Seismic Hazard Assessment, 2016

UME School

Seismic Response Analysis: From Site Effects to Site Characterization Techniques

Valerio Poggi

GEM Foundation, Pavia, Italy

Lecture outline

- Motivation
- Understanding local seismic response and microzonation
- Relevant phenomena for the modification of the ground motion
- Seismic site response evaluation in practice
- Geophysical site characterization techniques (depending on available time)
- Site term in GMPEs
- Concluding remarks

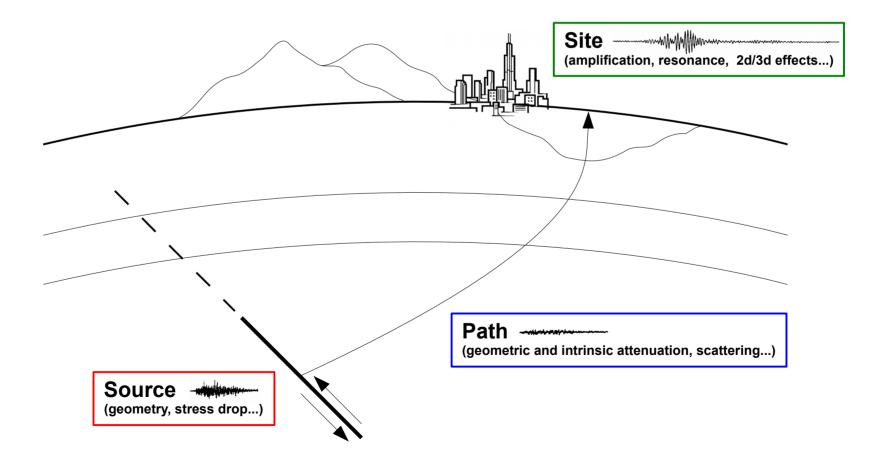


L'Aquila Earthquake 2009, Magnitude Mw 6.3

Introduction

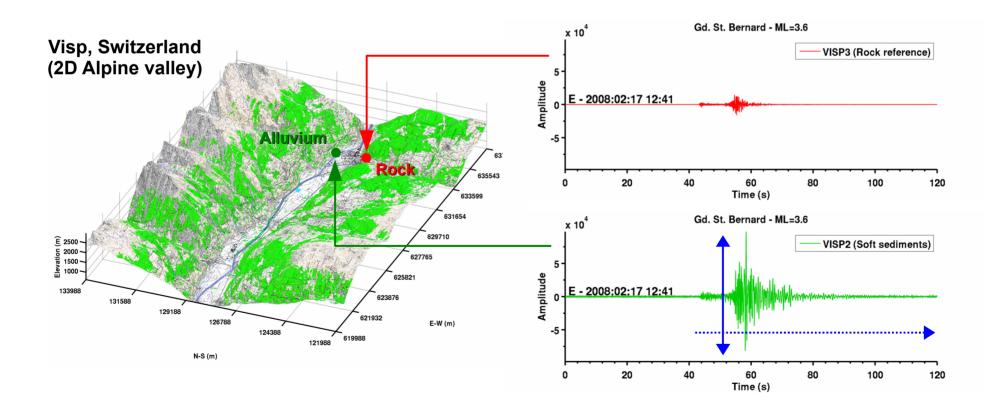
Factors controlling Ground Motion

- Earthquake signals can be strongly altered during their propagation from the **source** to the **observation point**
- Significant contribution comes from the uppermost few hundred meters of the earth structure, where the larger variability of the geological conditions is present
- As a result, the waveform at the recording station is generally very different from that one potentially observed close to the generating fault



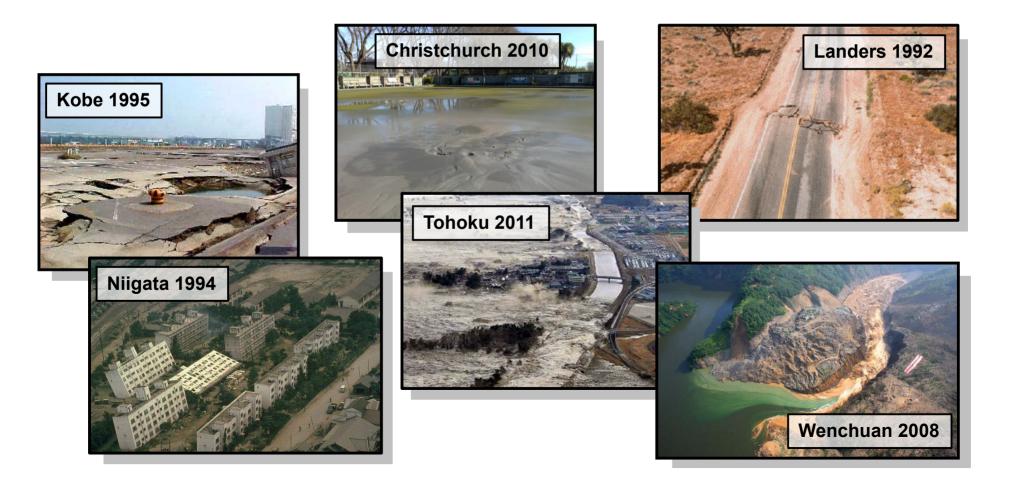
Effect on Ground Motion: Local Seismic Response

- For a particular site, the **amplitude** and **duration** of the ground motion during an earthquake can significantly be modified by the effect of the *local site conditions*
- On very soft sediments on top of a rigid bedrock, the ground motion can be amplified by more than a factor of 10, with increase in duration of several tens of seconds...
- Additionally, the energy can be non-evenly redistributed over different <u>frequency bands</u> of the spectrum, with a chance of matching the dominant resonant frequencies of buildings



Effect on the environment: Induced Effects

- The local environment is also vulnerable to certain shake levels, through development of induced or secondary effects, such as
 - ⇒ Ground failures: static displacement (offsets), subsidence, liquefaction, landslides...
 - ⇒ Indirect or triggered effects: flooding, tsunamis, snow avalanches..
- All these phenomena concur to the increase in seismic hazard at local scale

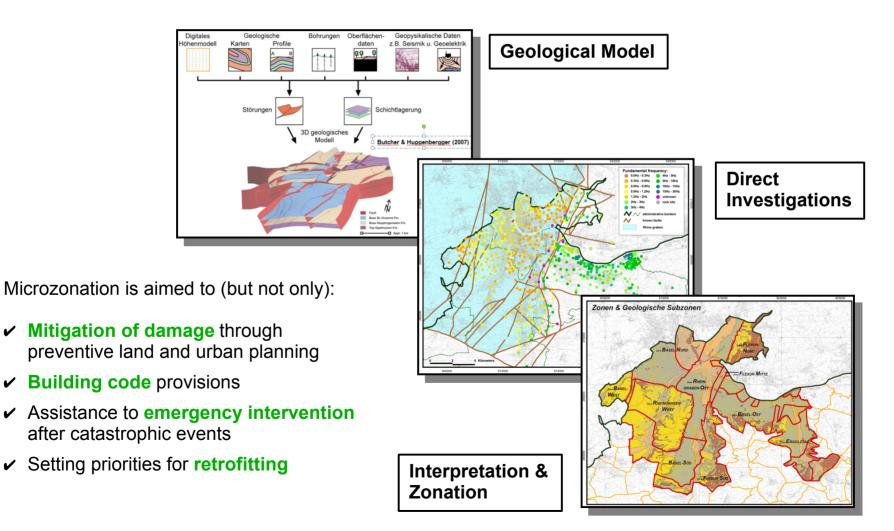


Seismic Microzonation and Site-Response Analysis

Microzonation is the seismic hazard assessment at local scale, accounting for both:

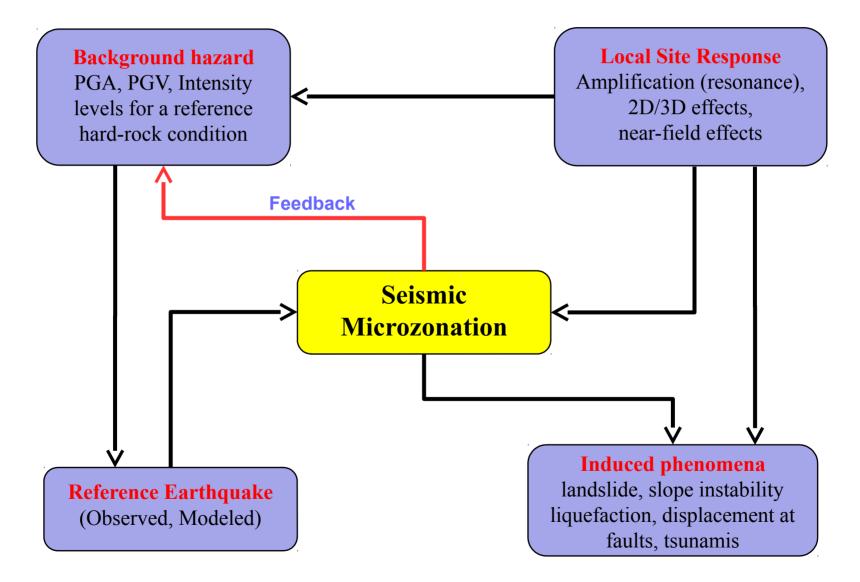
- the modification of the ground motion (amplitude, duration)
- earthquake induced phenomena

~



Microzonation Workflow

Microzonation strongly depends on the **background regional seismic hazard**, and produces feedback for its computation (iterative refinement)



Local Site Response

Local Effects influencing the Ground Motion

- Understanding the way local geological structures interact with the ground motion is the first step in site-response analysis
- Different phenomena can contribute to the complexity of the seismic response

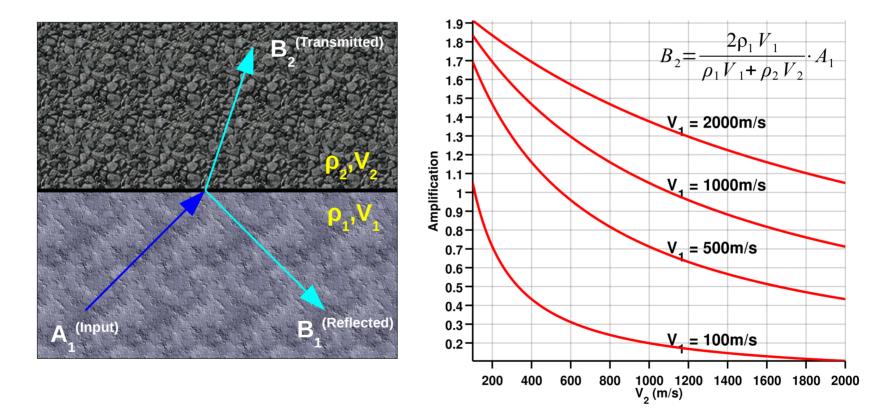
Amplification phenomena (seismic impedance contrast, resonance effect)
Geometrical effects (2d/3d basin geometries, topography)

Soil non-elastic behavior (anelasticity, scattering, non-linear response)

- Boundaries between these phenomena are overlapping; often one site-effect is controlled by the occurrence of others (e.g. 3d anelastic resonance....)
- Each phenomenon is controlled by a set of **specific ground parameters**, which can be quantified through the use of focused analysis (discussed later)

Seismic Velocity Contrast

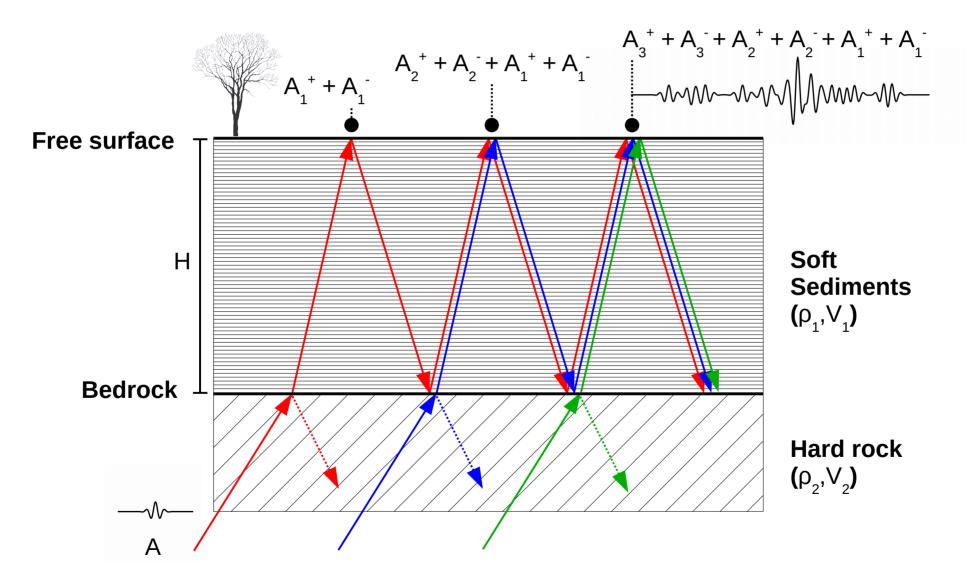
Theory of linear elasticity shows that a wave propagating across an interface between two media of different *seismic impedance* (*the product of the seismic velocity and the density*) modifies its amplitude and speed to satisfy the conservation of energy principle

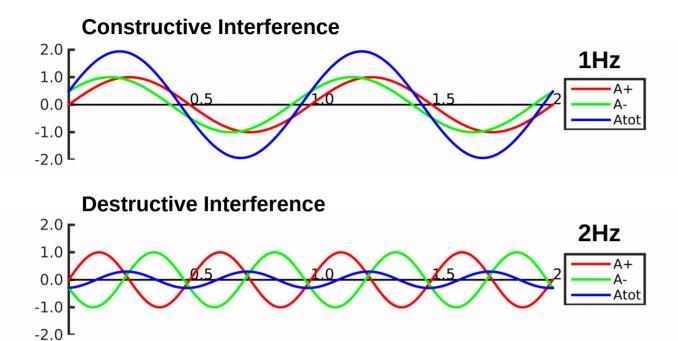


In the case of a sedimentary valley with soft sediments (low-velocity) on top of rigid bedrock (high-velocity), <u>amplification of the ground motion</u> has to be expected

The resonance amplification

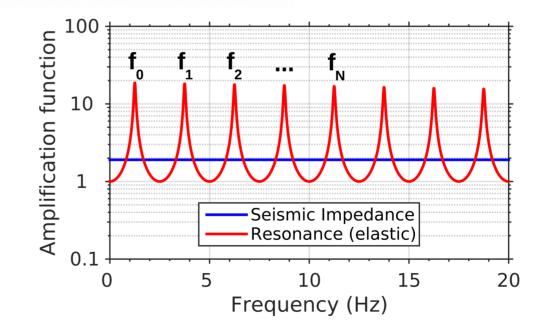
In soft sediment basins it is common a phenomenon of "*trapping*" of the wave-field, due to the multiple reflection and refraction of waves within the layers, which lead to a complex interaction called **seismic resonance**





The phenomenon is **frequency dependent**, that means ground motion can either be **amplified** or **deamplified** at different frequencies....

The larger amplification is experienced at the **resonance frequencies** (**fo**, **f1**, ... **fn**), controlled by the <u>geometrical</u> and <u>mechanical properties</u> of the soil

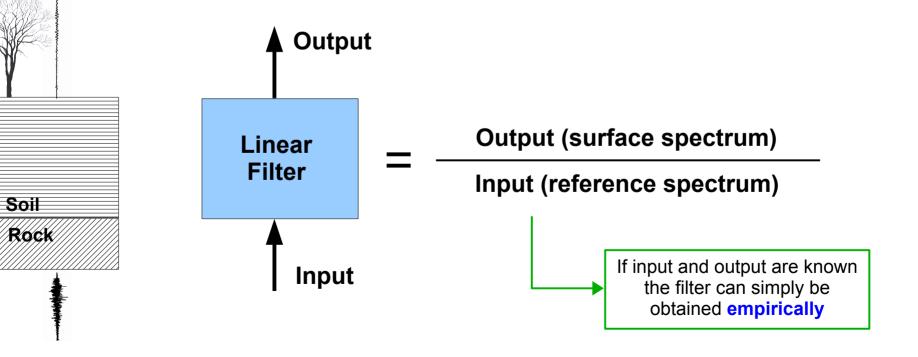


Linear Filter Equivalence

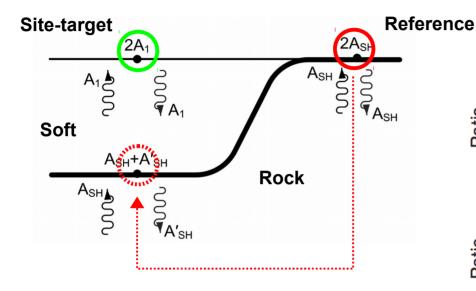
- For small strain levels the soil behaves as a linear filter
- Such Filter or transfer function can be obtained deconvolving the output signal (at the free surface) to the input signal (below the bedrock interface)
- Absolute value of the transfer function is the amplification function
- Two useful properties:

In frequency domain, deconvolution is just a spectral ratio

If input is a white spectrum (impulse), the output is equal to the filter itself!



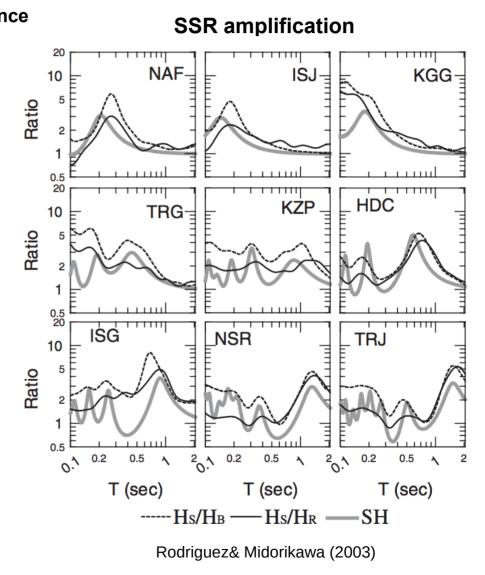
Empirical Site-to-Reference Spectral Ratios



- Also called Standard Spectral Ratios (SSR)
- The signal at the target site is deconvolved by the signal at a nearby rock station (the reference), which is assumed:

• free from site-effects (questionable...)

Similar to the motion at the bedrock (also questionable...)



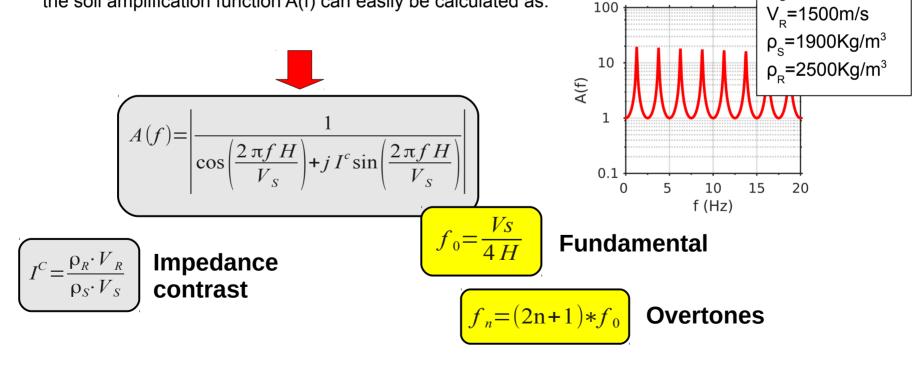
Analytical SH-wave Transfer Function

If input is unknown (very often), the solution can be obtained **analytically** or **numerically** In such cases, a sufficient knowledge of the soil properties is required

For example, by assuming:

- Plane waves with vertical incidence
- One-dimensional soil profile consisting in one layer over homogeneous half-space
- Perfectly elastic soil behavior

the soil amplification function A(f) can easily be calculated as:



H=20m

V_=100m/s

Well, site response analysis seems to be relatively easy to perform....

True; however this is mostly because of the simplification introduced by using **very simplified model assumptions** (e.g. basin is single layer, one-dimensional, perfectly elastic materials....)

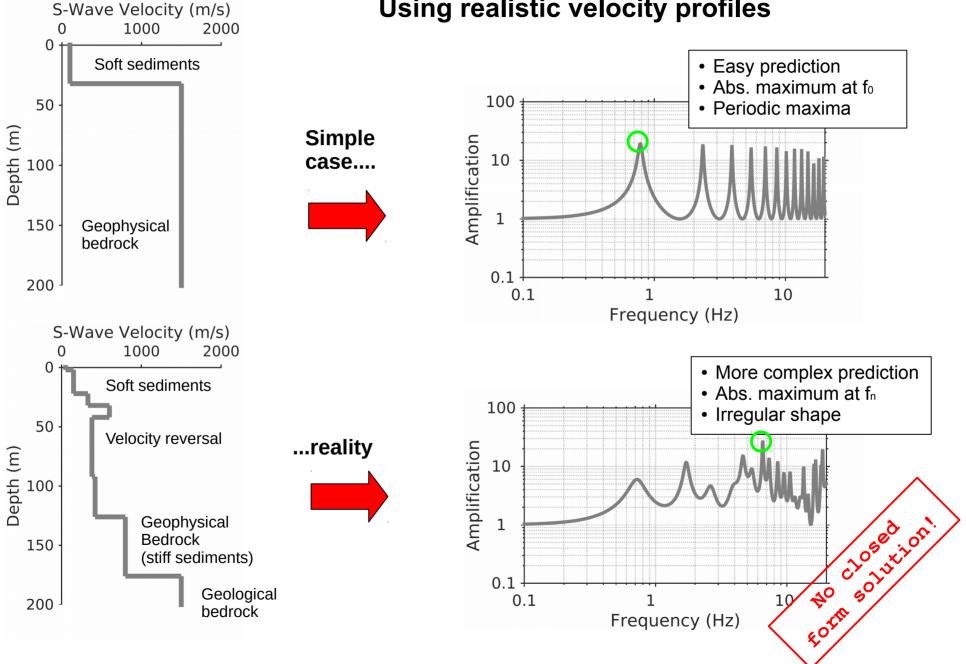
AND

oversimplification often leads to increase in uncertainty of the solution, the so called **epistemic uncertainty**

Obviously, things are getting more and more complicated when dealing with real geological structures and realistic velocity profiles

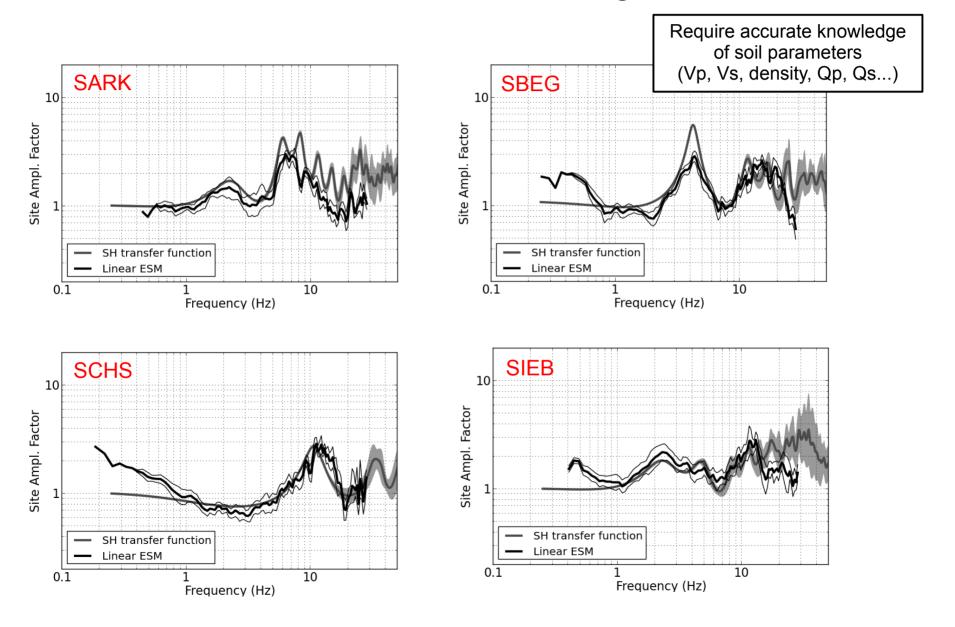
. . .

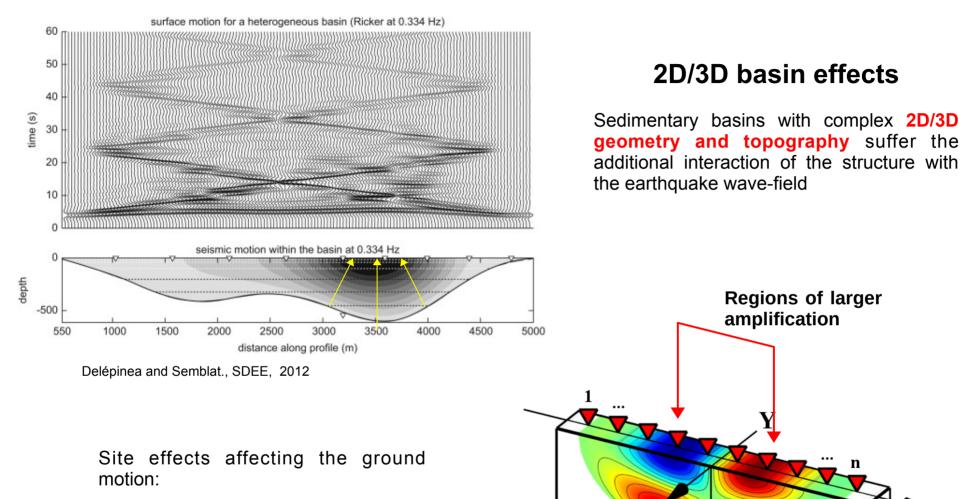
Let's see few examples....



Using realistic velocity profiles

...nonetheless, good results can still be obtained with 1D modeling





Х

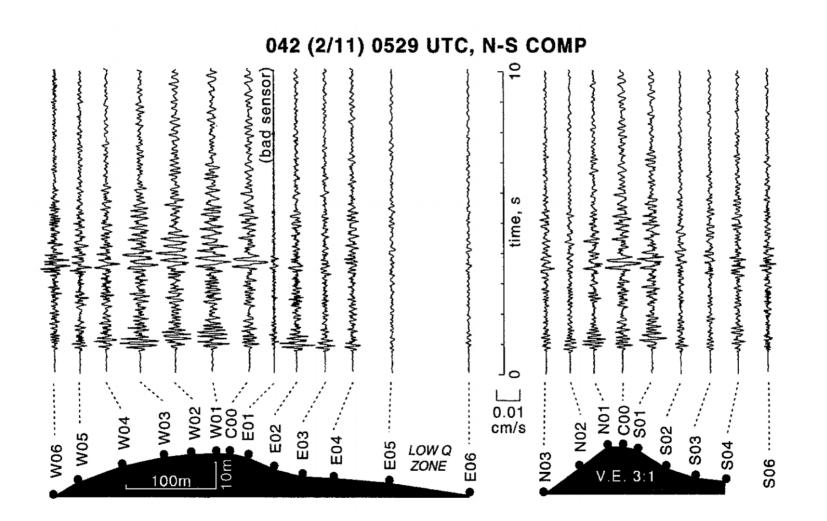
Bedrock

Ζ

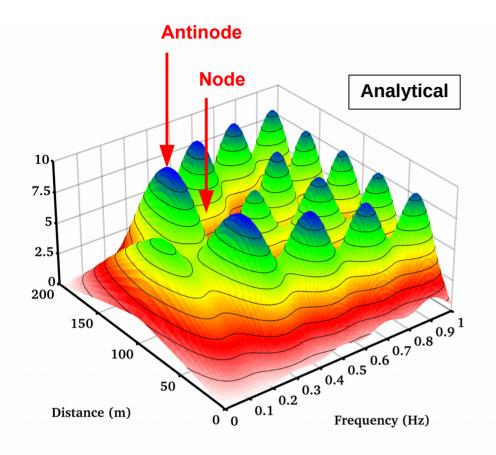
- Wave focusing and defocusing
- <u>Wave diffraction and scattering</u>
- <u>2D/3D resonance amplification</u>

2D/3D topographic effects

These are considered nowadays a **minor contribution** to the total amplification, but can still be relevant in combination with particular soil conditions (e.g. **weathering, fracturing**).



Spudich et al., BSSA, 1996

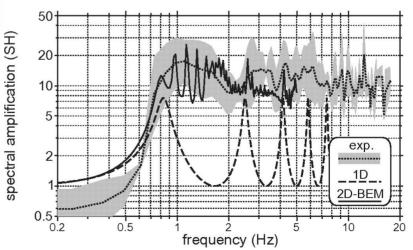


2D/3D resonance amplification

In the 2D/3D case, the resonance effect on the ground motion can be severe, but **well localized in delimited areas of the basin**

Empirical



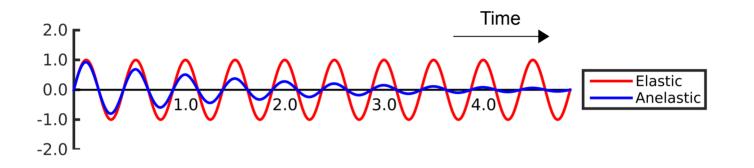


Quantifying resonance amplification is not easy:

- ⇒ Analytical solutions (nearly) impossible
- ⇒ <u>Numerical analysis very complex</u>
- ⇒ Empirical estimation problematic....

Anelastic attenuation

Anelastic (or intrinsic) attenuation is a property of the visco-elastic materials, where the energy of the propagating wave is dissipated by the effect of friction of the constituting elements (minerals, sedimentary grains, etc.)

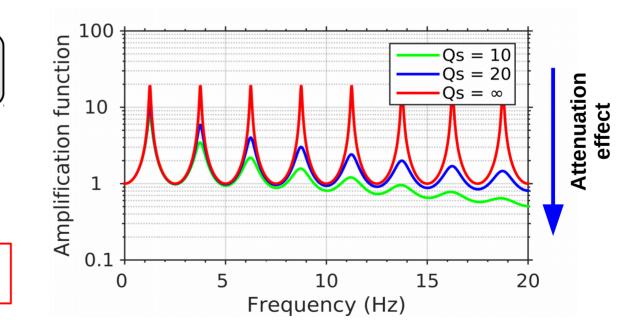


$$\int A_{Att}(f) = |A(f)| \cdot e^{-\pi f \frac{H}{V_s Q_s}}$$

Qs calibration

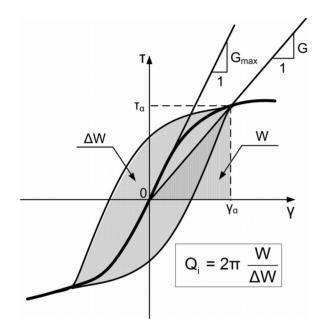
not easy!

Anelastic attenuation has basically the effect of a **low pass filter**



Non-linear soil behavior

As the excitation level increases during strong earthquakes, some loose soils start behaving following a **non-linear stress-strain relation**



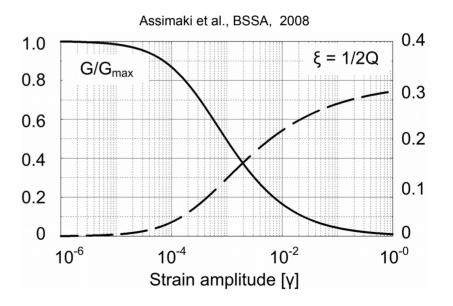
As a result, the signal amplitude is simultaneously:

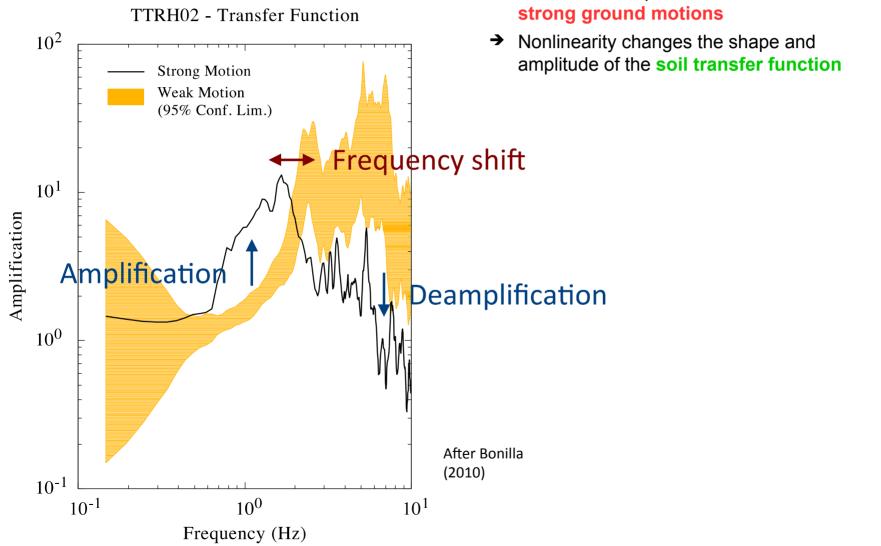
- O decreased by attenuation
- Increased by increase in velocity

Result depends on the intensity of the shaking, the signal duration... Non-linear soil response is characterized by simultaneous:

• increase in damping (attenuation)

Oreclassic reduction of the shear modulus (and thus the seismic velocity)



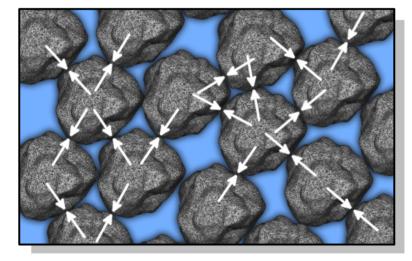


The problem of soil non-linearity

➔ Soil can develop a nonlinear behaviour under

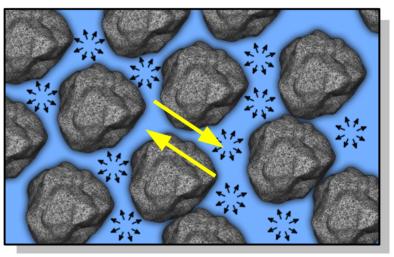
Soil Liquefaction

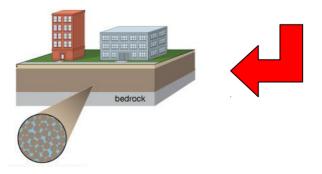
- Liquefaction occurs in porous, water-saturated soils when the **shear strength** of the sediment is reduced by a temporary increase in **water pressure** induced by the stress-field of the earthquake
- Important for lifelines (gas, water, electricity), sewage system, earth dams, rail, roads, landfill areas (harbors), ...

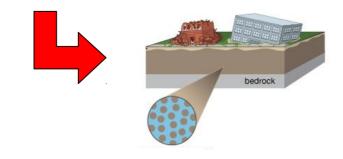


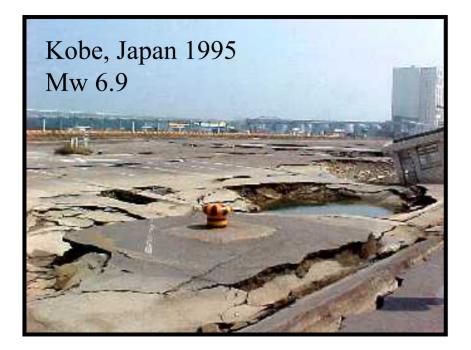
Static conditions

! Under dynamic loading !











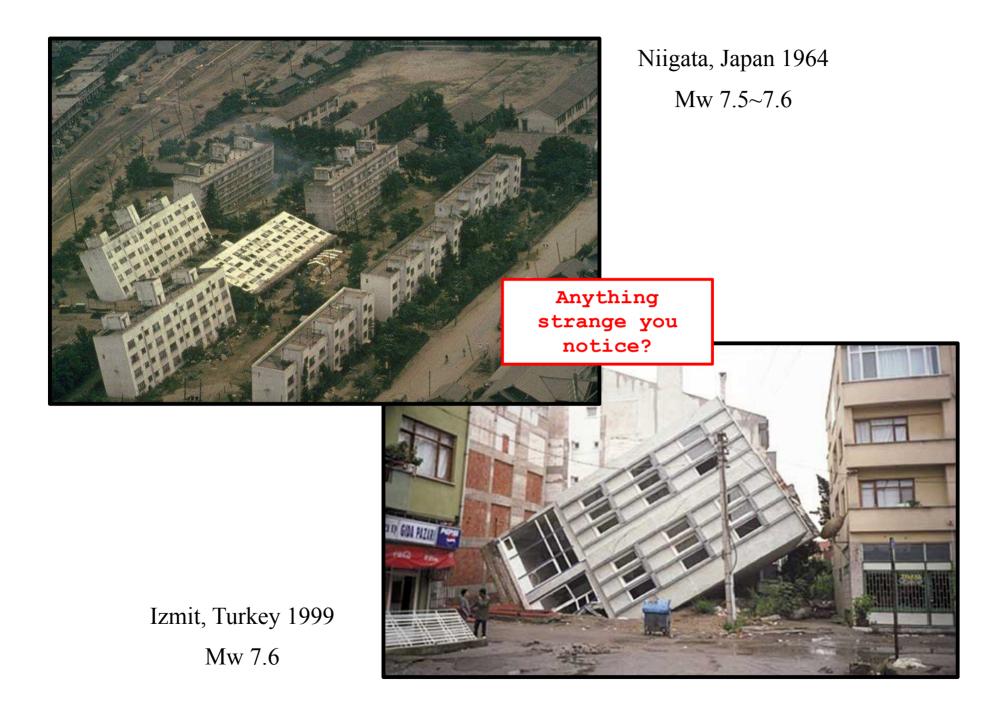
Soil Liquefaction

Some example of the effects at local scale....



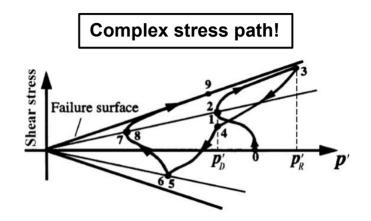
Emilia, Italy 2012 Mw 6.1

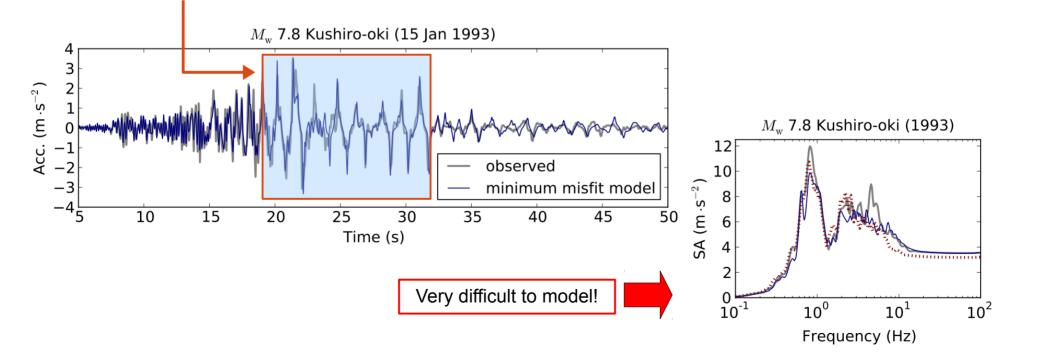
Christchurch, New Zealand 2010 Mw 7.1



Cyclic Mobility

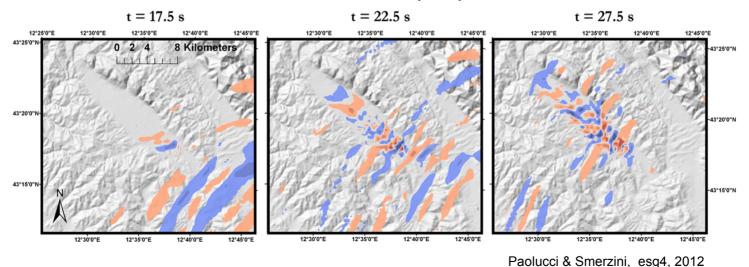
- It occurs in <u>dense</u>, <u>cohesionless saturated soils</u> when <u>cyclic</u> <u>loading-unloading</u> is applied
- The material experiences several cycles of **softening** (decrease in shear resistance) and **stiffening**
- · Soil failure may occur after several cycles of loading
- Earthquake signal can heavily be altered by development of large high-frequency pulses in acceleration



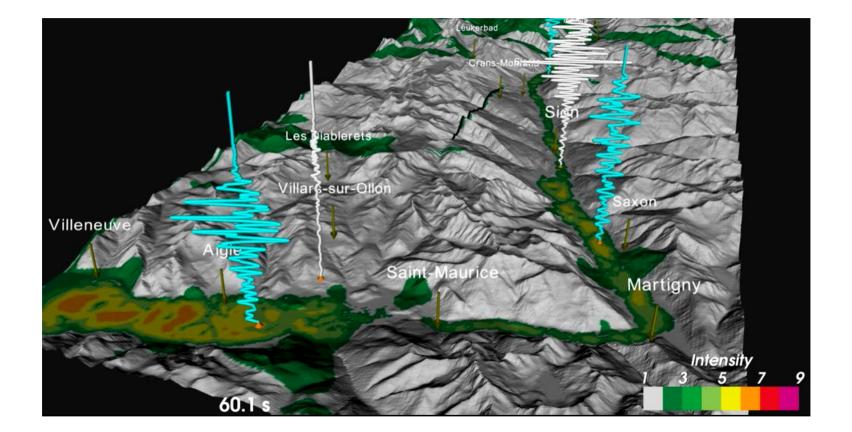


Indirect modeling methods

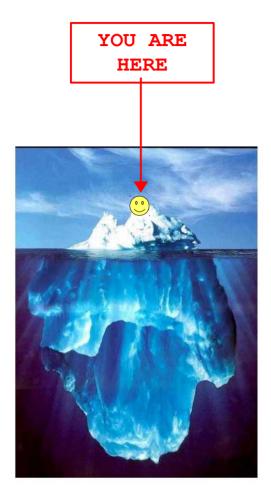
- When the complexity of the model and of the phenomena to simulate is too large, analytical methods are not feasible anymore
- Complex wave-field modeling is nowadays done though the use of highly sophisticated numerical techniques
- Quality of the solution depends on many factors:
 - Assumptions and approximation of simulated the physical laws
 - Assumptions and approximation / available knowledge of the **model parameters**
 - Computation costs (large simulations might require days on computer clusters)



Gubbio basin (M=6)



Time to watch a movie...



Some concluding remarks

- What you just learned is only the tip of the iceberg...
- Many other phenomena are relevant at local scale and a variety of analysis techniques available
- Seismic response analysis can be very complex (and very useful) if properly done

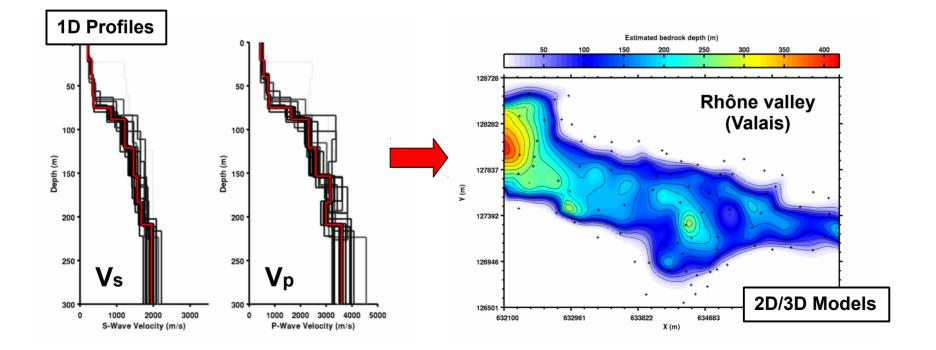
Nonetheless....

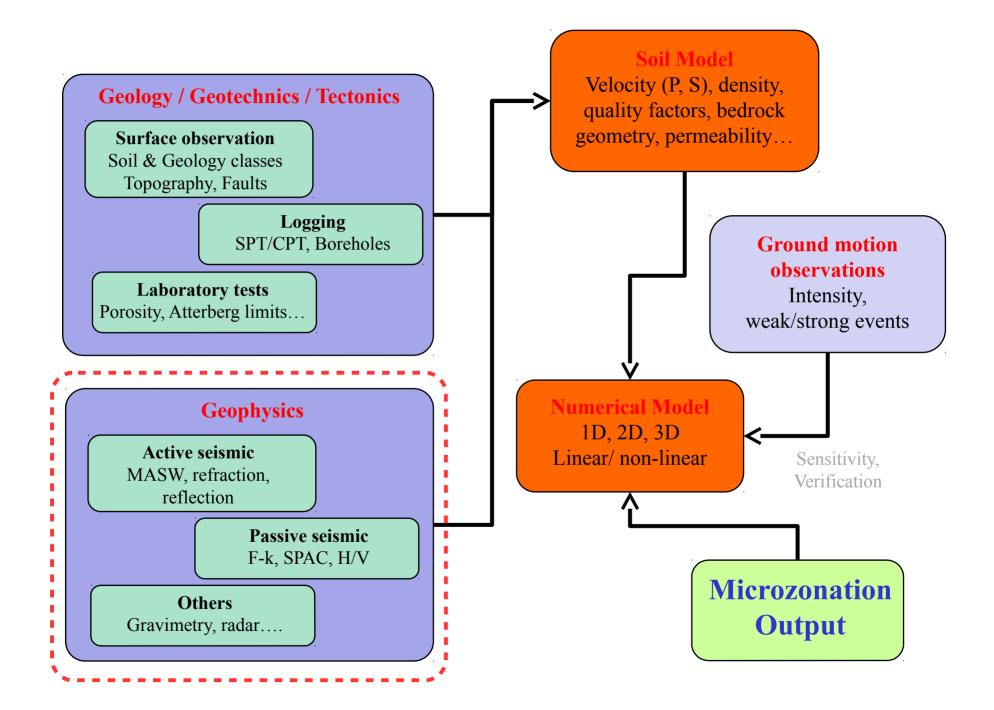
- Local response is often neglected or analyzed too simplistically
- Why? Basics are not well-understood by practitioners (and in some cases also by scholars)
- As result, many present studies are affected by considerable uncertainty, which then propagates into other studies.....

Site Characterization Techniques

Ground Parameter Overview

- The most relevant parameters to characterize the soil behavior are the seismic velocity of body waves (Vp and Vs), the density (ρ) and the attenuation factors (Qp and Qs)
- The way these parameters are <u>geometrically distributed</u> controls the modification of ground-motion during an earthquake
- Shear wave velocity, in particular, is the most important property in engineering applications
- A sufficient knowledge of these parameters is essential for any interpretation of recorded earthquake ground motion





Indirect (geophysical) investigations

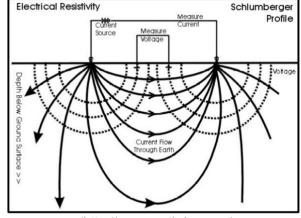
Indirect investigation techniques (or **geophysical methods**) use the properties of the **physical fields** (<u>electric, magnetic, gravity, seismic</u>) to infer information on the soil structure remotely (water table, bedrock depth)

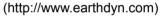
Static-field methods:

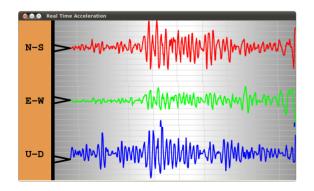
- Electrical methods (resistivity, self-potential)
- Magnetic method (magnetic susceptibility)
- Gravimetric method

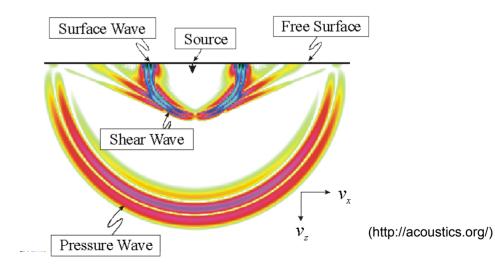
Wave-field methods:

- Electromagnetic methods (radar)
- Seismic methods (active and passive)









Active seismic methods

- \rightarrow Make use of an **artificial sources** to generate a seismic signal
- \rightarrow Two major categories: the travel-time and surface wave methods
- \rightarrow The receivers can be located at the surface or in boreholes

Advantages:

- Good signal quality in noisy environments
- Good resolution on the velocity profile

Disadvantages:

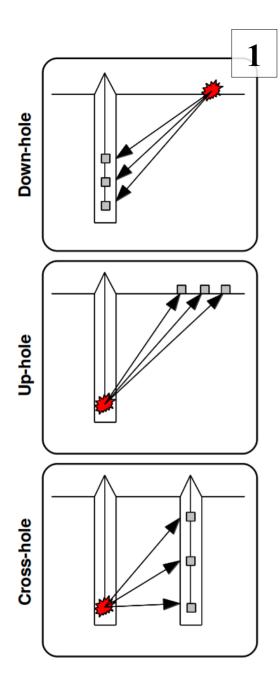
- Scarce penetration depth with conventional sources (e.g. hammer, minigun)
- Relatively high costs of implementation
- They can hardly be used in urban environment

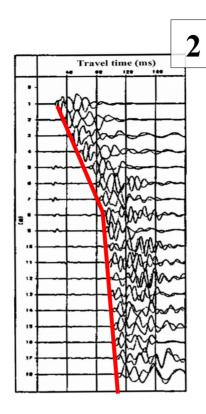


(http://www.earth.ox.ac.uk)



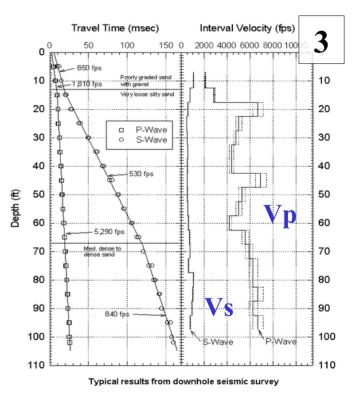




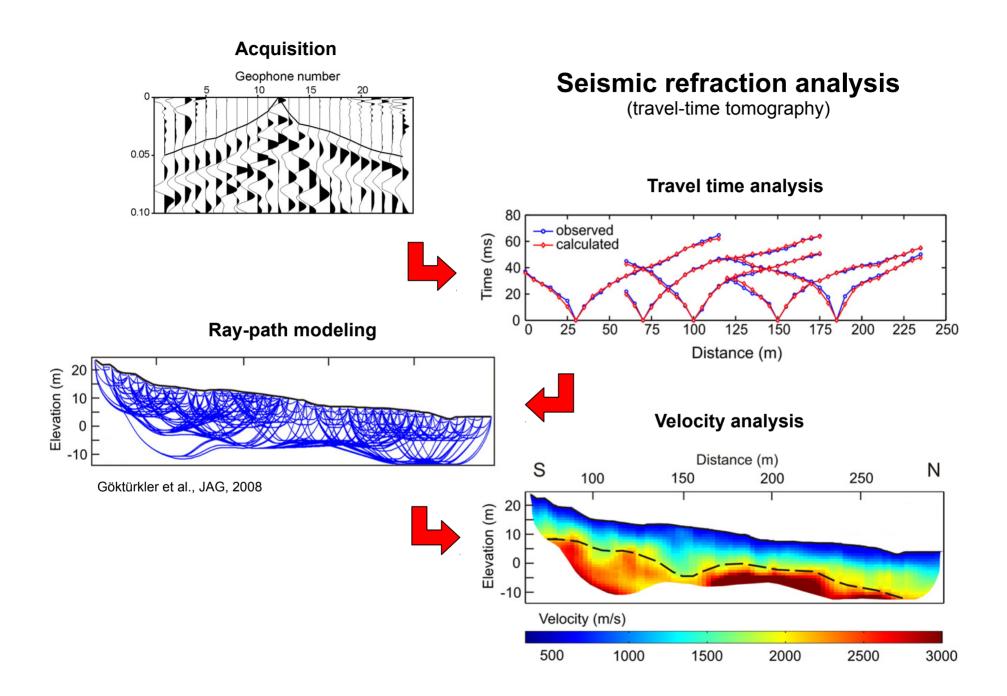


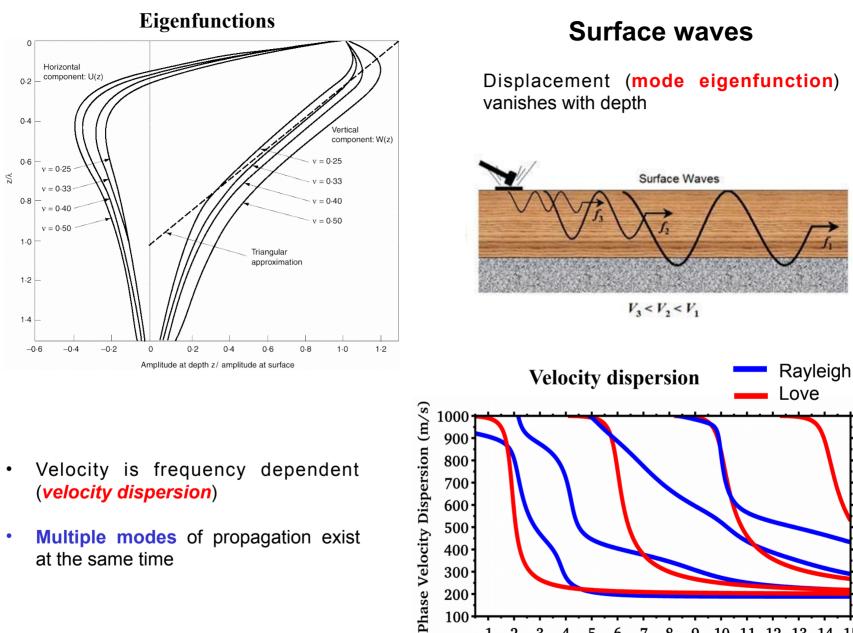
Takahashi et al. IJRMMS. 2006

Borehole seismic (Travel-time analysis)



(http://www.earthdyn.com)





 Frequency (Hz)

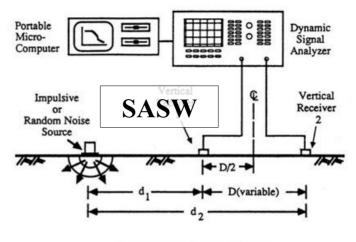
9 10 11 12 13 14 15

Multiple modes of propagation exist at the same time

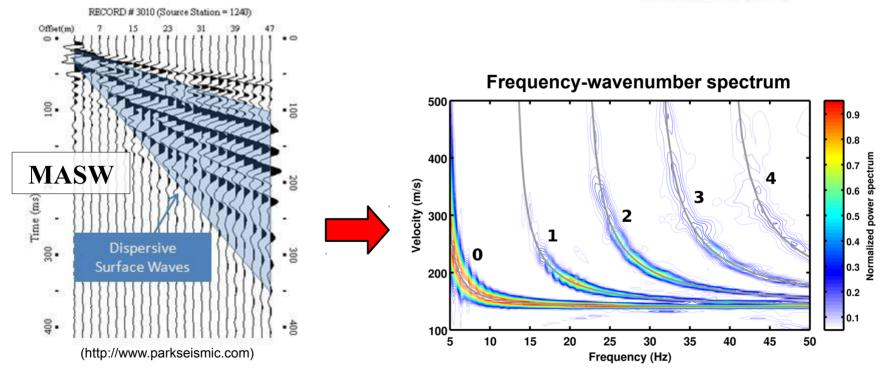
Active surface wave analysis

SASW \rightarrow Spectral Analysis of Surface Waves (relative phase delay between <u>pairs of receivers</u>)

MASW → Multichannel Analysis of Surface Waves (frequency-wavenumber analysis)

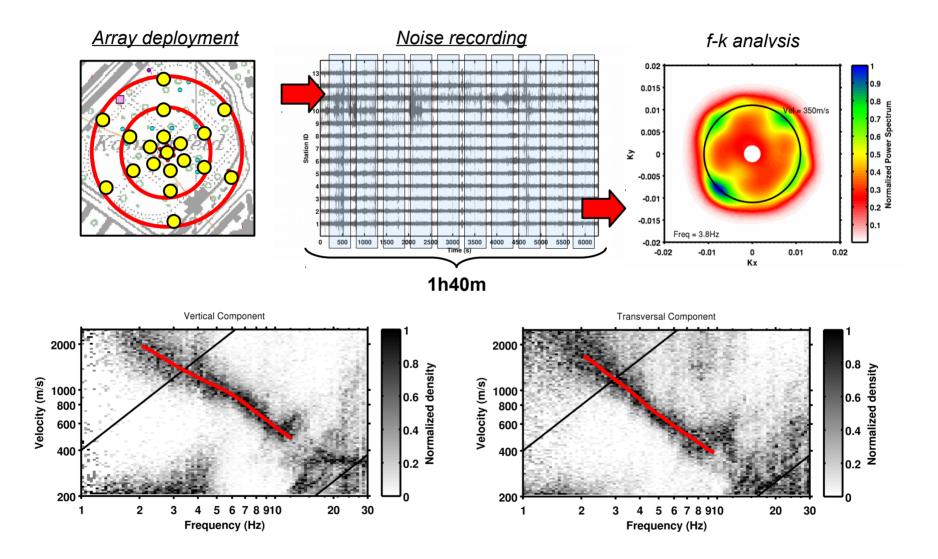


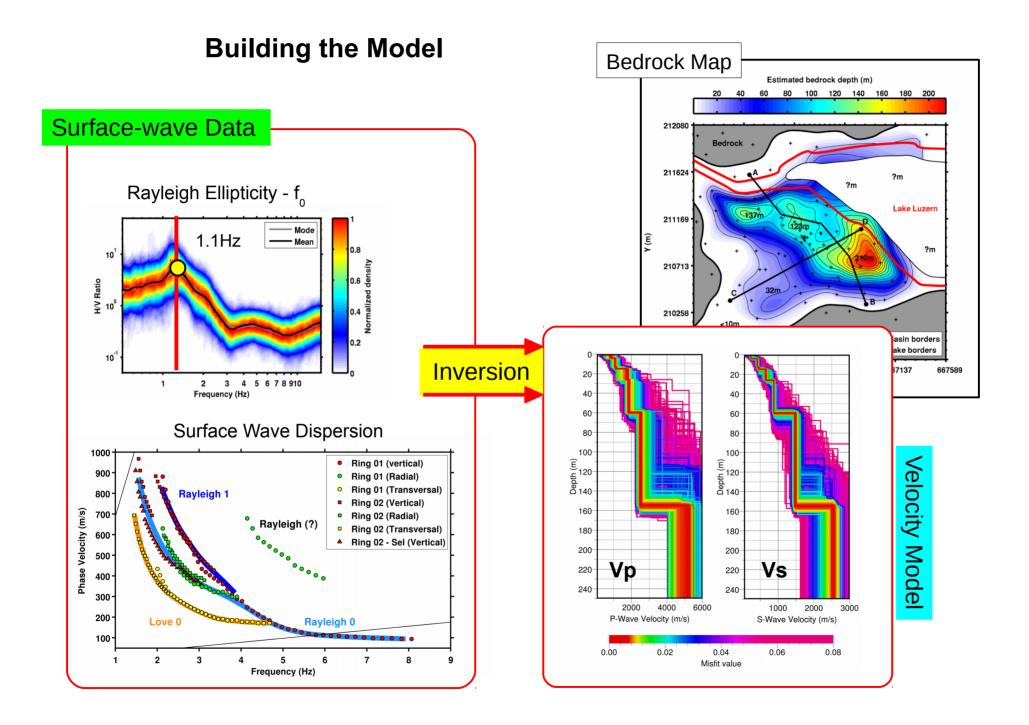
From Rix et al. (1991)



Ambient vibration seismology

(Array analysis)



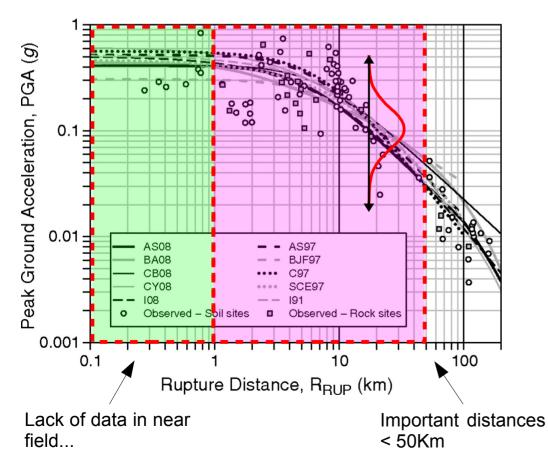


GMPE site term and Soil Proxies

GMPE - Ground Motion Prediction Equations

Given a specific source scenario (e.g. magnitude, fault mechanism...), GMPEs predict the shaking level at a given location (e.g. at distance R)





Often source, path and site terms are described by a simple **regressive model** (e.g. high order polynomials) using a merely empirical approach and **single predictors** (**PGA**, **PGV**, **Intensity**)

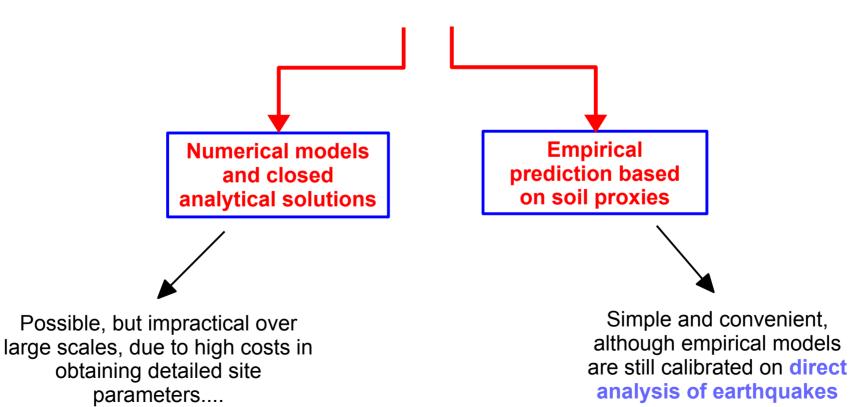
PRO: generally quite easy to use, often calibrated on world-wide datasets

CONS: based just on observation, (little) physical justification, large epistemic uncertainty

The Generic Site Amplification Term

GMPEs represent a simple and convenient way to predict ground motion level over wide areas and sites of different characteristic

In order to predict site response for a specific site and in case of lack of direct recordings, a site amplification model is then necessary



This can be done in two ways, using:

Soil classification and proxies

Present **GMPEs** and **building codes** use simplified approaches to map the variability of local site response over wide areas by means of **statistical models** based on **ground types** (or classes) and **empirical observations**

Ground types are identified by appropriate **near-surface proxies**, such as:

- \rightarrow the average velocity over the first 30 meters (Vs₃₀)
- \rightarrow the fundamental frequency of resonance
- \rightarrow results from SPT/CPT tests
- \rightarrow geological/geotechnical classification...

Ground Class	Description	<i>v_s</i> [m/s]	N _{SPT}	s _u [kN/m²]	S	Т _в [s]	Т _с [s]	T _D [s]
A	firm rock (e.g. granite, gneiss, quartzite, siliceous limestone, limestone) or soft rock (e.g. sandstone, conglomerate, Jura marl, Opalinus claystone) beneath a maximum soil cover of 5 m	> 800	_	-	1.00	0.15	0.4	2.0
В	deposits of extensive cemented gravel and sand and/or overconsolidated soils with a thickness exceeding 30 m	400800	> 50	> 250	1.20	0.15	0.5	2.0
С	deposits of normally consolidated and uncemented gravel and sand and/or moraine with a thickness exceeding 30 m	300500	1550	0250	1.15	0.20	0.6	2.0
D	deposits of unconsolidated fine sand, silt and clay with a thickness exceeding 30 m	150300	< 15	< 70	1.35	0.20	0.8	2.0
E	alluvial surface layer of Ground Classes C or D, with a thickness of 5 to 30 m lying above a stiffer layer of the Ground Classes A or B	-	-	-	1.40	0.15	0.5	2.0
F	deposits of structurally-sensitive and organic deposits (e.g. peat, lake marl, slide material) with a thickness exceeding 10 m	-	-	-	-	-	-	_

SIA261 - Example of soil classification using Vs₃₀

Some Considerations on the Use of Soil Proxies

→ Proxies are a convenient way to characterize soil types of "*expected*" similar seismic response using just a single parameter

→ Soil proxies can be obtained by direct measure or (very often) by indirect extrapolation from other direct observations (e.g. geology, topography)

 \Rightarrow However, despite of their simplicity, these proxies:

(1) do not fully describe the **vertical/lateral variability** of the soil structure

② can hardly describe the **frequency dependent** amplification behavior

(3) cannot account for site-specific phenomena like **soil non-linearity** and **resonance amplification**

What Vs₃₀ actually is?...

- Vs₃₀ is the travel-time average shear-wave velocity over the first 30m.
- It is computed in such a way:

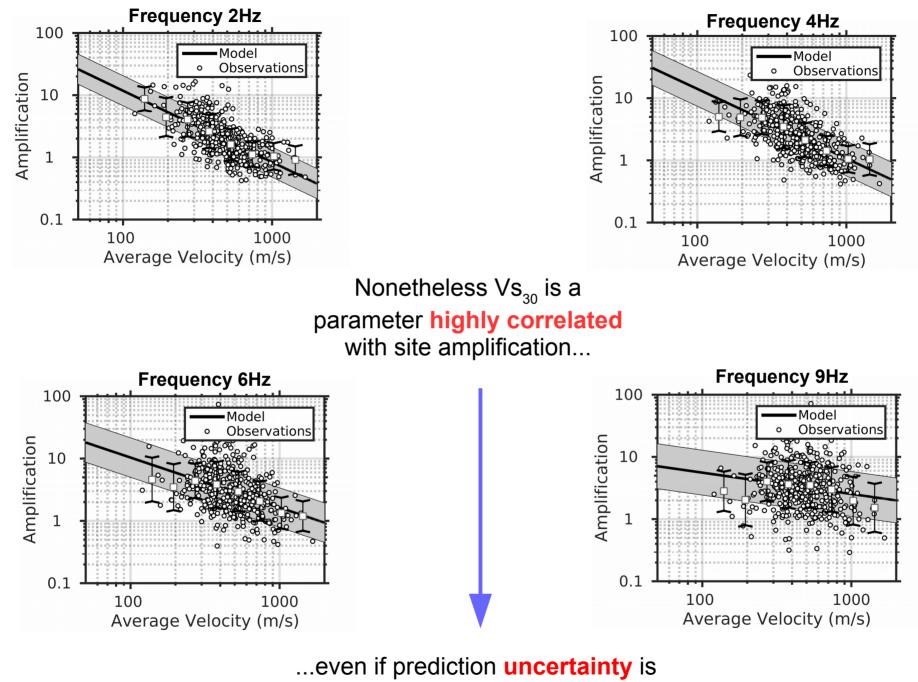
$$Vs\,30 = \frac{30}{\sum_{i=1,N} \frac{h_i}{v_i}}$$

...but why using 30m, and not 10, 25 or 50m?

 Simply because ~30m (100ft!) was the standard penetration depth of most of the direct logging techniques of the past (at least in US).

Consequently...

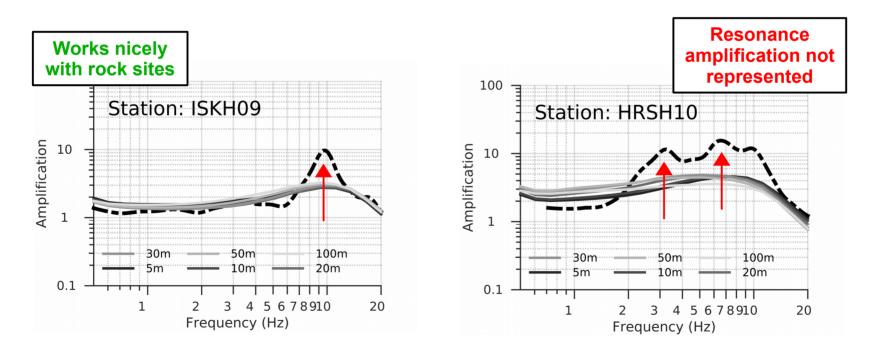
• The large availability of log data within this depth range imposed this parameters as **de facto standard** (but without a clear **physical meaning**)

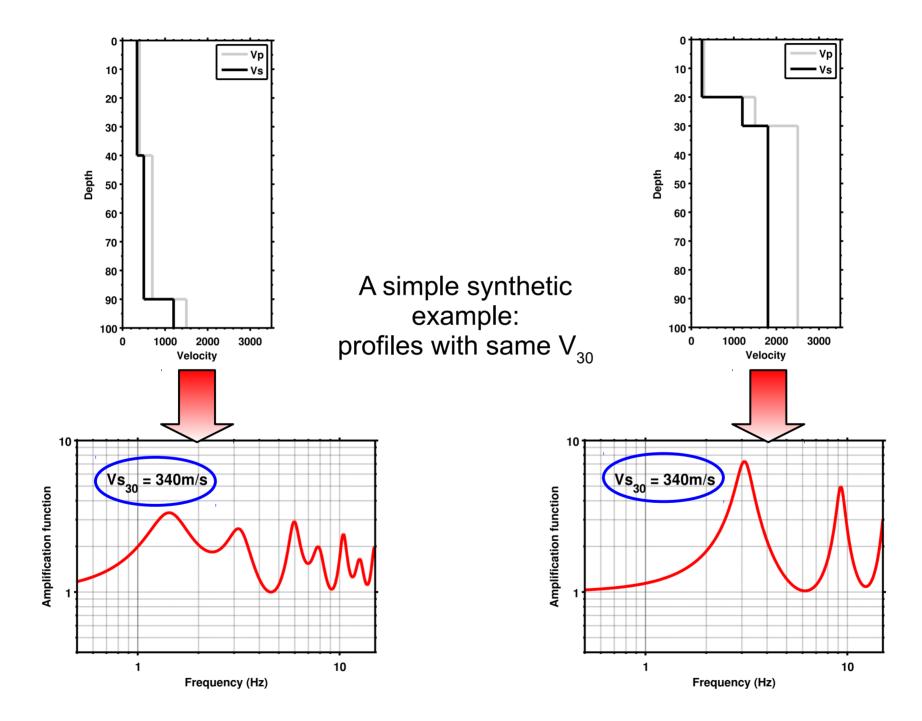


quite large

Source of Uncertainty of the Predictor

- Vs₃₀ is basically a proxy for the contrast of seismic impedance between the **basement** (source condition) and the **uppermost** (average) soil, which is controls the average amplification level of the site
- However, Vs₃₀ cannot explain those complex phenomena developing *"within"* the profile...



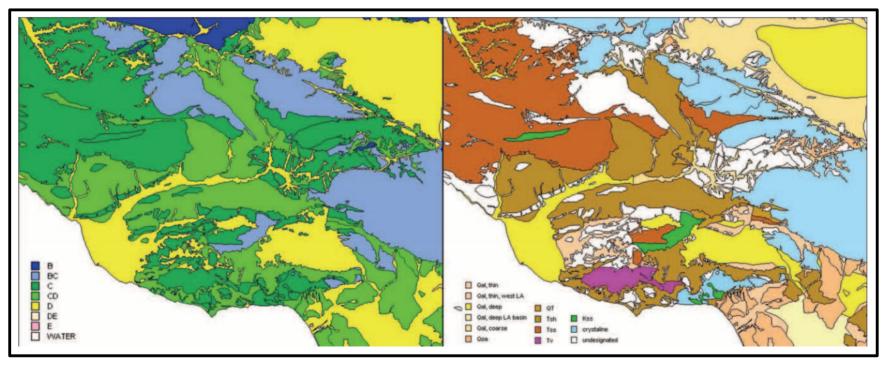


Additional Source of Uncertainty

- Vs₃₀ can also be biased by the way it is obtained, often not from direct measurement but **extrapolated** from other surface proxies (geology, geotechnical classification, CPT tests....)
- The conversion introduces an additional contribution to the uncertainty, which sum to the final error in the prediction

Geology

Vs30



Willis and Clahan (2006)

Vs₃₀ from Topography

- Nowadays, a popular way to map • Vs_{30} over large areas is the use of topographic slope from geodetic observations (Wald and Allen, 2007, 2009)
- The relation is based on the • concept of "depositional energy" of the sediments

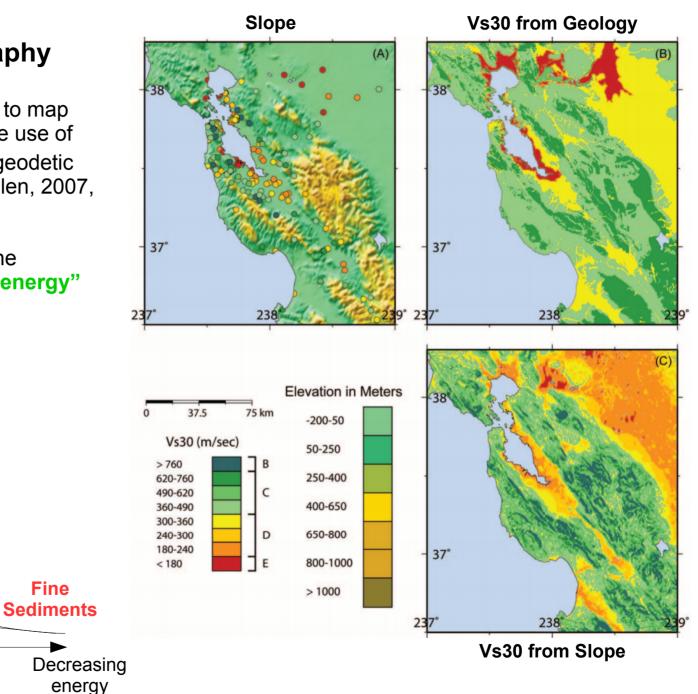
Coarse

Sediments

Fine

Outcropping

rock



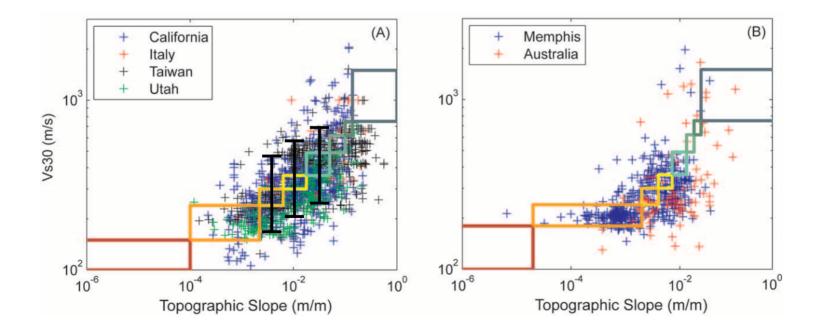
Vs₃₀ from Topography

The slope-Vs₃₀ relationship is based on the National Earthquake Hazard Reduction Program (NERHP) Vs₃₀ boundaries (arbitrary?)

	V_S^{30} Range (m/sec)	Slope Range (m/m)			
Class		Active Tectonic	Stable Continent		
Е	<180	<1.0E-4	<2.0E-5		
	180-240	1.0E - 4 - 2.2E - 3	2.0E - 5 - 2.0E - 3		
D	240-300	2.2E - 3 - 6.3E - 3	2.0E - 3 - 4.0E - 3		
	300-360	6.3E-3-0.018	4.0E - 3 - 7.2E - 3		
	360-490	0.018-0.050	7.2E-3-0.013		
С	490-620	0.050-0.10	0.013-0.018		
	620–760	0.10-0.138	0.018-0.025		
В	>760	>0.138	>0.025		

Calibration databases from different regions:

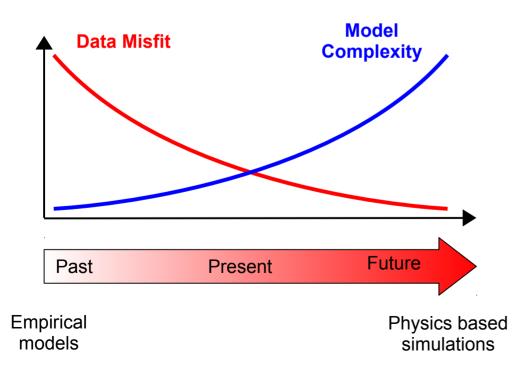
- California
- > Utah
- ➤ Central U.S.
- Taiwan
- > Italy
- Australia



...and the question is finally:

Is Vs₃₀ really so adequate as proxy for site amplification?

Vs₃₀ is probably not sufficient for future engineering products, as it introduces too large uncertainties



Epistemic uncertainty can be reduced at the expenses of increasing model complexity, by introducing physics-based concepts Modeling Site-Response Into GMPEs

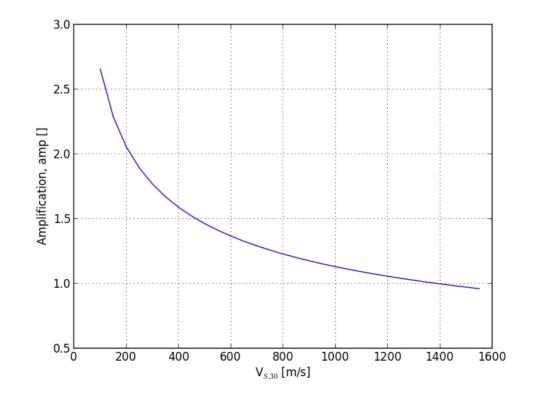
Boore et al. (1997)

Assuming a linear amplification of motion Boore et al. (1997) proposed the following formula to model site amplification using a site-specific $V_{S,30}$ value:

$$\ln(Amp) = a \ln\left(\frac{V_{S,30}}{V_{Ref}}\right)$$

For PGA the coefficients are:

- a = 0.371
- V_{ref} = 1396 [m/s]



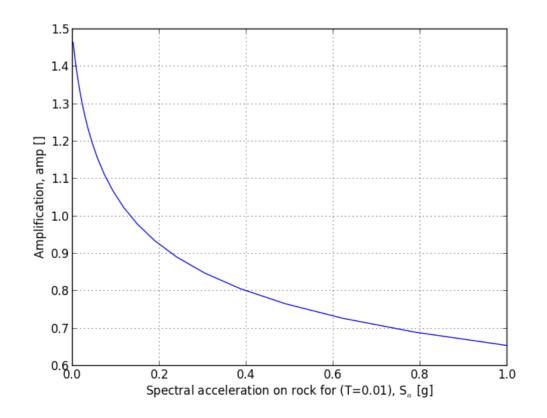
Ambrahamson and Silva (1997)

Ambrahamson and Silva (1997) using a generalized soil category developed a model for site response accounting for the non-linear behaviour of materials

$$\ln(Amp) = a + b \ln \left(P \hat{G} A_{rock} + c \right)$$

For PGA the coefficients are:

- a = 0.417
- b = -0.230
- c = 0.03



Choi and Stewart (2005)

Choi and Stewart (2005) proposed and empirical model for assessing the nonlinear amplification factor for spectral acceleration as a function of $V_{S,30}$. The results can be used as *Vs-30-based* site factors with attenuation relationships

$$\ln(F_{ij}) = c \ln\left(\frac{V_{s-30_{ij}}}{V_{ref}}\right) + b \ln\left(\frac{PHA_{r_{ij}}}{0.1}\right) + \eta_i + \varepsilon_{ij},$$

where:

- PHA_r peak horizontal acceleration for reference [rock] site condition [g]
- V_{ref} and c are regression parameters
- h_i is a random effect term for earthquake event i (should have zero median across all events, standard deviation is denoted as t); and e_{ij} represents the intra-event model residual for motion j in event i (should have median near zero for wellrecorded events, standard deviation is denoted s).