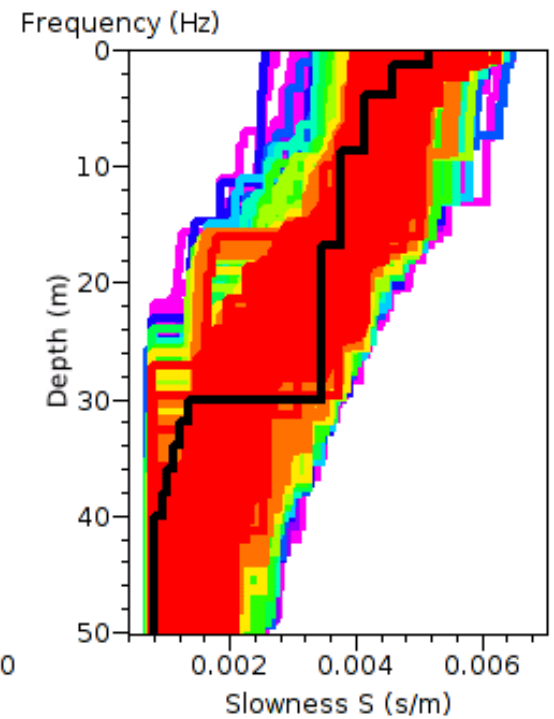
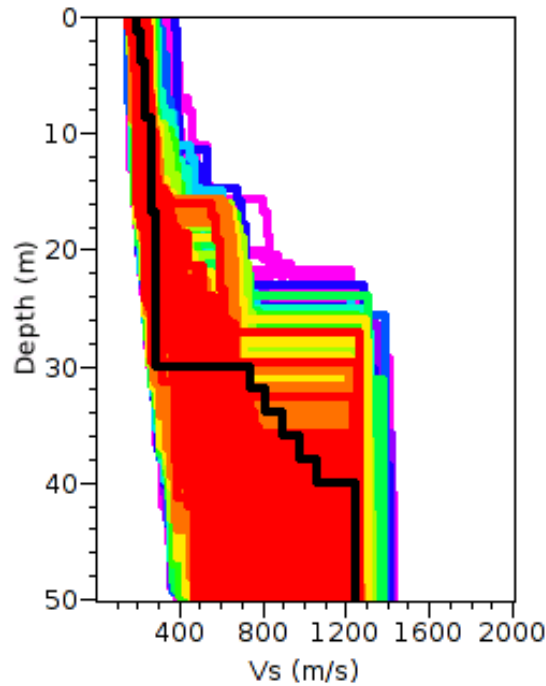
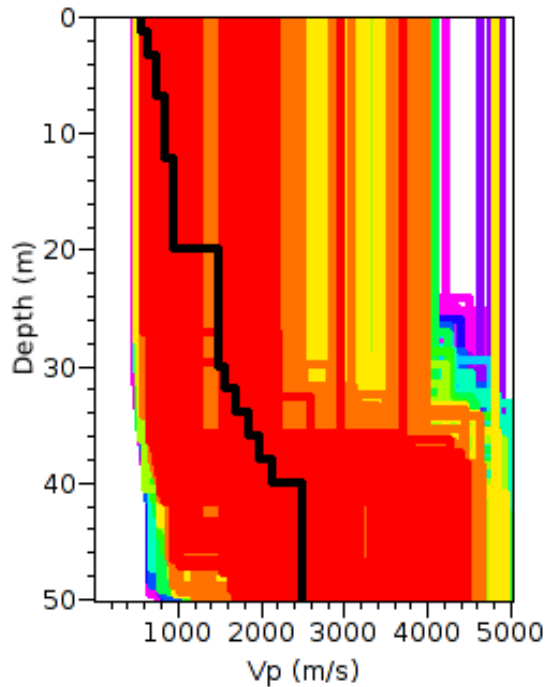
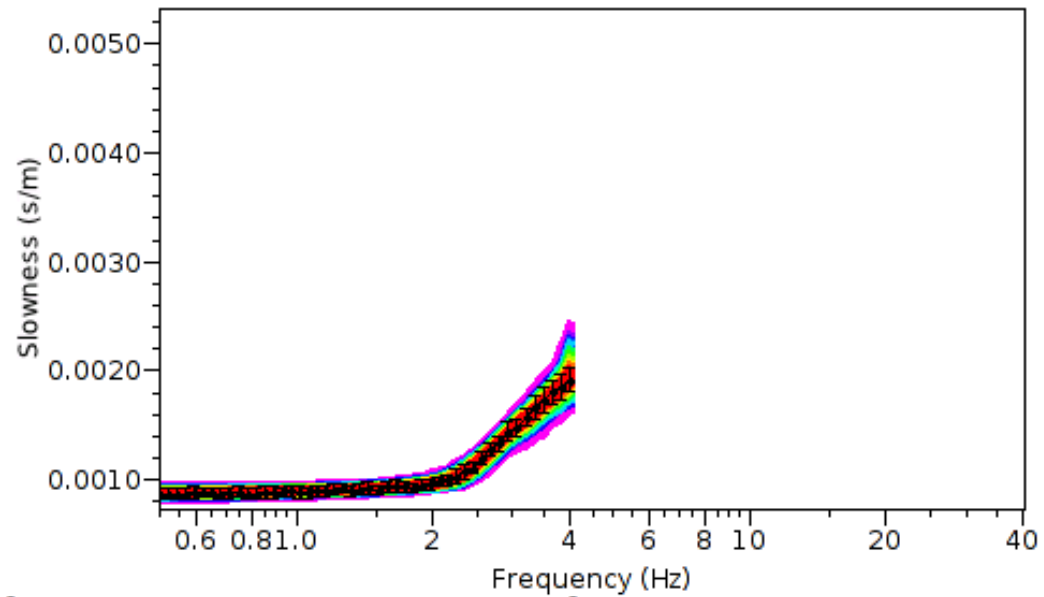
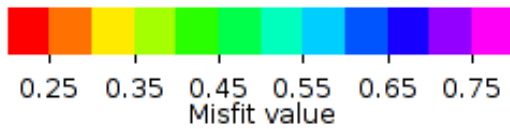
15-layer model  
No low velocity  
zones



# Full range dispersion curve

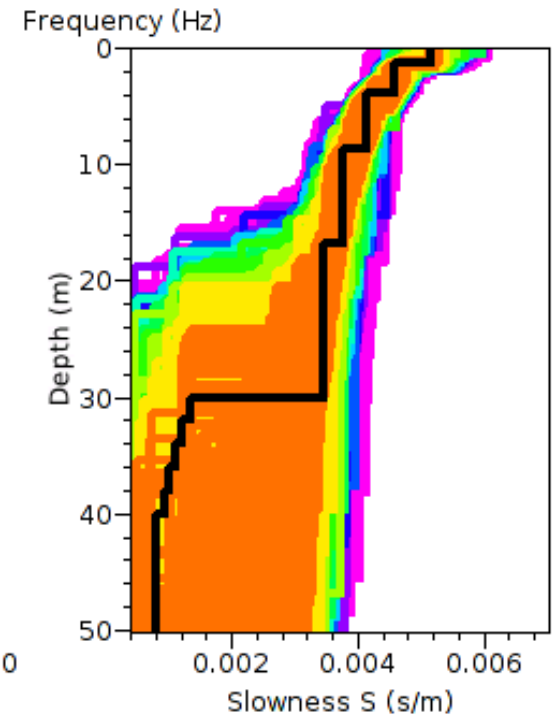
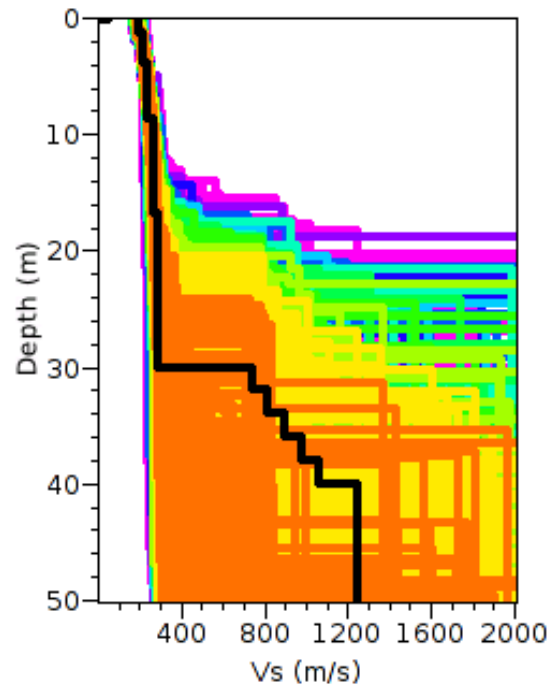
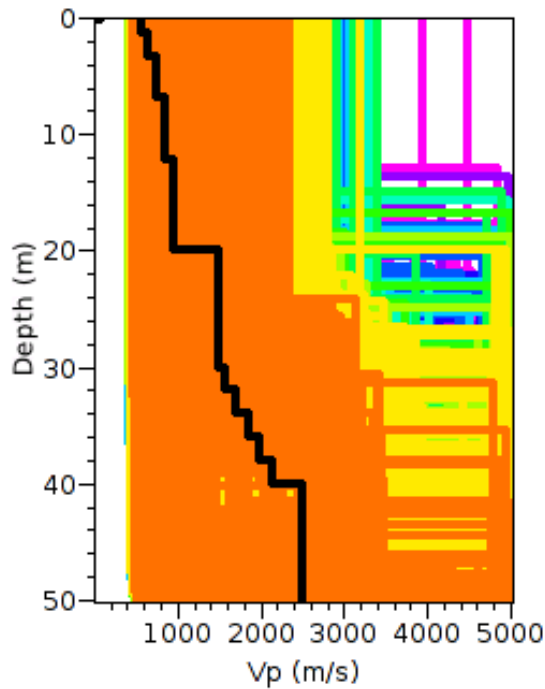
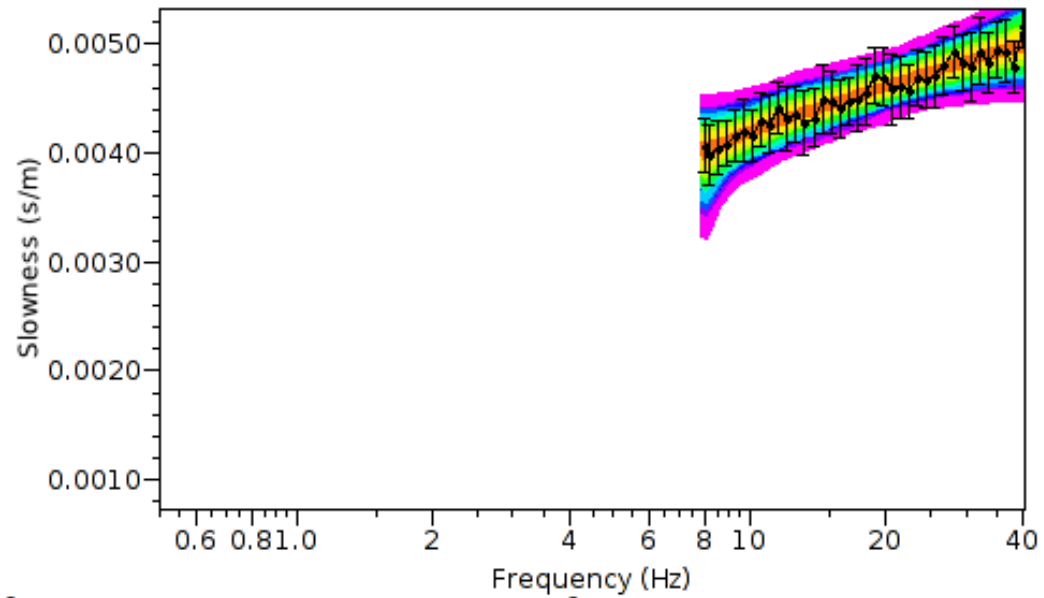
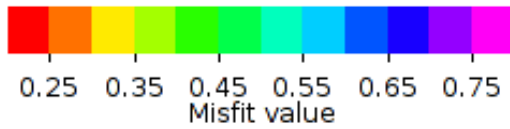


Low frequency

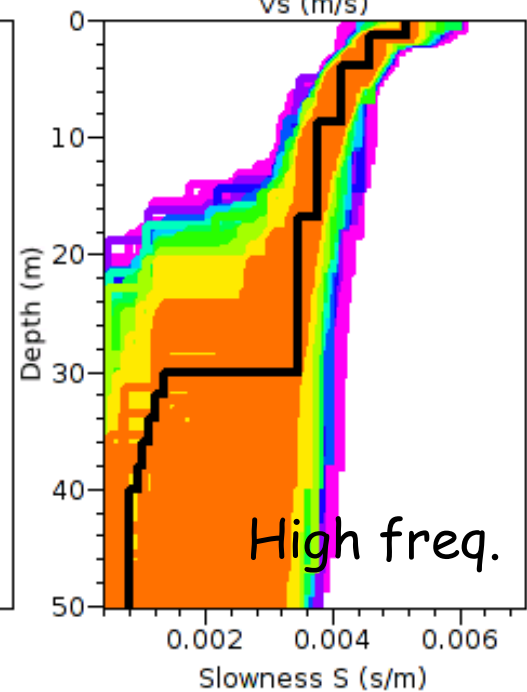
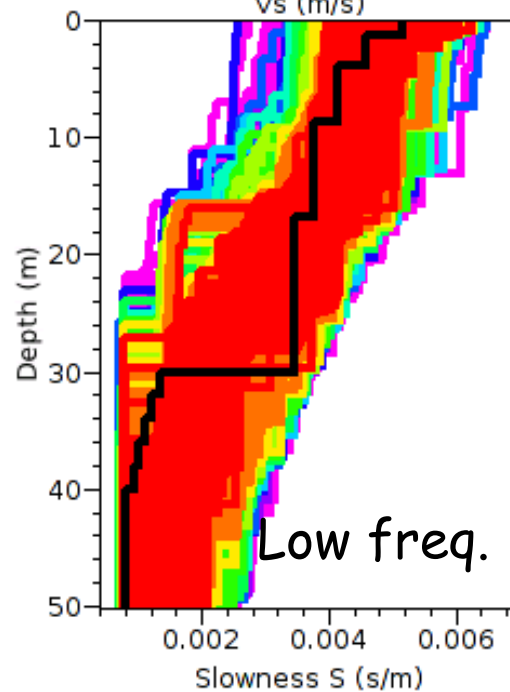
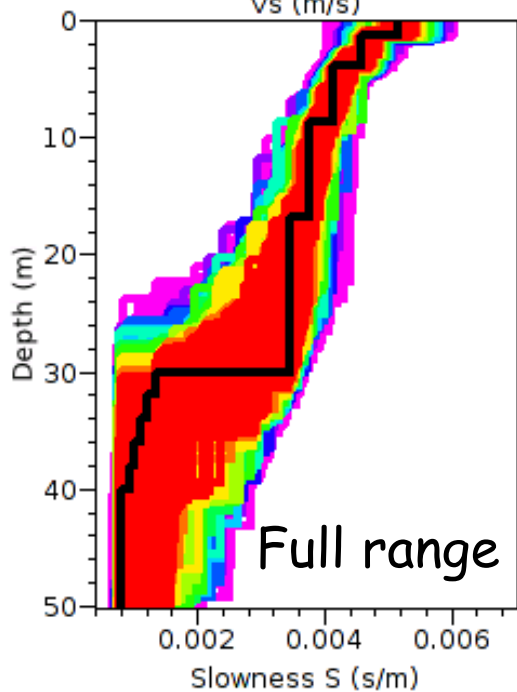
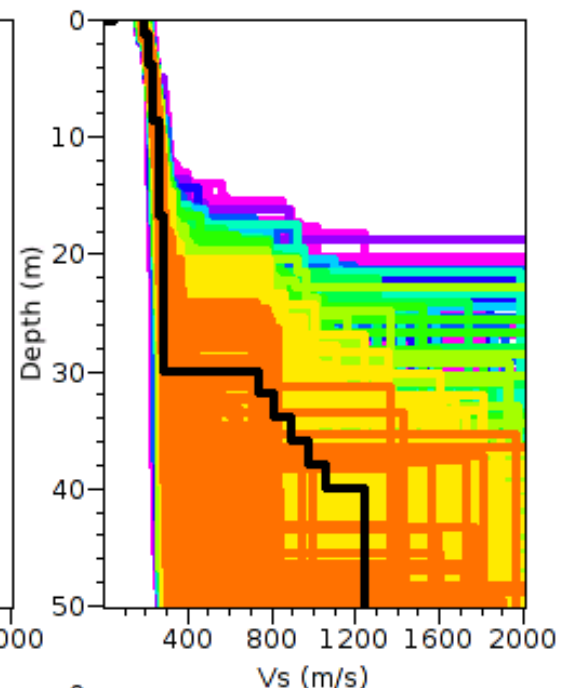
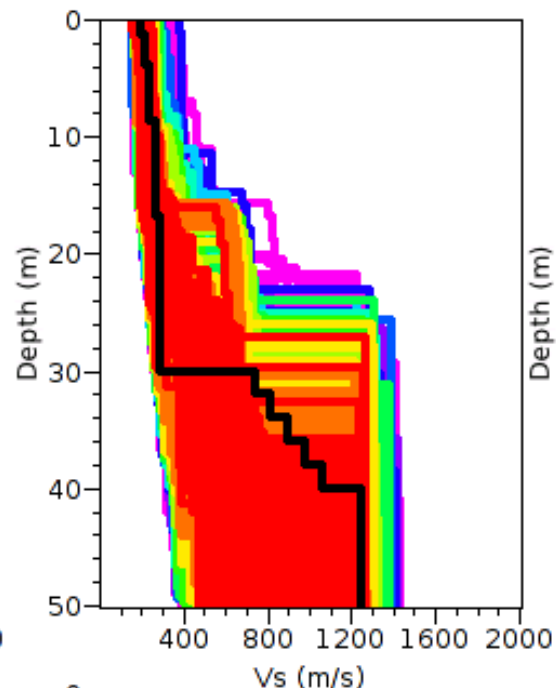
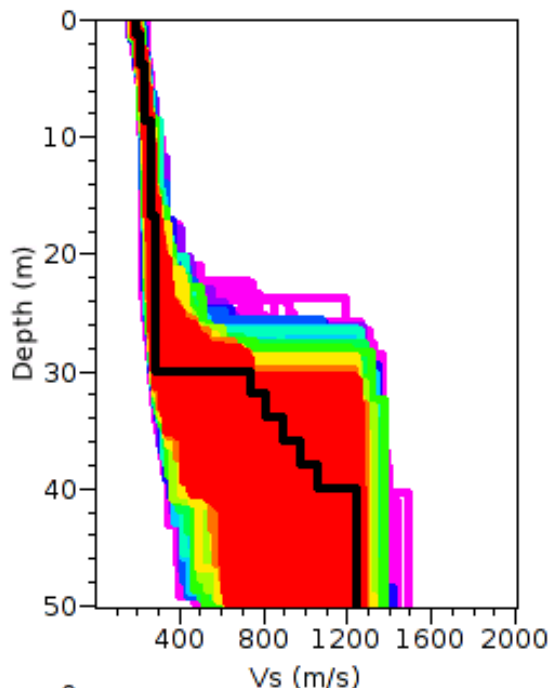




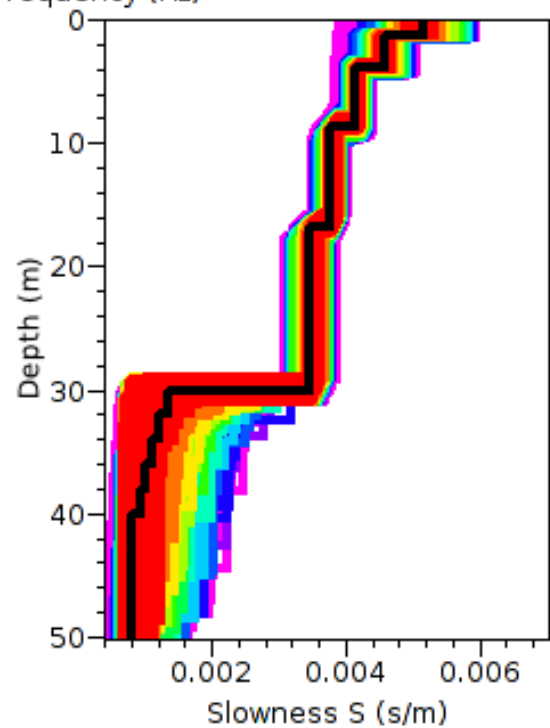
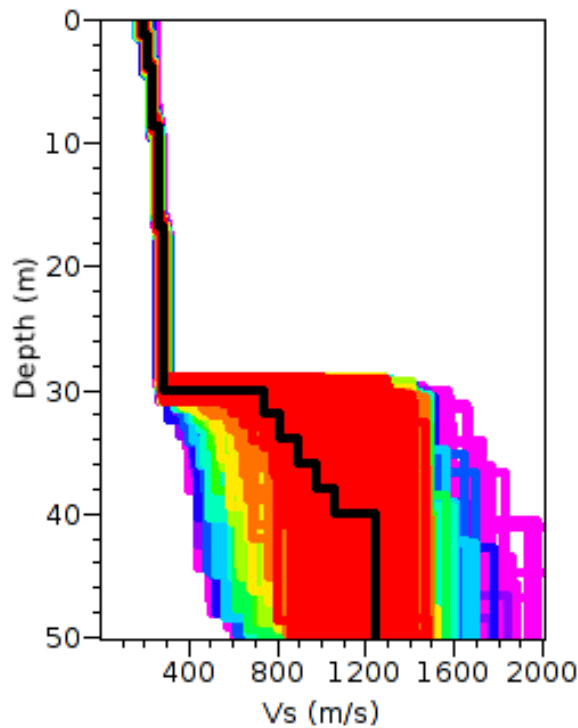
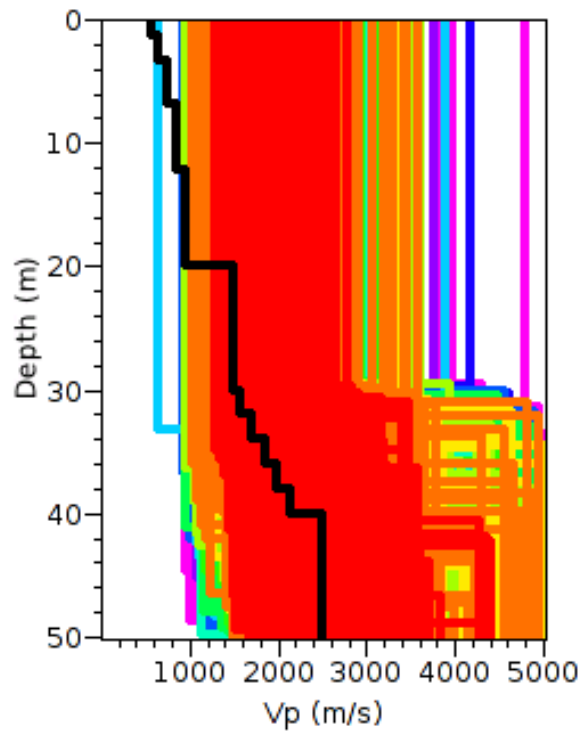
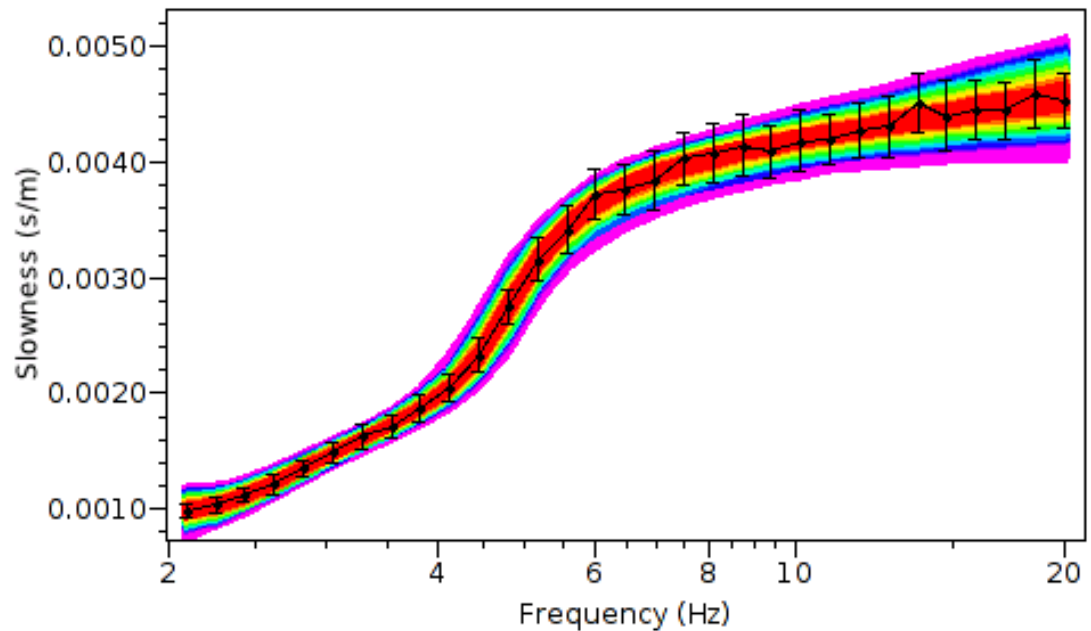
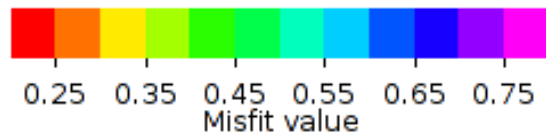
High frequency



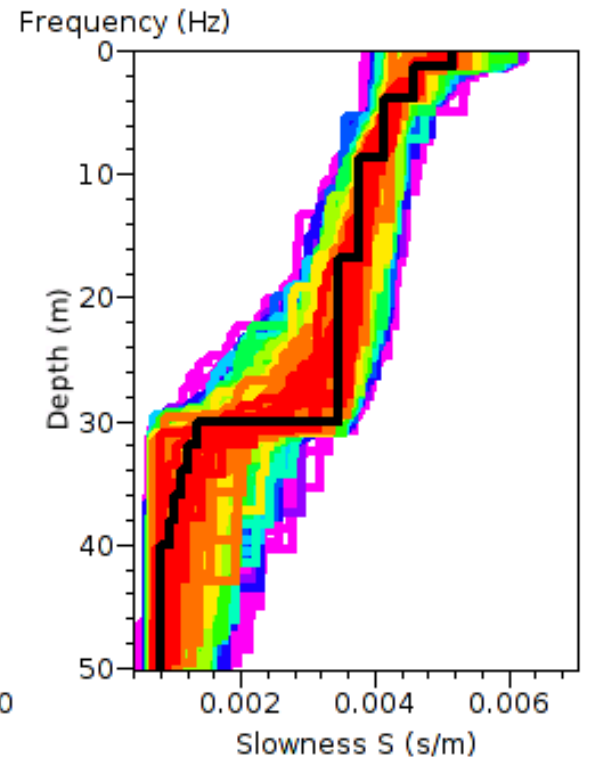
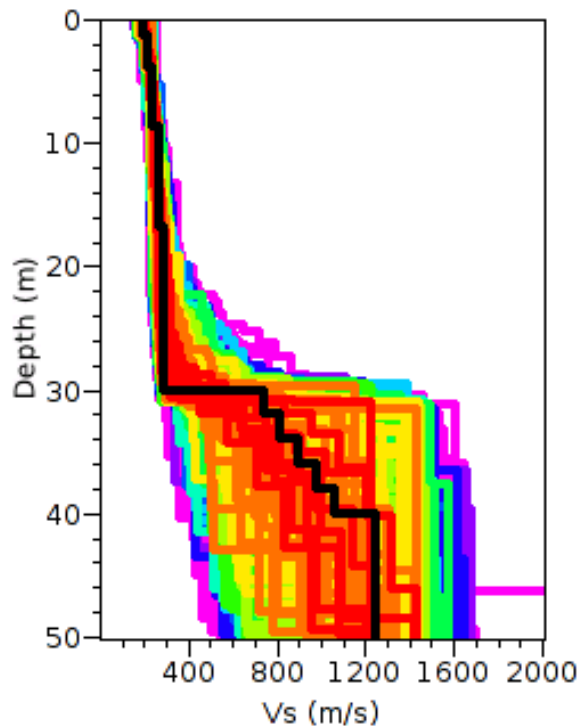
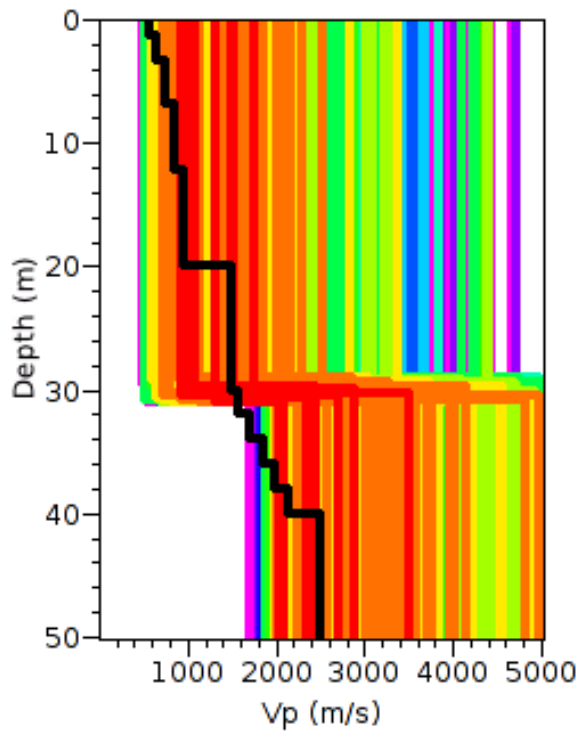
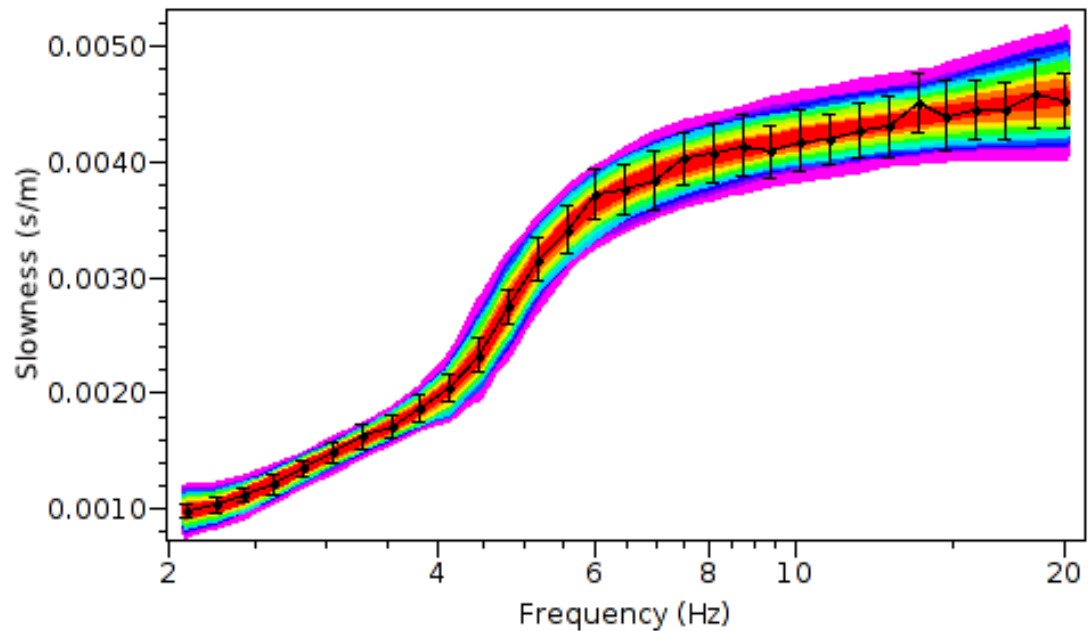
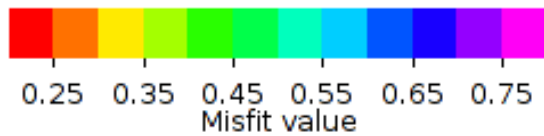
Effects of frequency range



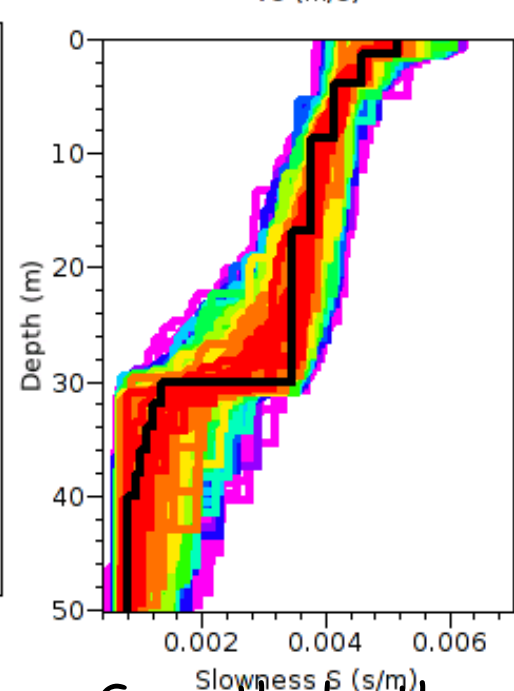
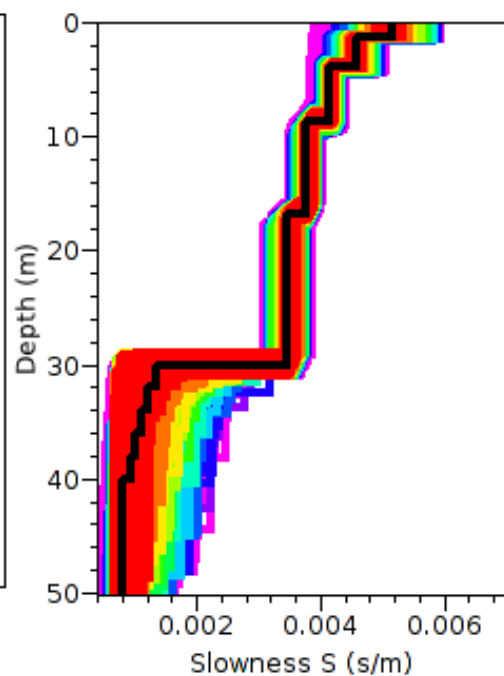
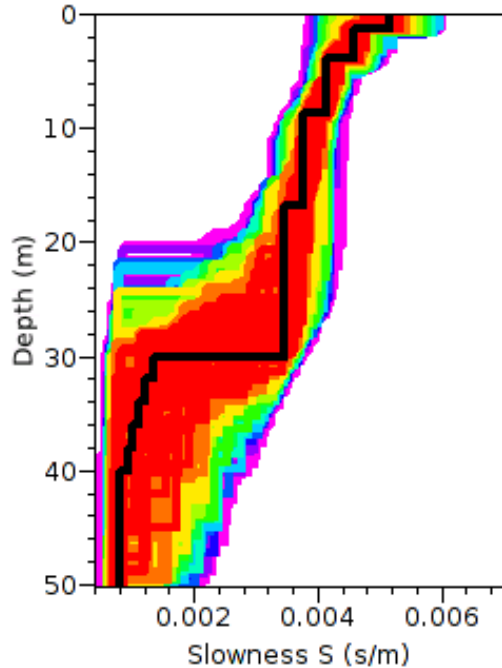
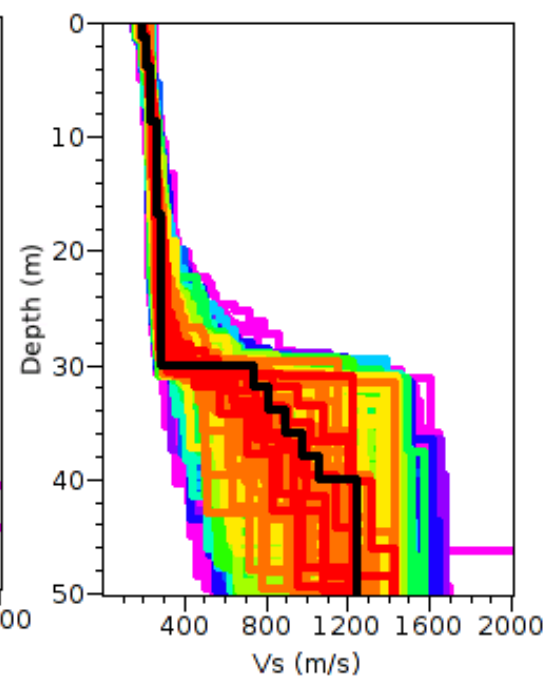
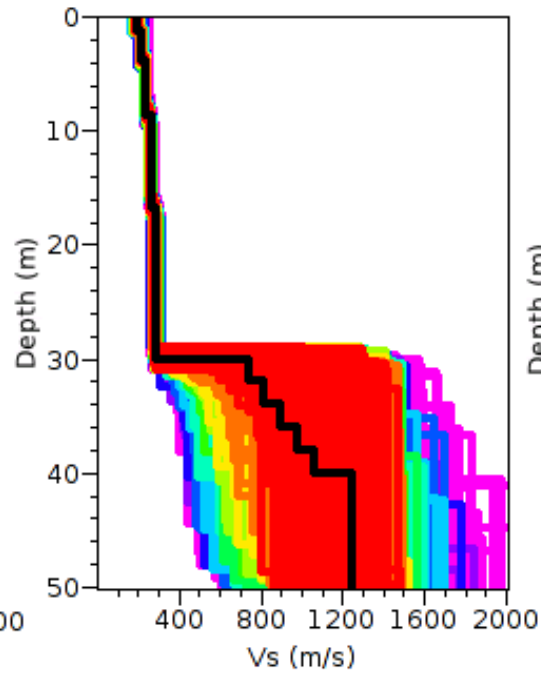
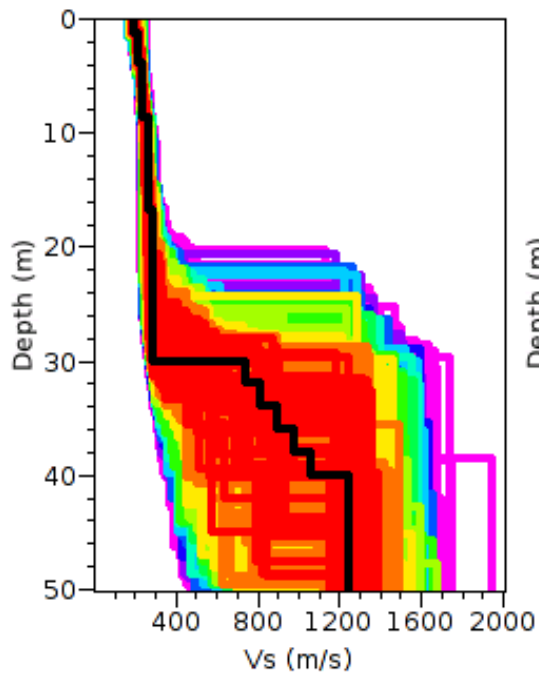
# Sharp depth constraint



# Smooth depth constraint



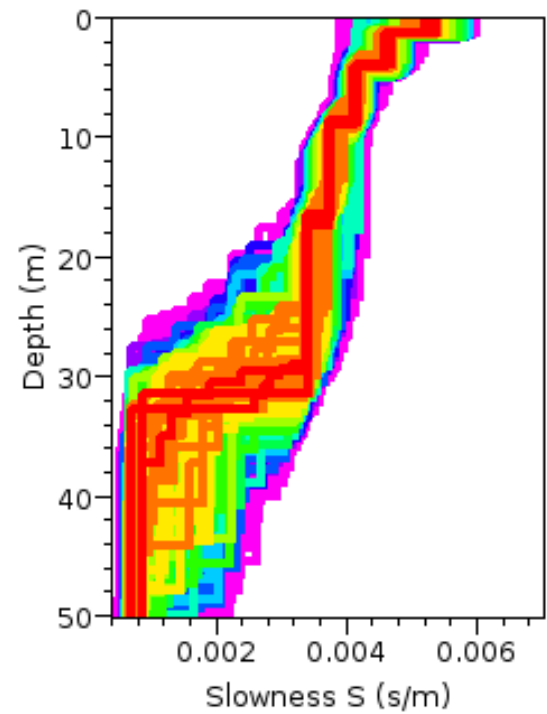
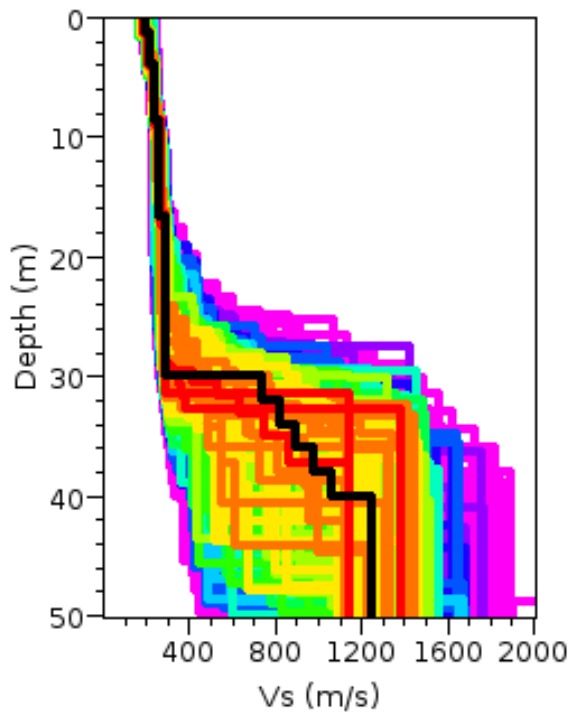
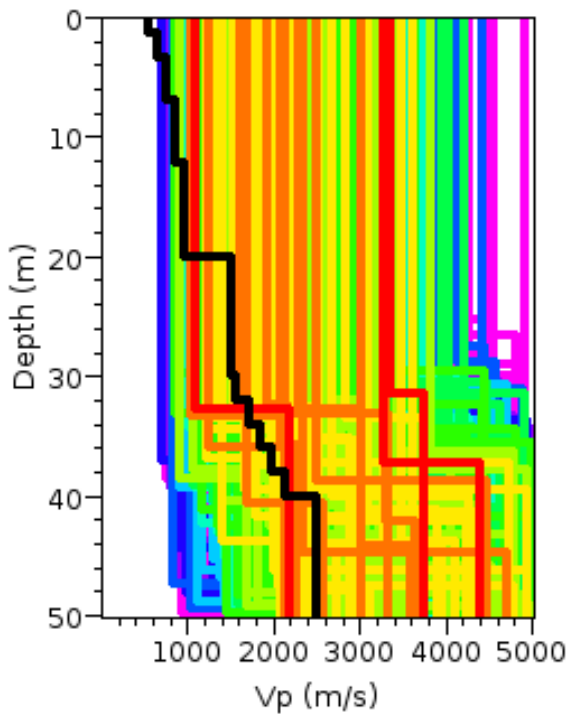
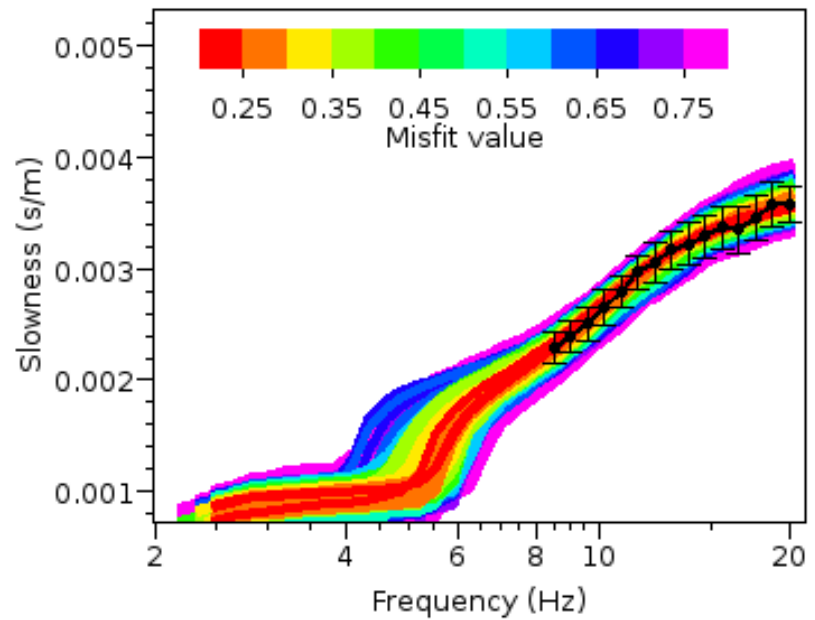
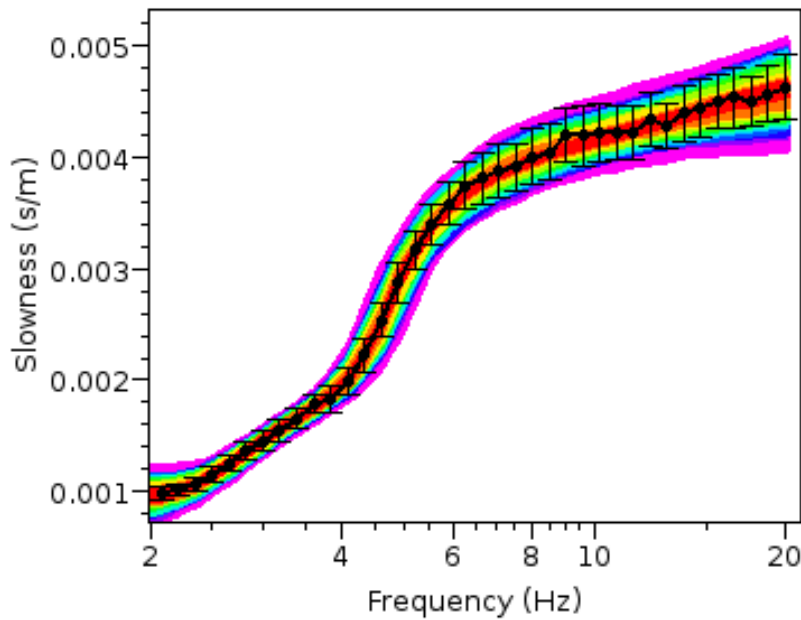
Effects of depth constraint



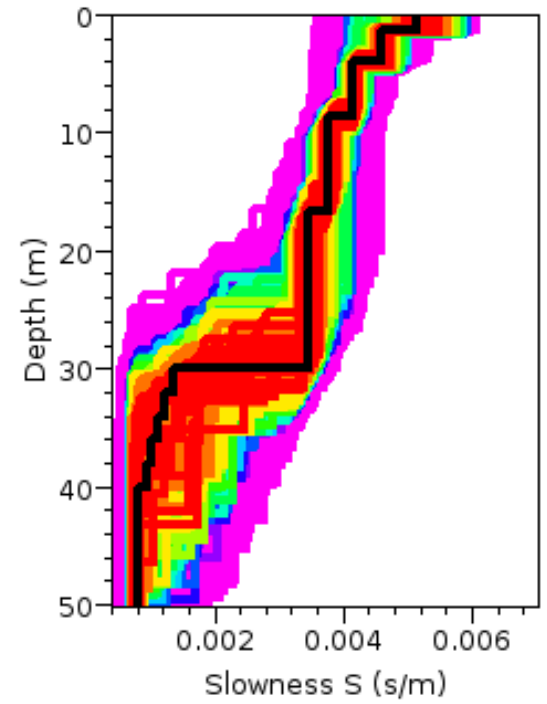
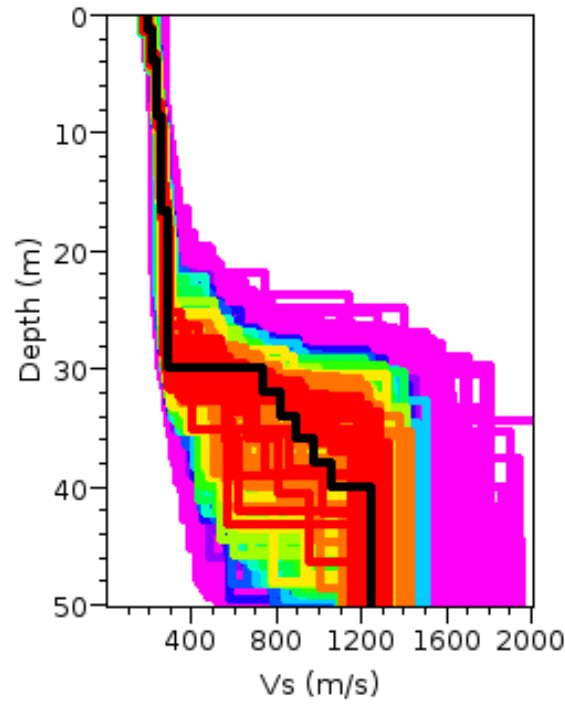
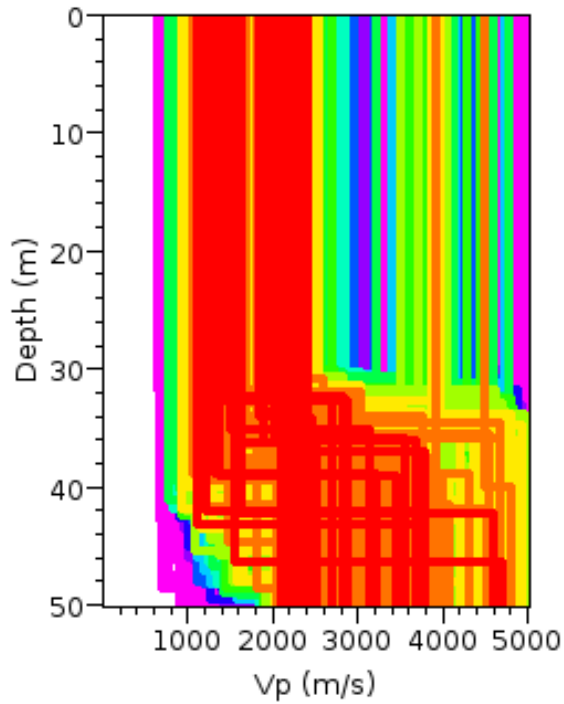
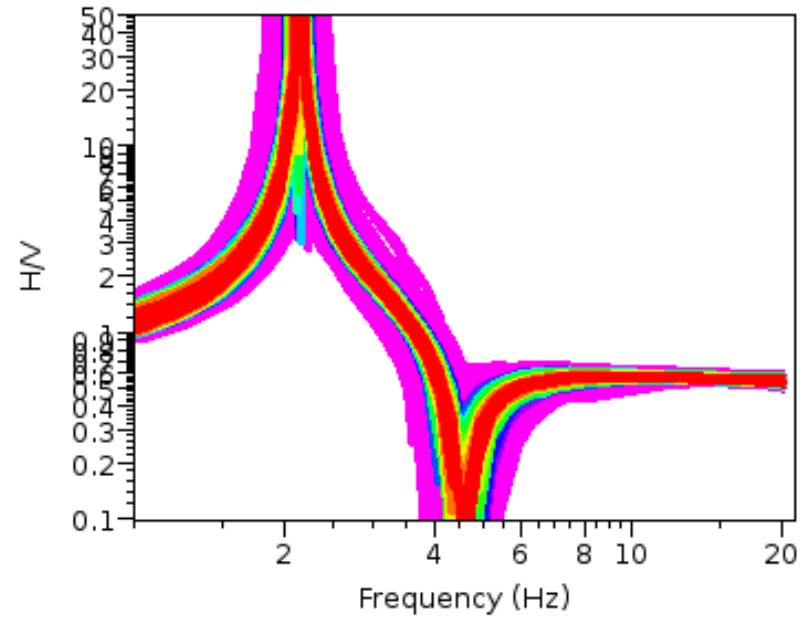
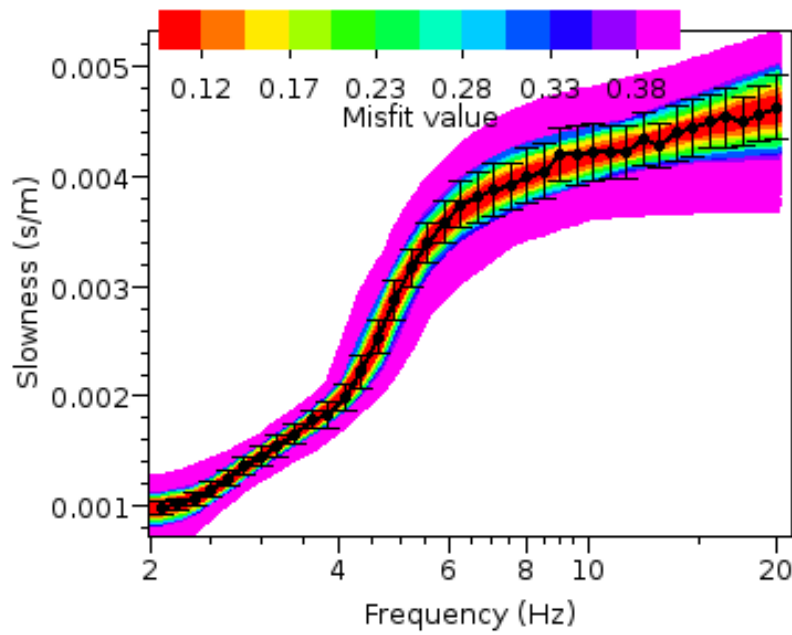
No constraint

Sharp depth

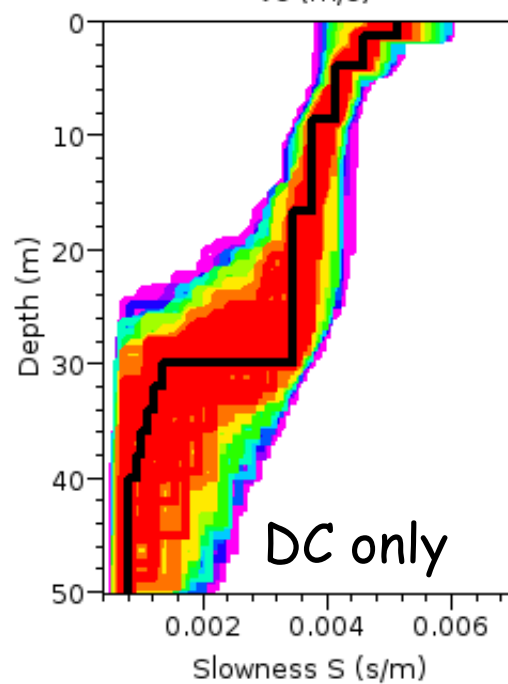
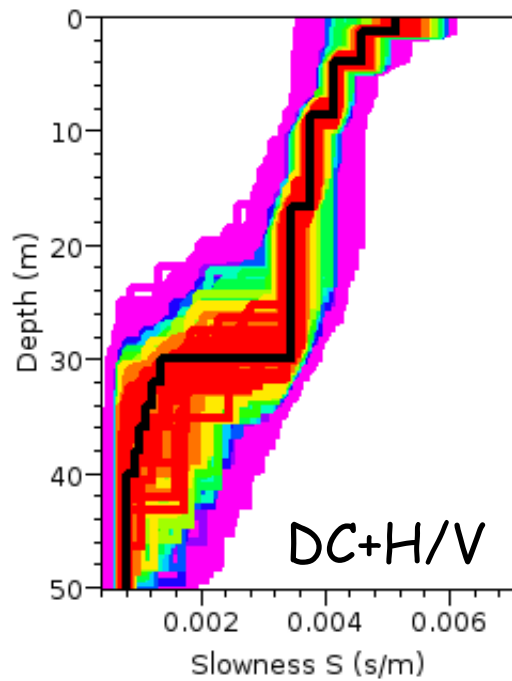
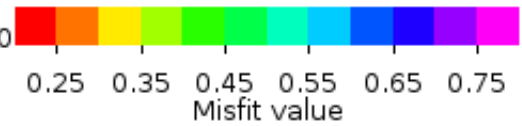
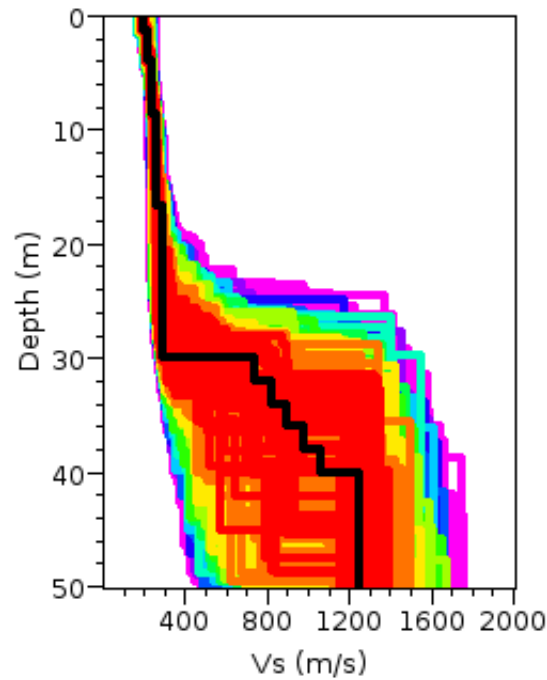
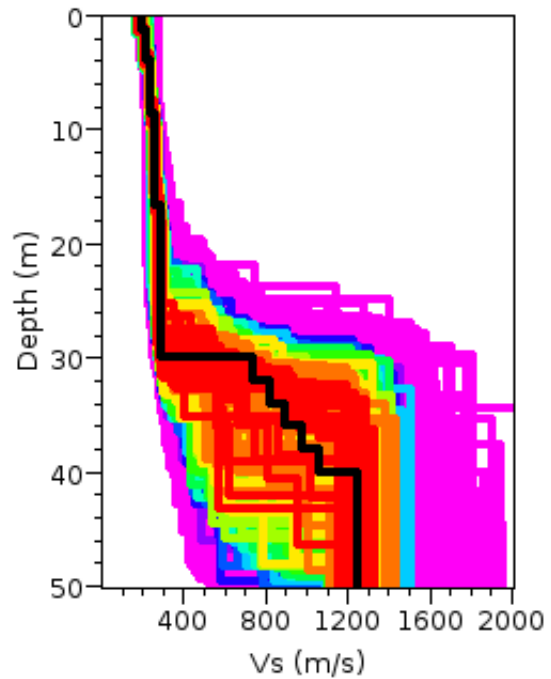
Smooth depth



# Joint inversion of H/V peak



Joint inversion of H/V peak





# Conclusions

- **New Neighborhood Algorithm for parameter spaces with irregular boundaries**
- **Exploration capabilities improved**
- Better exploration means also better data fit
- Less forward computations needed to achieve the same data fit
- Robust results: all seeds return the same model distribution